

Paper Review:

Measurement of Gravitational Coupling between Millimeter-Sized Masses

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13.11.2020 Ando Lab Seminar



Measurement of Gravitational Coupling between Millimeter-Sized Masses

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We demonstrate gravitational coupling between two gold spheres of radius $r \approx 1$ mm and mass $m \approx 90$ mg. By periodically modulating the source mass position at a frequency $f_{mod} = 12.7$ mHz we generate a time-dependent gravitational acceleration at the location of the test mass, which is measured off resonance in a miniature torsional balance configuration. Over an integration time of 350 hours the test mass oscillator enables measurements with a systematic accuracy of 4×10^{-11} m/s² and a statistical precision of 4×10^{-12} m/s². This is sufficient to resolve the gravitational signal at a minimal surface distance of 400 μ m between the two masses. We observe both linear and quadratic coupling, consistent in signal strength with a time-varying $1/r$ gravitational potential. Contributions of non-gravitational forces could be kept to less than 10 % of the observed signal. We expect further improvements to enable the isolation of gravity as a coupling force for objects well below the Planck mass. This opens the way for precision tests of gravity in a new regime of isolated microscopic source masses.

[arxiv:2009.09546](https://arxiv.org/abs/2009.09546)

- Measurement of gravitational force between two tiny spheres using a torsion pendulum
- Modulating a source mass off resonance
- Almost limited by thermal noise of the torsion mode
- Statistical error: 1 %, systematic error: 10 %

Contents

- Introduction
- Experiment
- Results
- Discussion & Outlook

- Supplement Material
 - ◉ Torsion pendulum
 - ◉ Calibration
 - ◉ etc...

Introduction

- Testing gravity is one important experimental endeavor:
 - ◉ Unification within standard model
 - ◉ Consistency with quantum theory
- Example:
 - ◉ Astronomically
 - ▶ Direct detection of GW
 - ▶ Direct imaging of SMBH
 - ◉ Earth-bound
 - ▶ Test of equivalent principle
 - ▶ Precision measurement of G (Newton's constant)
 - ▶ Test of inverse square law

Motivation

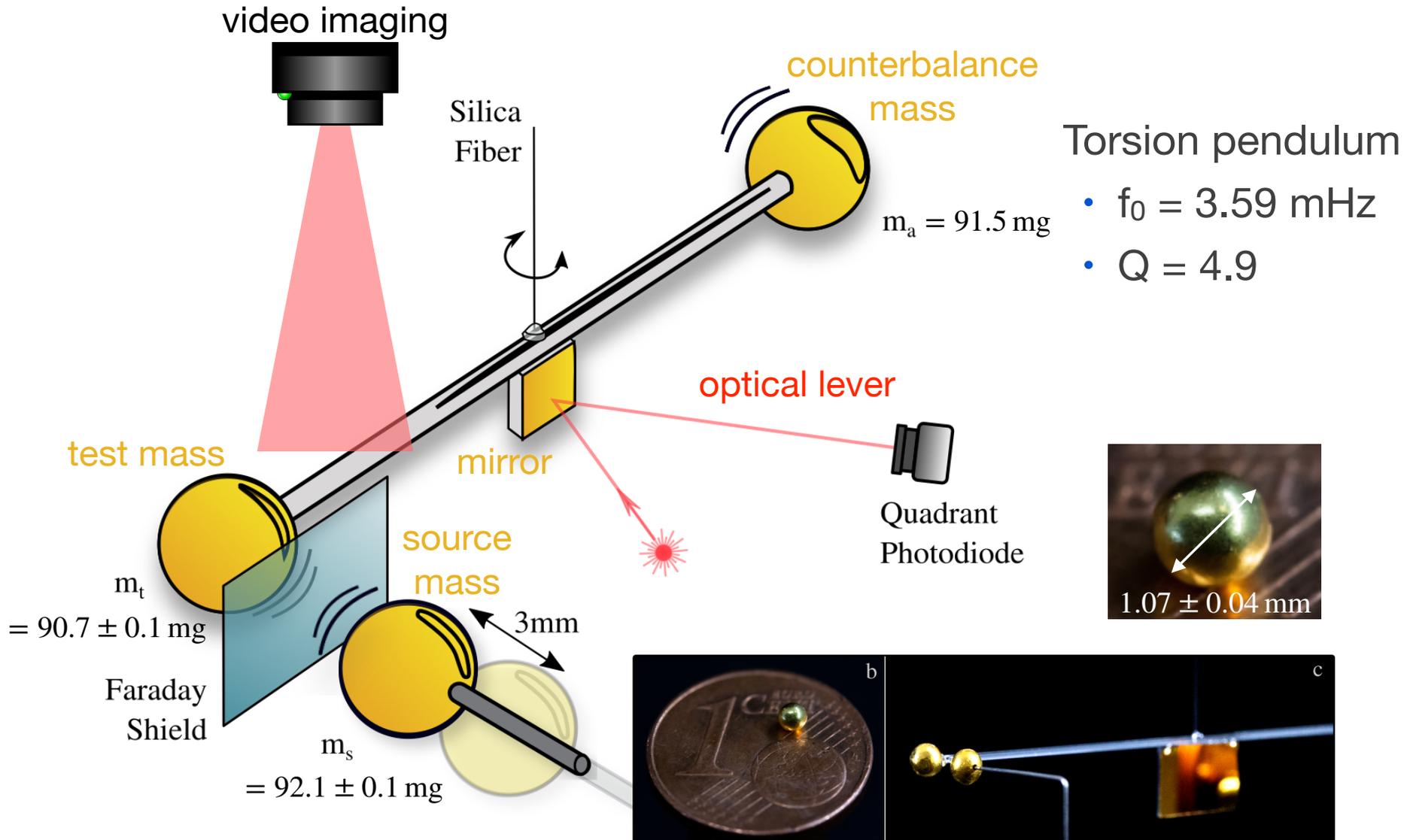
For such experiments,

- Test mass: from quantum system to macroscopic scale
- Source mass: kg-scale and beyond
 - ▶ Microscopic source mass is a frontier!
- In this paper they show gravitational coupling in sub-100mg scale

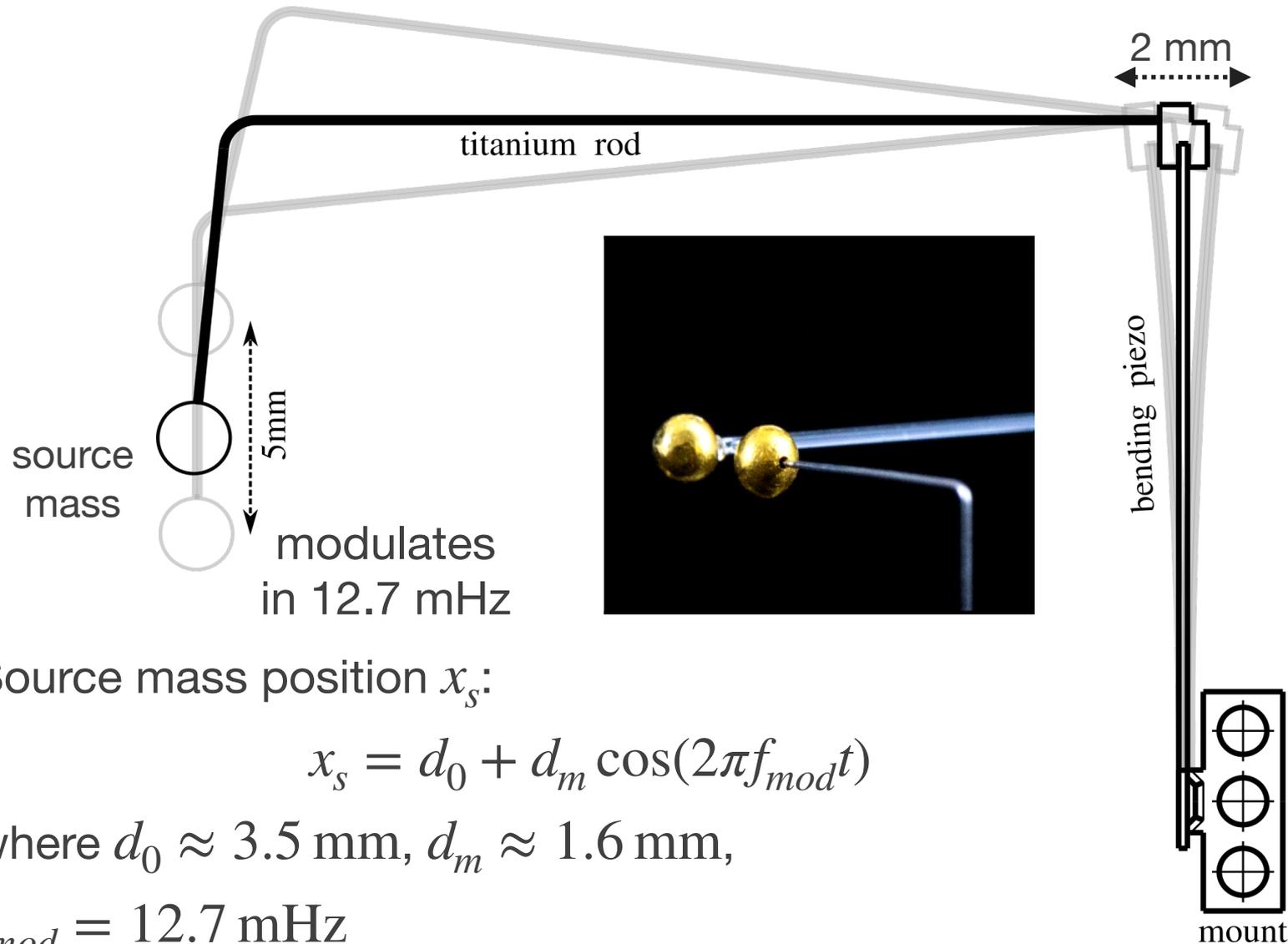
Goal:

- Show a prospects to Planck mass scale ($\sim 22 \mu\text{g}$) experiment

Experiment Setup: Torsion Pendulum



Experiment Setup: Source Mass Drive



Source mass position x_s :

$$x_s = d_0 + d_m \cos(2\pi f_{mod} t)$$

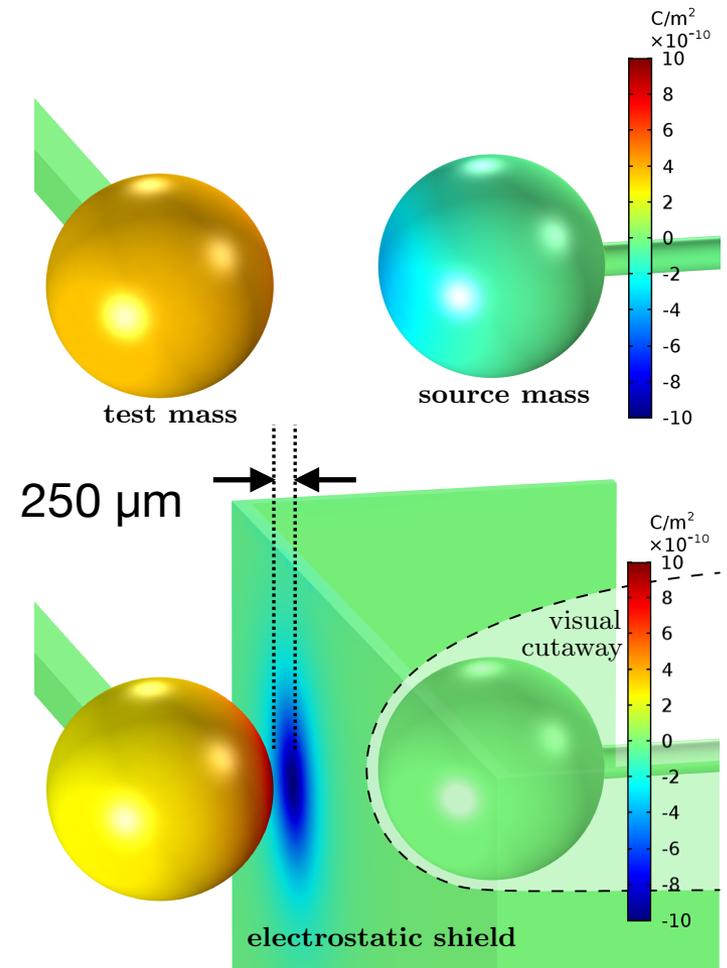
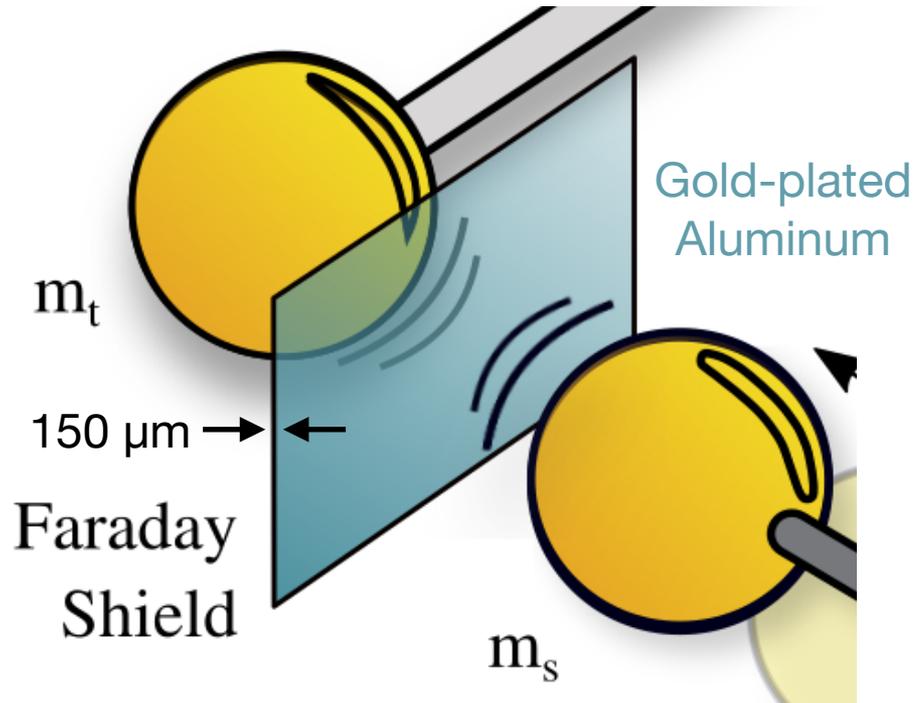
where $d_0 \approx 3.5$ mm, $d_m \approx 1.6$ mm,

$$f_{mod} = 12.7 \text{ mHz}$$

Experimental Setup: Faraday Shield

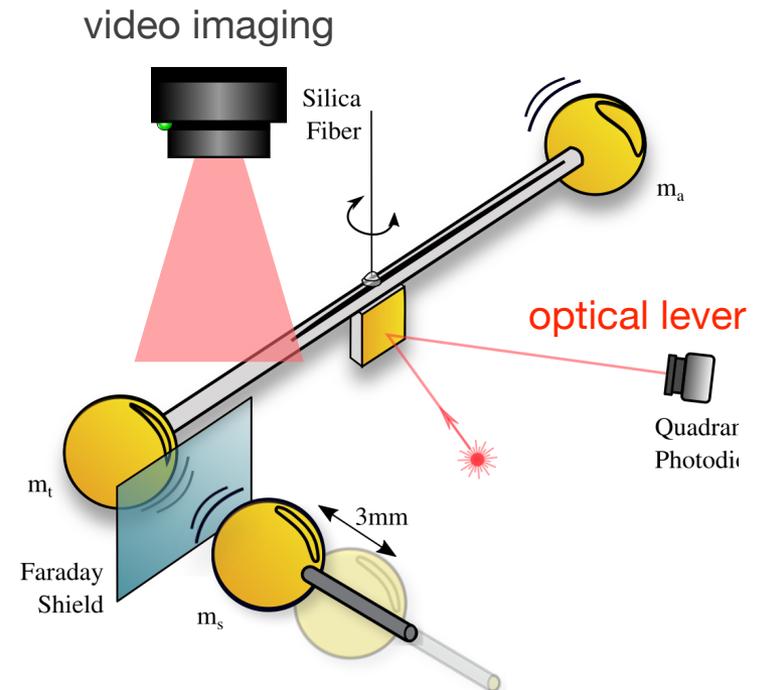
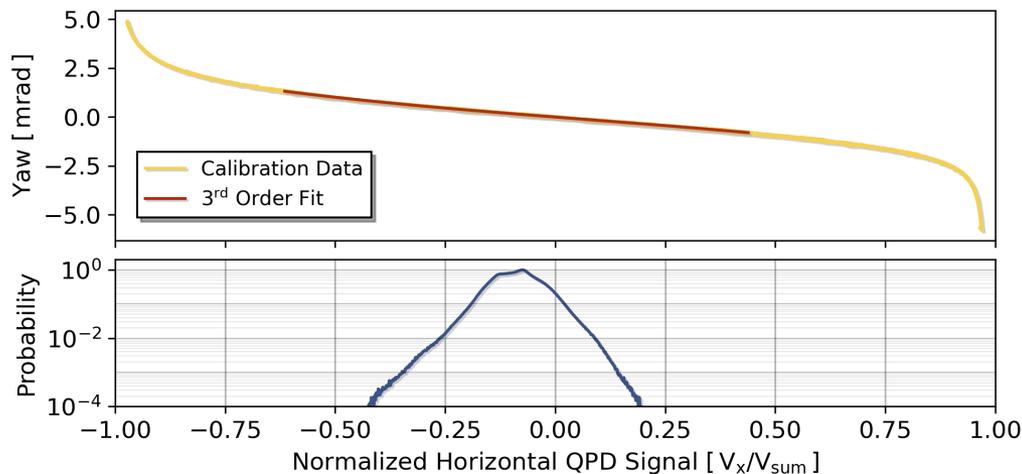
Faraday shield to reduce electrostatic coupling

- w/o: Electrostatic $\sim 3 \times$ Gravity
- w/: Electrostatic $< 0.03 \times$ Gravity



Calibration: Test Mass Position

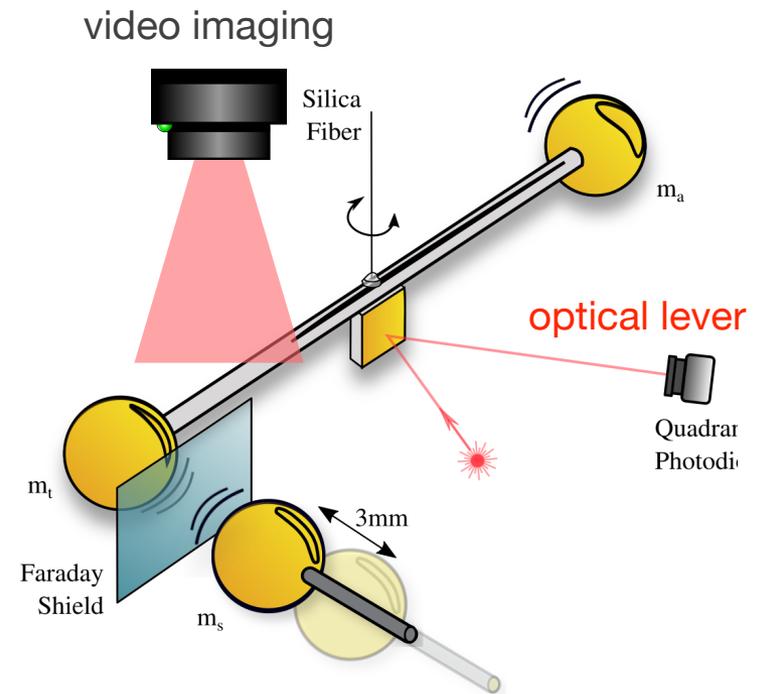
- Calibration of TM position is done by comparing these two signals:
 - Optica lever
 - Good resolution ($2e-9$ m/ $\sqrt{\text{Hz}}$)
 - Narrow linear region (~ 0.5 mrad)
 - Video tracking: tracking by pixel image
 - Wide range
 - Worse resolution ($24\mu\text{m}/\text{px}$)



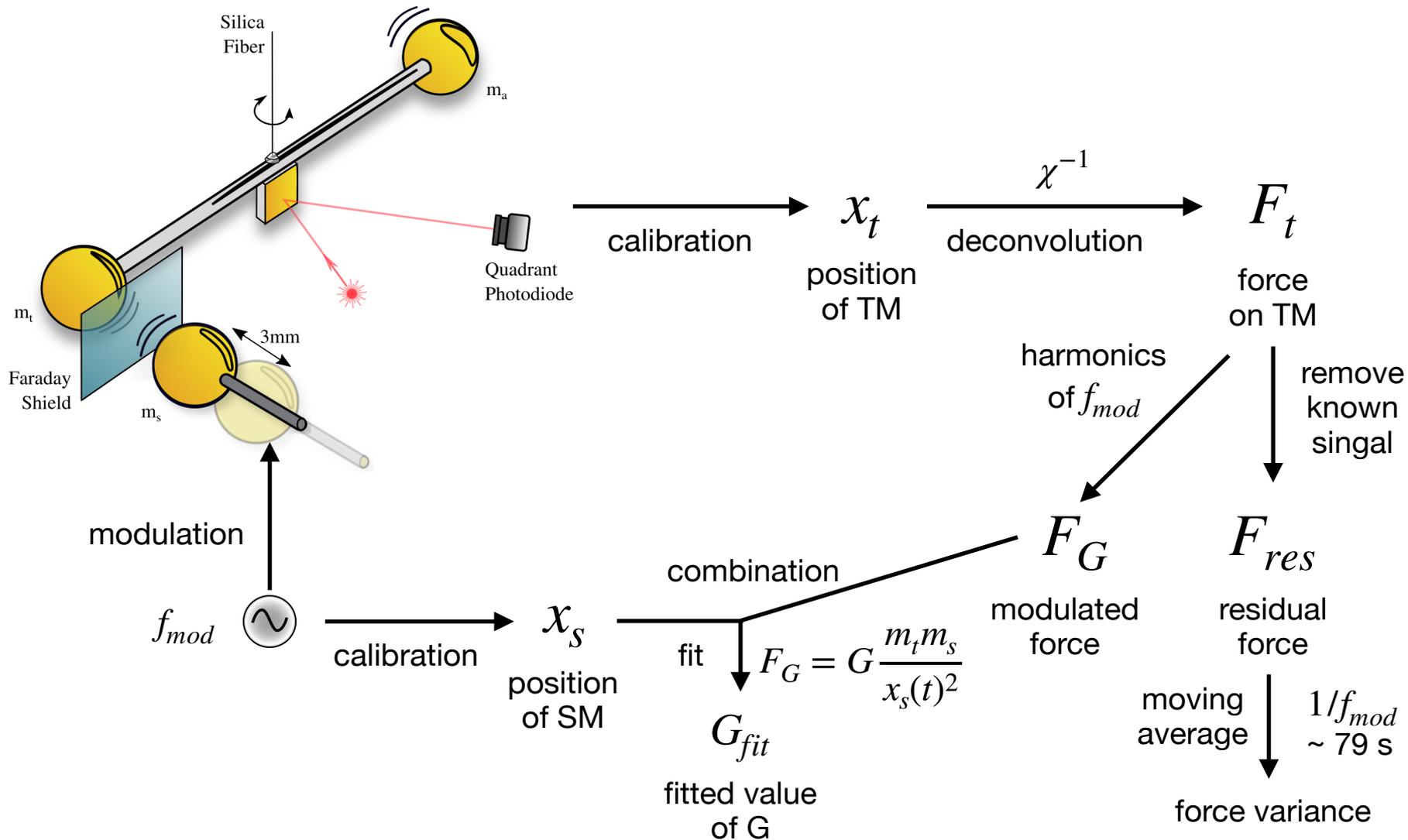
Calibration: Piezo Drive

Piezo drive motion is calibrated by video tracking

- Time lag, long term drift exist
 - ◉ Modeled as a transducer with an additional low-pass filter
 - ◉ Still unexplainable drift exists
- In observation run, separation between TM and SM is measured at the beginning and the end of the measurement
 - ◉ Not monitored continuously during measurement
 - ◉ Induced shift of mean position ($55\ \mu\text{m}$) and change of modulation depth ($13\ \mu\text{m}$)
 - ◉ They are supposed to be linear over the measurement run

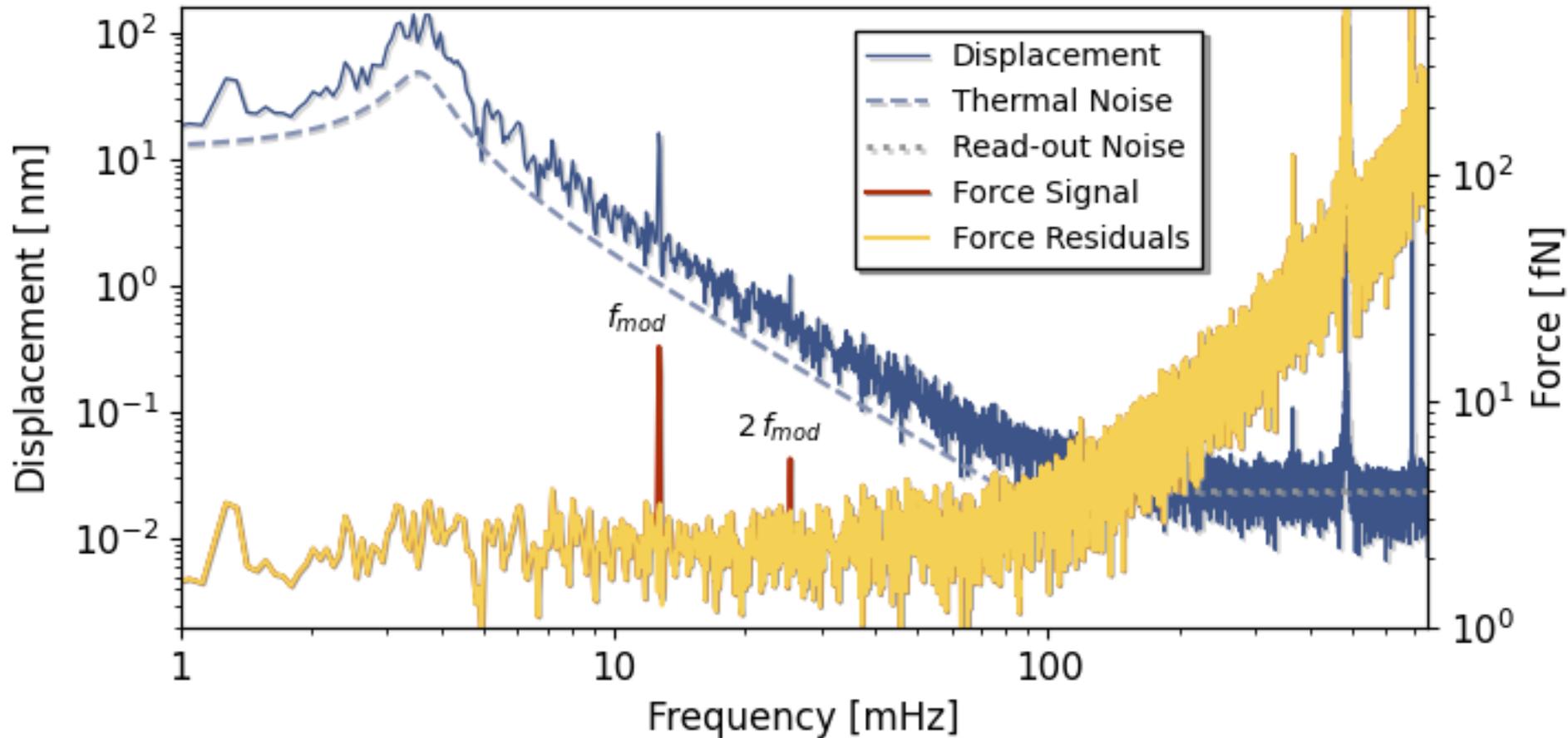


Data Processing



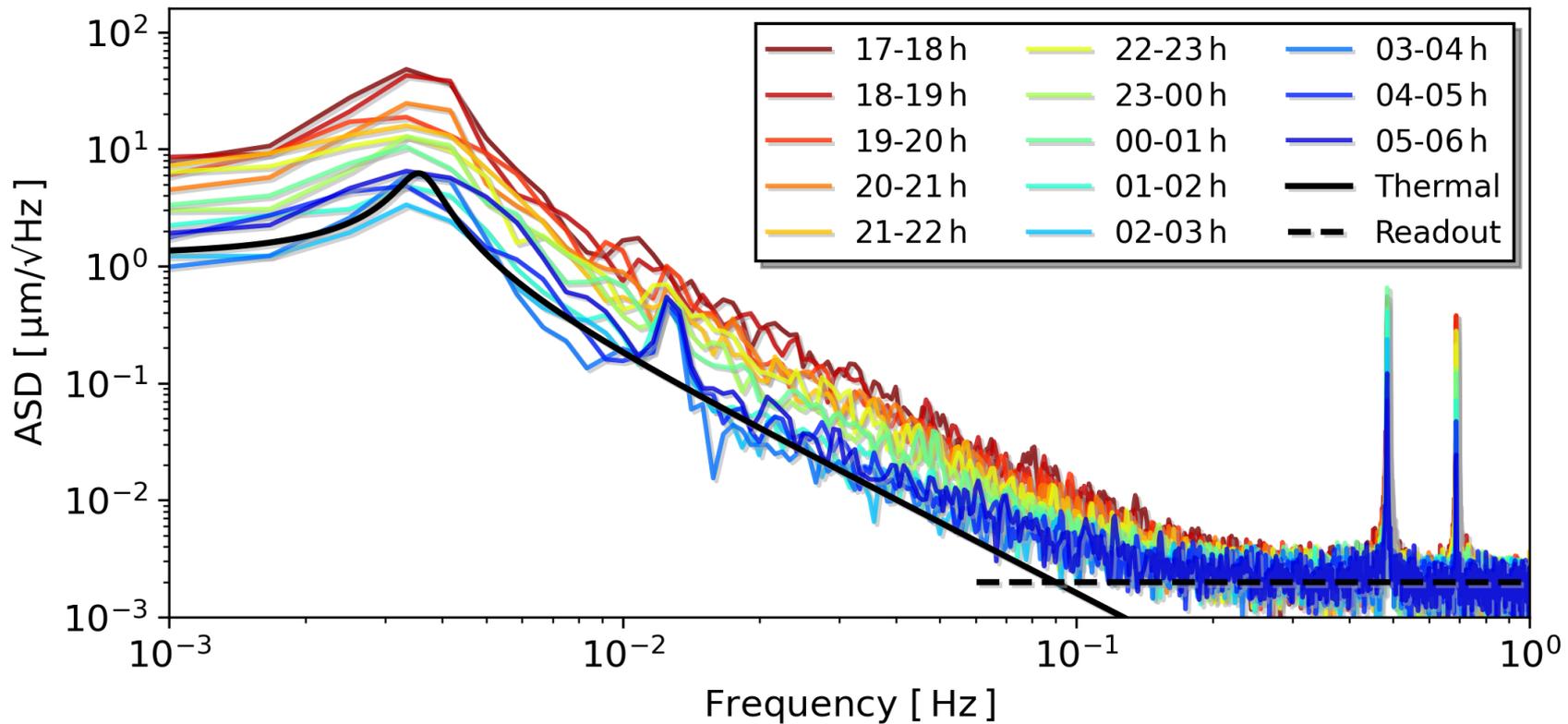
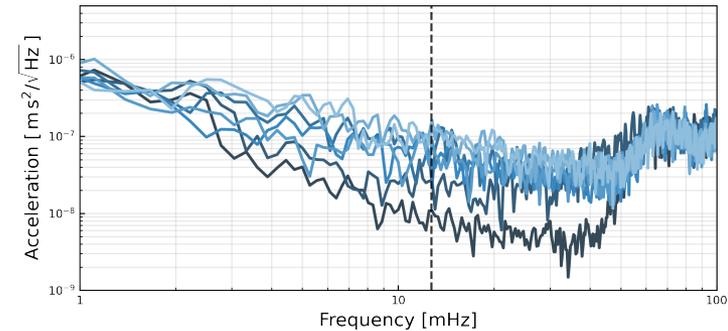
Displacement Sensitivity

Thermal-noise-limited sensitivity

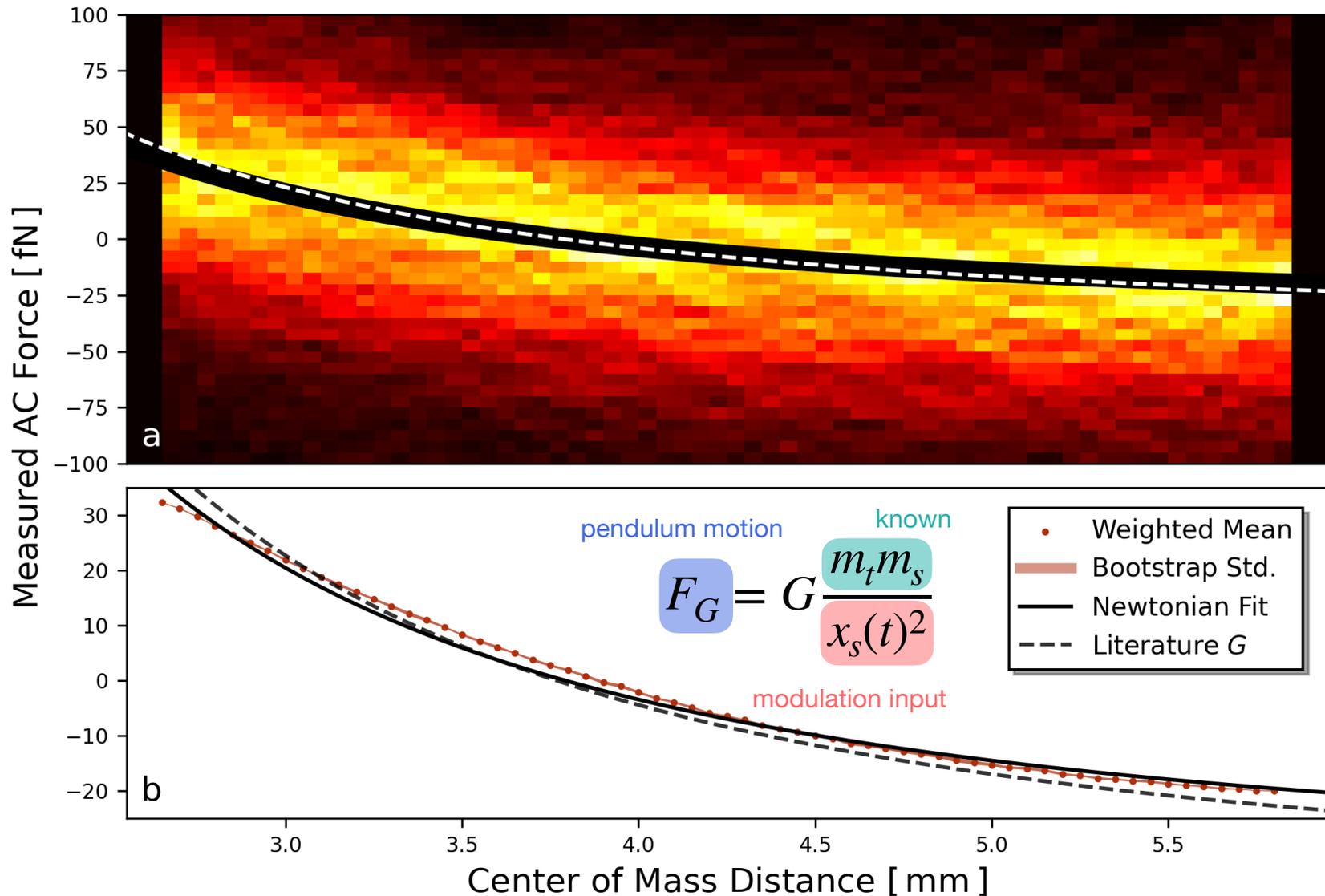


Non-Stationary Noise

- Vary in time
- Correlation with seismic noise
- But not linear response



Force vs Separation



Force vs Separation

pendulum motion

$$F_G = G \frac{m_t m_s}{x_s(t)^2}$$

known

modulation input

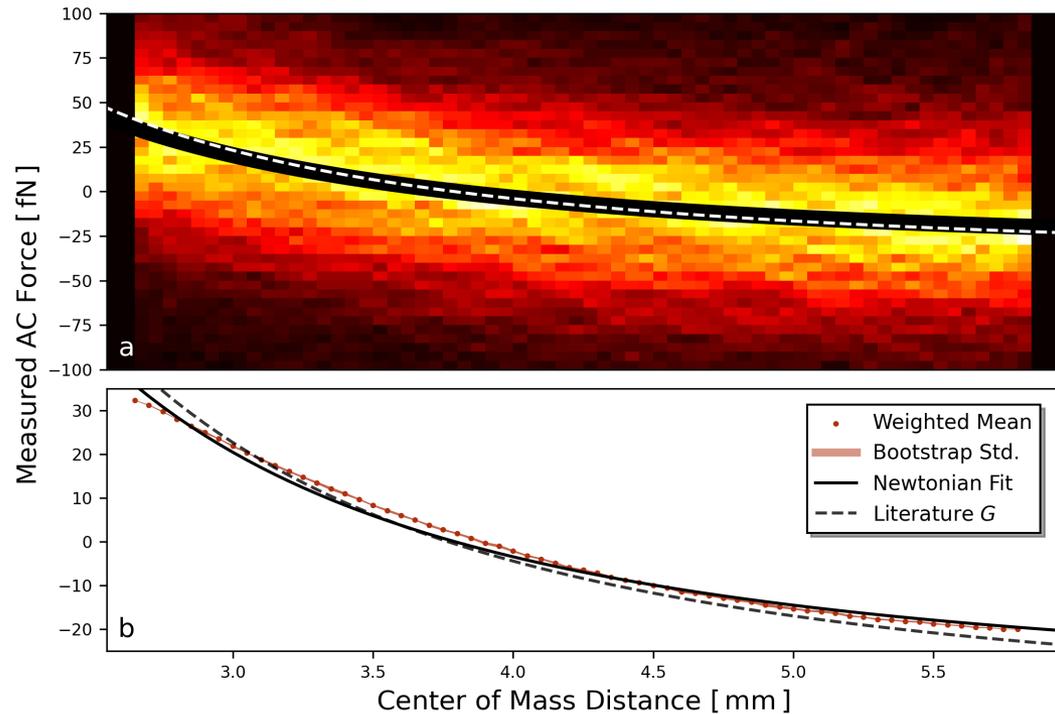
One data set in 13.5 hours

- Using this data, fitted G is

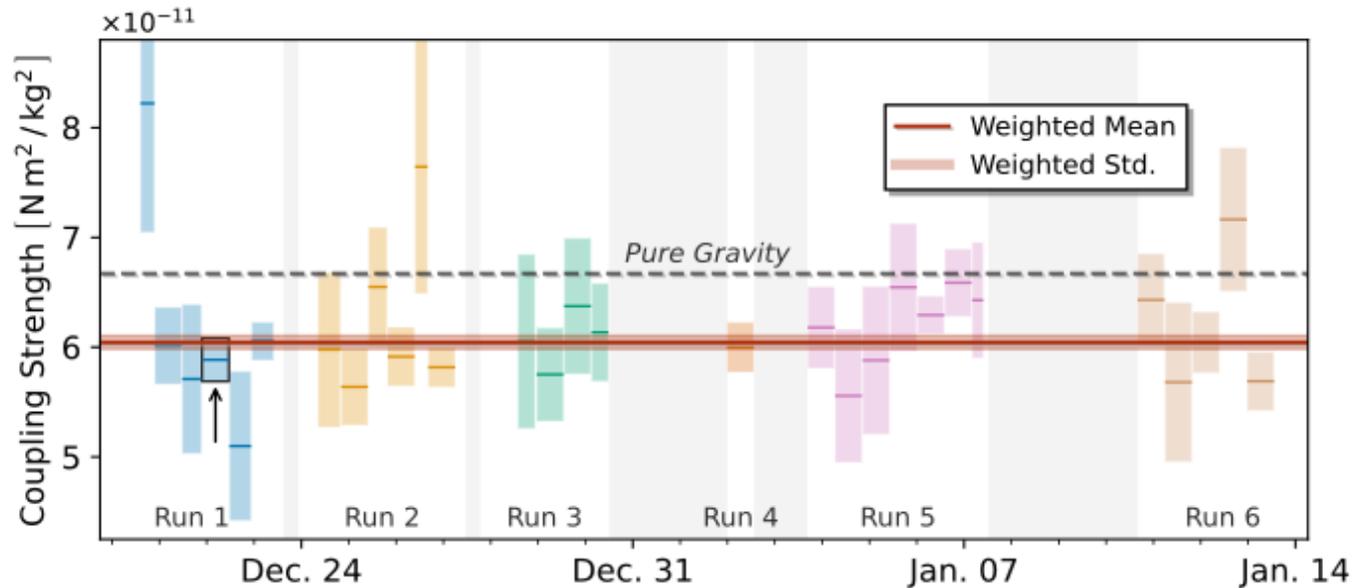
$$G_{fit} = 5.89 \pm 0.2 \times 10^{-11} \text{ N m}^2 / \text{kg}^2$$

- Literature value:

$$G_{lit} = 6.67 \times 10^{-11} \text{ N m} / \text{kg}^2$$



Combination of All Measurement Run



- Measurement over 3 weeks during 2019 Christmas season (because seismic noise due to human activity was quiet)
- Total measurement time: 350 hours
- Combining measurement runs, estimated G is

$$G_{comb} = 6.04 \pm 0.06 \times 10^{-11} \text{N m /kg}^2$$

- 1 % statistical error, 9 % systematic deviation below G_{lit}

Systematic Influences

- The quantified systematic influences is not fully cover the deviation of the estimated G 9 % below
- Video-tracking related items
 - ◉ calibration
 - ◉ drive calibration
 - ◉ height offset
 - ▶ In the future they will improve by
 - continuous tracking
 - 3D monitoring
- Most items relate with scale of the source mass
 - ▶ They put a limit on the accuracy of the estimation of G, but not limit the measurement of smaller source masses

effect	influence [F_G]
act. mass gravity	-1.1E-4
capillary gravity	+4.5E-3
glue gravity	+3E-3
titanium gravity	+7E-3
electrostatic	±3E-2
magnetic	±1E-4
calibration	±6E-3
drive calib.	±1.6E-2
mass separation	±1E-3
m_s accuracy	±1.1E-3
m_t accuracy	±1.1E-3
m_{glue} accuracy	+3E-3
height offset	±1.5E-2
m_s roundness	unknown
m_t roundness	unknown
Q accuracy	±5E-3
bandpass $1f_m$	+1.6E-2
bandpass $2f_m$	-7.6E-2
downsamplig	±1E-3
compensation pole	±1E-5
anti aliasing filter	±2E-6
upper limit	+11.0E-2
lower limit	-7.6E-2

Table II: identified systematic deviations

Summary of the Results

- Over an integration time of 350 hour,
 - ⊙ Resolution $\approx 4 \times 10^{-10} \text{ m/s}^2$
 - ⊙ Systematic precision $\approx 4 \times 10^{-11} \text{ m/s}^2$
 - ⊙ Statistical accuracy $\approx 4 \times 10^{-12} \text{ m/s}^2$
- Contribution of non-gravitational forces is kept below 10 %
- Current sensitivity is limited by thermal noise when ambient condition is optimal (quiet seismic motion)

Toward Smaller Masses

Consider possibilities of realizing the system with Planck mass ($m_P \approx 22 \mu\text{g}$) objects

- ▶ Reduction of thermal noise
- Current Q factor is $Q \sim 5$ for small amplitude
- When driving large amplitude (π rad), $Q = 20,000$ and different rest position
 - ▶ Potentially $Q = 20,000$ is achievable for this pendulum
 - ▶ The sensitivity will improve by $\sqrt{20000/5} \sim 65$ times
- Current SNR is $6.06/0.04 \sim 100$ with 100 mg object
 - ▶ For $Q=20,000$ SNR will improve to $\sim 6.04/0.04 \times 65 \sim 9800$
 - ▶ For Planck mass objects, SNR will $9800 \times 2.2e-4 \sim 2$
 - ▶ Measurable!
- Optical levitation is one way to reduce thermal noise

Other Challenges to Smaller Mass

- Casimir force between a plate and a sphere

$$F_{Casimir} = \frac{r_t k_B T \zeta(3)}{8d_s^2}$$

- In this experiment ($r_t = 1 \text{ mm}$, $d_s \approx 250 \mu\text{m}$) Casimir force is more than four orders of magnitude smaller than gravitational force
- For a Planck mass sized sphere with separation below $100 \mu\text{m}$ Casimir force will dominate the Newtonian gravity
 - ▶ We can avoid this by modulating gravitational force
- Casimir force might introduce instability of the torsion pendulum
- W/o Faraday shields Casimir force btw TM and SM exists
 - ▶ For Planck mass sized spheres the lower limit of the separation is $\sim 20 \mu\text{m}$

Future Application

- Application of Planck mass sized gravitational force source
 - ◉ Determine value of G in a different way
 - ▶ [CQG **33**, 125031 \(2016\)](#)
 - ◉ Search for new scalar field
 - ▶ [Science **349**, 849-851 \(2015\)](#)
 - ◉ Test of gravitation theory beyond Newtonian dynamics
 - ▶ [Canadian Journal of Physics **93**, 892-895 \(2015\)](#)
 - ◉ Quantum nature of gravity
 - ▶ [PRL **124**, 013603 \(2020\)](#)

Summary

- Gravitational force test in the regime of microscopic source mass is unexplored frontier
- They measured gravitational force between two tiny spheres (~ 100 mg) using a torsion pendulum
- Almost limited by thermal noise of the torsional mode
- Estimated G: $G_{comb} = 6.04 \pm 0.06 \times 10^{-11} \text{N m /kg}^2$
 - ◉ Statistical error: 1 %, systematic error: 10 %
 - ◉ Not fully covered by the quantified systematic errors
- Planck mass scale measurement will be realizable if Q is improved by factor of 4000 (or introducing optical levitation)

Appendix

125001 (2019).

- [35] Shimoda, T., Aritomi, N., Shoda, A., Michimura, Y., and Ando, M., Seismic cross-coupling noise in torsion pendulums. *Physical Review D* **97**(10), 104003 (2018).
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- [41] Komori, K. *et al.*, Attonewton-meter torque sensing with a macroscopic optomechanical torsion pendulum. *Physical Review A* **101**(1), 011802 (2020).
- [42] Ranjit, G., Cunningham, M., Casey, K., and Geraci, A. A., *Physical Review Letters* **117**(1), 010501 (2016).