Design of Phase-III TOBA

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Overview

- I would like to discuss the configuration of Phase-III TOBA for my Ph.D. thesis
- First part: comparison of the readout optical systems
- Second part: requirement of the suspension system
- I omit the introduction of TOBA because there are no M1 students

Contents

- Comparison of the readout optical systems
- Requirement of the suspension system
- Timeline for the next two years

Contents

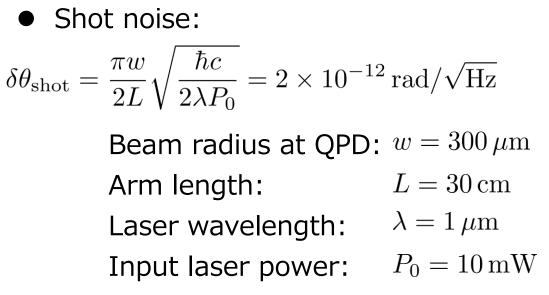
- Comparison of the readout optical systems
- Requirement of the suspension system
- Timeline for the next two years

Comparison of optical systems

- I summarized these considerations with two slides for each optical system
 - We will come back to this table at the end

Unit: [rad/√Hz]	Oplev	MI	PRMI	FPMI	QI	Cavities	WFS	CWFS, FWFS
Shot noise	2×10 ⁻¹²	2×10 ⁻¹⁵	5×10 ⁻¹⁶	4×10 ⁻¹⁸	2×10 ⁻¹⁵	4×10 ⁻¹⁸	1×10 ⁻¹¹	7×10 ⁻¹⁴
Thermal noise	7×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	7×10 ⁻¹⁷	7×10 ⁻¹⁷
Seismic coupling	2×10 ⁻¹²	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	No coupling	No coupling
Numbers of optics	1	6	10	11	11 polarizing	8	5	6
PD	QPD	PD	PD, RFPD	PD, RFPD	3PD	2RFPD	RFQPD	RFQPD
Experience in Ando Lab	Shimos d-san's D	Shoda- san, Shimod a-san's M	Aritomi -san's M	Nothing	Okada- san	ANU, Takano- san's D	Nothing	Nothing

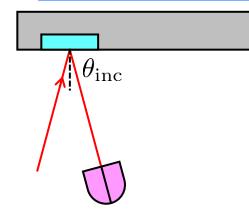
Optical lever



• Thermal noise (mirror substrate):

$$\begin{split} \delta\theta_{\rm thermal} &= \sqrt{\frac{2k_BT}{\pi^{3/2}f} \frac{1-\nu_s^2}{E_s} \frac{\phi_s}{w^3}} = 7 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz}} \\ f &= 0.1 \, {\rm Hz} \quad w = 100 \, \mu {\rm m} \quad T = 4 \, {\rm K} \\ {\rm Substrate: \ fused \ silica} & {\rm Young's \ modulus: \ } E_s = 7.4 \, {\rm GPa} \\ {\rm Poisson's \ ratio:} \quad \nu_s = 0.17 \\ {\rm Loss \ angle:} \quad \phi_s = 10^{-8} \end{split}$$

Optical lever

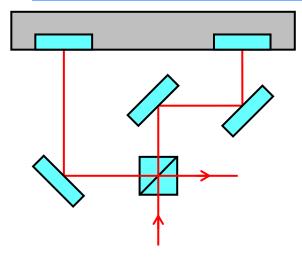


• Seismic coupling: $\delta \theta_{seis} = \frac{\sin \theta_{inc}}{2L} \delta x_{seis} \text{CMRR} = 2 \times 10^{-12} \text{ rad}/\sqrt{\text{Hz}}$ Incident angle: $\theta_{inc} = 1 \text{ mrad}$ Arm length: L = 30 cmTranslational seismic noise: $\delta x_{seis} = 10^{-7} \text{ m}/\sqrt{\text{Hz}}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

• Numbers of optics: 1 mirror (only essential optics. Of course, some mirrors or BS are needed)

• PD: 1 QPD

Michelson interferometer



• Shot noise:

$$\delta\theta_{\rm shot} = \frac{1}{2L} \sqrt{\frac{\hbar c\lambda}{\pi P_0}} = 2 \times 10^{-15} \, \mathrm{rad}/\sqrt{\mathrm{Hz}}$$

Arm length: $L = 30 \,\mathrm{cm}$ Laser wavelength: $\lambda = 1 \,\mu\mathrm{m}$ Input laser power: $P_0 = 10 \,\mathrm{mW}$

• Thermal noise (bar):

$$\delta\theta_{\rm thermal} = \frac{1}{L} \sqrt{\frac{4k_B T}{\omega} \frac{\phi_{\rm bar}}{\mu \omega_0^2}} = 1 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz}$$

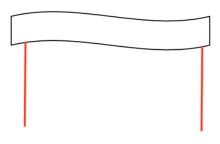
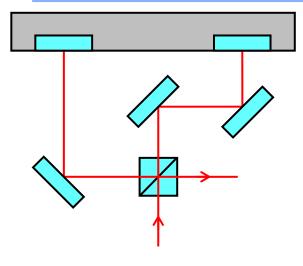


図 4.8: 試験マスの2次のモード Aritomi-san's master thesis

 $T = 4 \text{ K} \qquad \omega = 2\pi \times 0.1 \text{ Hz} \qquad \phi_{\text{bar}} = 10^{-6} \qquad \text{Arito}$ Frequency of second mode: $\omega_0 = 2\pi \times 10 \text{ kHz}$ Reduced mass of second mode: $\mu = 0.3 \text{ kg}$

Michelson interferometer

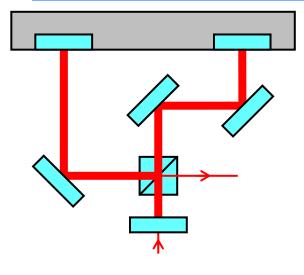


Seismic coupling: $\delta\theta_{\rm seis} = \frac{\theta_{\rm mir}}{I} \delta x_{\rm seis} \text{CMRR} = 2 \times 10^{-13} \,\text{rad}/\sqrt{\text{Hz}}$ Angle of two mirrors: $\theta_{\rm mir} = 10^{-6} \, \rm rad$ Arm length: $L = 30 \,\mathrm{cm}$ Translational seismic noise: $\delta x_{\rm seis} = 5 \times 10^{-6} \,\mathrm{m}/\sqrt{\mathrm{Hz}}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

- Cannot meet the requirement
 → discuss in the next section
- Numbers of optics: 5 mirrors, 1 BS

• PD: 1 PD

Power recycled MI



• Shot noise:

$$\delta\theta_{\rm shot} = \frac{1}{2L} \sqrt{\frac{\hbar c\lambda}{\pi G P_0}} = 5 \times 10^{-16} \, \mathrm{rad}/\sqrt{\mathrm{Hz}}$$

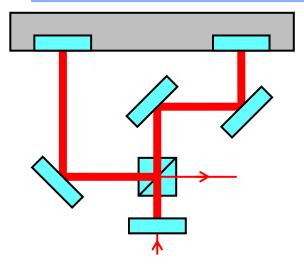
Arm length: $L = 30 \,\mathrm{cm}$ Laser wavelength: $\lambda = 1 \,\mu\mathrm{m}$ Input laser power: $P_0 = 10 \,\mathrm{mW}$ Power recycle gain:G = 10

• Thermal noise (bar): same as MI

$$\delta\theta_{\rm thermal} = \frac{1}{L} \sqrt{\frac{4k_B T}{\omega} \frac{\phi_{\rm bar}}{\mu \omega_0^2}} = 1 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz}$$

 $T = 4 \text{ K} \qquad \omega = 2\pi \times 0.1 \text{ Hz} \qquad \phi_{\text{bar}} = 10^{-6}$ Frequency of second mode: $\omega_0 = 2\pi \times 10 \text{ kHz}$ Reduced mass of second mode: $\mu = 0.3 \text{ kg}$

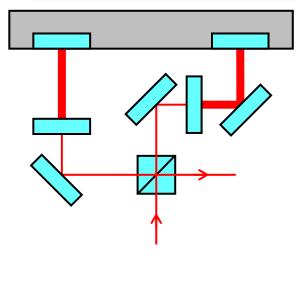
Power recycled MI



• Seismic coupling: same as MI $\delta \theta_{seis} = \frac{\theta_{mir}}{L} \delta x_{seis} CMRR = 2 \times 10^{-13} rad/\sqrt{Hz}$ Angle of two mirrors: $\theta_{mir} = 10^{-6} rad$ Arm length: L = 30 cmTranslational seismic noise: $\delta x_{seis} = 5 \times 10^{-6} m/\sqrt{Hz}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

- Numbers of optics: 6 mirrors, 2 BS (1 for PDH), 2 lenses
- PD: 1 RFPD, 1 PD

Fabry-Pérot MI



• Shot noise:

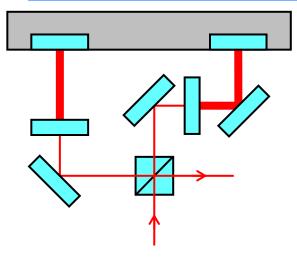
$$\delta heta_{
m shot} = rac{t^2}{8L} \sqrt{rac{\hbar c \lambda}{\pi P_0}} = 4 \times 10^{-18} \, {
m rad}/\sqrt{
m Hz}$$

Arm length: $L = 30 \, {
m cm}$
Laser wavelength: $\lambda = 1 \, \mu {
m m}$
Input laser power: $P_0 = 10 \, {
m mW}$
Transmittance of
front mirrors: $t^2 = 1\%$ (End: 0%)

• Thermal noise (bar): same as MI

$$\begin{split} \delta\theta_{\rm thermal} &= \frac{1}{L} \sqrt{\frac{4k_B T}{\omega} \frac{\phi_{\rm bar}}{\mu \omega_0^2}} = 1 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz} \\ T &= 4 \, {\rm K} \qquad \omega = 2\pi \times 0.1 \, {\rm Hz} \qquad \phi_{\rm bar} = 10^{-6} \\ {\rm Frequency \ of \ second \ mode:} \qquad \omega_0 = 2\pi \times 10 \, {\rm kHz} \\ {\rm Reduced \ mass \ of \ second \ mode:} \qquad \mu = 0.3 \, {\rm kg} \end{split}$$

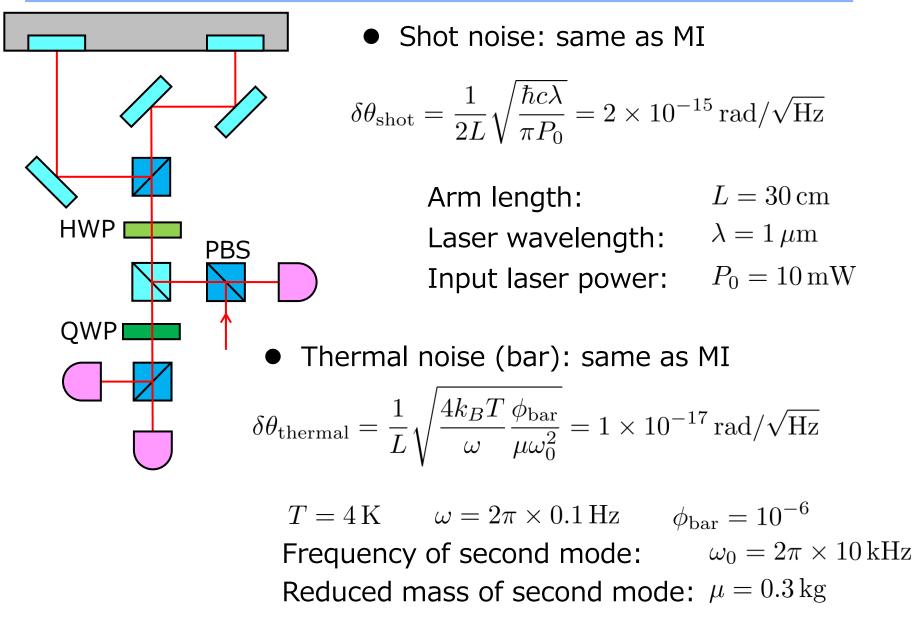
Fabry-Pérot MI



• Seismic coupling: same as MI $\delta \theta_{seis} = \frac{\theta_{mir}}{L} \delta x_{seis} CMRR = 2 \times 10^{-13} rad/\sqrt{Hz}$ Angle of two mirrors: $\theta_{mir} = 10^{-6} rad$ Arm length: L = 30 cmTranslational seismic noise: $\delta x_{seis} = 5 \times 10^{-6} m/\sqrt{Hz}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

- Numbers of optics: 7 cavity mirrors, 2 BS, 2 lenses
- PD: 1 RFPD, 1 PD

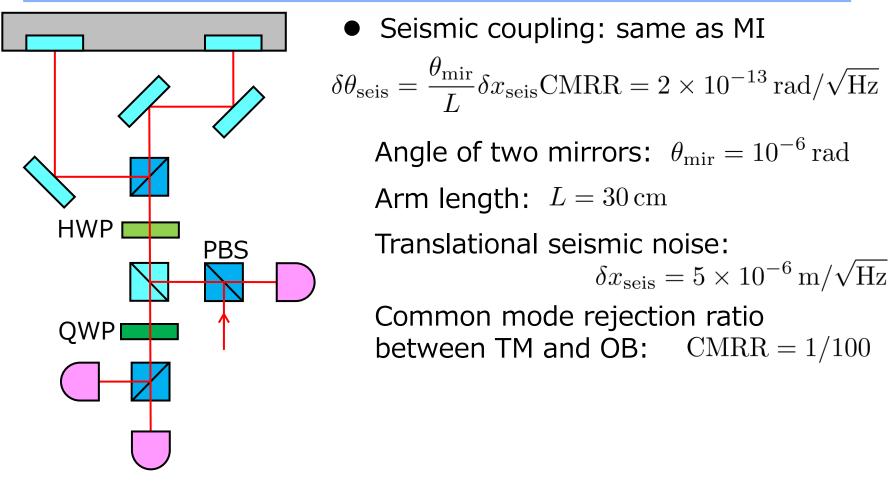
Quadrature interferometer



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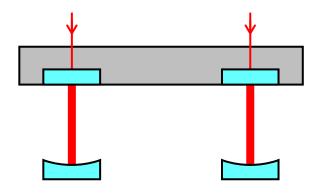
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Quadrature interferometer



- Numbers of optics: 5 mirrors, 1 BS, 3 PBS, 1 QWP, 1 HWP
- PD: 3 PD

Differential Fabry–Pérot cavities

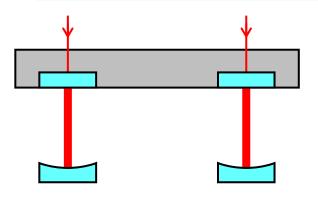


$$\begin{split} \delta\theta_{\rm shot} &= \frac{t^2}{8L} \sqrt{\frac{\hbar c\lambda}{\pi P_0}} = 4 \times 10^{-18} \, {\rm rad}/\sqrt{\rm Hz} \\ \text{Arm length:} & L = 30 \, {\rm cm} \\ \text{Laser wavelength:} & \lambda = 1 \, \mu {\rm m} \\ \text{Input laser power:} & P_0 = 10 \, {\rm mW} \\ \text{Transmittance of} \\ \text{front mirrors:} & t^2 = 1\% \text{ (End: 0\%)} \end{split}$$

• Thermal noise (bar): same as MI

$$\begin{split} \delta\theta_{\rm thermal} &= \frac{1}{L} \sqrt{\frac{4k_B T}{\omega} \frac{\phi_{\rm bar}}{\mu \omega_0^2}} = 1 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz} \\ T &= 4 \, {\rm K} \qquad \omega = 2\pi \times 0.1 \, {\rm Hz} \qquad \phi_{\rm bar} = 10^{-6} \\ {\rm Frequency \ of \ second \ mode:} \qquad \omega_0 &= 2\pi \times 10 \, {\rm kHz} \\ {\rm Reduced \ mass \ of \ second \ mode:} \qquad \mu &= 0.3 \, {\rm kg} \end{split}$$

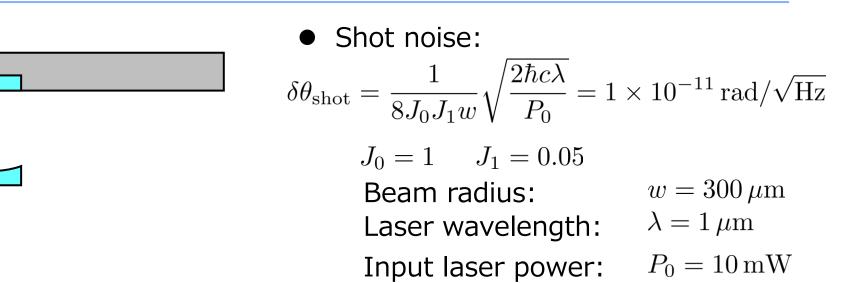
Differential Fabry–Pérot cavities



• Seismic coupling: same as MI $\delta \theta_{seis} = \frac{\theta_{mir}}{L} \delta x_{seis} CMRR = 2 \times 10^{-13} rad/\sqrt{Hz}$ Angle of two mirrors: $\theta_{mir} = 10^{-6} rad$ Arm length: L = 30 cmTranslational seismic noise: $\delta x_{seis} = 5 \times 10^{-6} m/\sqrt{Hz}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

- Numbers of optics: 4 mirrors, 2 BS, 2 lenses
- PD: 2 RFPD

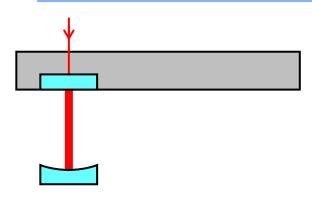
Wavefront sensor



• Thermal noise (mirror substrate): same as oplev

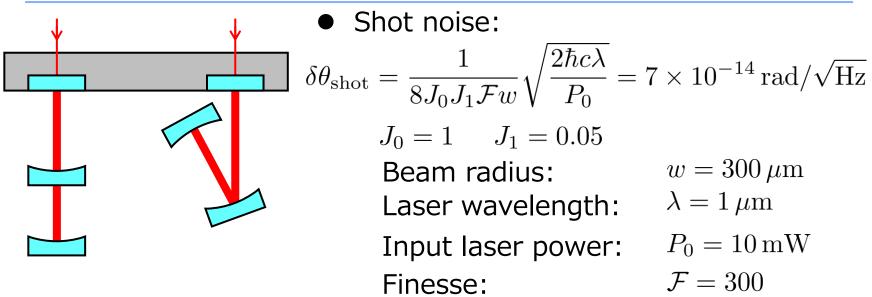
$$\begin{split} \delta\theta_{\rm thermal} &= \sqrt{\frac{2k_BT}{\pi^{3/2}f}} \frac{1-\nu_s^2}{E_s} \frac{\phi_s}{w^3} = 7 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz} \\ f &= 0.1 \, {\rm Hz} \quad w = 100 \, \mu {\rm m} \quad T = 4 \, {\rm K} \\ {\rm Substrate: \ fused \ silica} & {\rm Young's \ modulus: \ } E_s = 7.4 \, {\rm GPa} \\ {\rm Poisson's \ ratio:} \quad \nu_s = 0.17 \\ {\rm Loss \ angle:} \quad \phi_s = 10^{-8} \end{split}$$

Wavefront sensor



- Seismic coupling:
 - In principle, no coupling by using a flat mirror and sufficient PDH (length) control
 - Non-linear coupling?
- Numbers of optics: 2 cavity mirrors, 1 BS, 2 lenses
- PD: 1 RFQPD

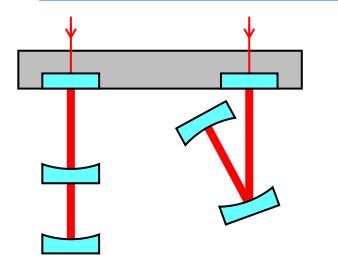
Coupled or Folded WFS



• Thermal noise (mirror substrate): same as oplev

$$\begin{split} \delta\theta_{\rm thermal} &= \sqrt{\frac{2k_BT}{\pi^{3/2}f} \frac{1-\nu_s^2}{E_s} \frac{\phi_s}{w^3}} = 7 \times 10^{-17} \, {\rm rad}/\sqrt{\rm Hz}} \\ f &= 0.1 \, {\rm Hz} \quad w = 100 \, \mu {\rm m} \quad T = 4 \, {\rm K} \\ {\rm Substrate: fused silica} & {\rm Young's \ modulus: } E_s = 7.4 \, {\rm GPa} \\ {\rm Poisson's \ ratio:} \quad \nu_s = 0.17 \\ {\rm Loss \ angle:} \quad \phi_s = 10^{-8} \end{split}$$

Coupled or Folded WFS



- Seismic coupling:
 - In principle, no coupling by using a flat mirror and sufficient PDH (length) control
 - Non-linear coupling?
- Numbers of optics: 3 cavity mirrors, 1 BS, 2 lenses
- PD: 1 RFQPD

Comparison of optical systems

- Oplev, WFS, CWFS cannot meet the shot noise requirement
- WFS cannot meet even with KAGRA parameter

<u>Aso+ (2013)</u>

• CWFS will meet with large beam and high finesse

Unit: [rad/√Hz]	Oplev	MI	PRMI	FPMI	QI	Cavities	WFS	CWFS, FWFS
Shot noise	2×10 ⁻¹²	2×10 ⁻¹⁵	5×10 ⁻¹⁶	4×10 ⁻¹⁸	2×10 ⁻¹⁵	4×10 ⁻¹⁸	1×10 ⁻¹¹	7×10 ⁻¹⁴
Thermal noise	7×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	7×10 ⁻¹⁷	7×10 ⁻¹⁷
Seismic coupling	2×10 ⁻¹²	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	No coupling	No coupling
Numbers of optics	1	6	10	11	11 polarizing	8	5	6
PD	QPD	PD	PD, RFPD	PD, RFPD	3PD	2RFPD	RFQPD	RFQPD
Experience in Ando Lab	Shimos d-san's D	Shoda- san, Shimod a-san's M	Aritomi -san's M	Nothing	Okada- san	ANU, Takano- san's D	Nothing	Nothing

Comparison of optical systems

- I give them rough scores to make the ranking
- Michelson interferometer: very simple
- Two cavities: sensitive and quite simple

Unit: [rad/√Hz]	MI	PRMI	FPMI	QI	Cavities
Shot noise	2×10 ⁻¹⁵	5×10 ⁻¹⁶ 2	4×10 ⁻¹⁸ 3	2×10 ⁻¹⁵	4×10 ⁻¹⁸ 3
Thermal noise	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷	1×10 ⁻¹⁷
Seismic coupling	2×10 ⁻¹²	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³	2×10 ⁻¹³
Numbers of optics	6 5	10 3	11 2	11 polarizing 1	8 4
PD	PD 3	PD, RFP ²	PD, RFP ²	3PD 2	2RFPD 1
Experience in Ando Lab	Shoda-san, Shimoda- san's M 3	Aritomi- san's M	Nothing 1	Okada-san 2	ANU, Takano- san's D 3
	12	9	8	6	11

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My concerning points

• MI is simple, easy to operate and sensitive, so it makes sense that it has been used in many exp. so far

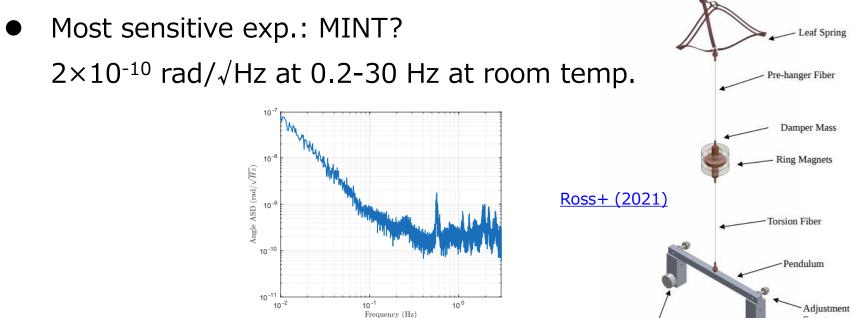


FIG. 7: Amplitude spectral density of the inertial angular noise.

FIG. 2: CAD rendering of the MINT pendulum and eddy current damper assembly.

Interferometer

Mirrors

Difficult if not the highest sensitivity in the world?

Is MI not impactful enough for Ph.D.?

 Is it first in the world to build a torsion pendulum with cryo. temp. and two cavities to readout angles? Screw

Contents

- Comparison of the readout optical systems
- Requirement of the suspension system
- Timeline for the next two years

Two kinds of seismic noise

- We should take into account of two kinds of seismic noise to design TOBA's suspension
- Rotational seismic noise
 - Assuming $10^{-9} \text{ rad}/\sqrt{\text{Hz}}$ at 0.1 Hz
 - Need to be isolated to $10^{-15} \text{ rad}/\sqrt{\text{Hz}}$

(= reduce 6 orders of magnitude)

- Translational seismic noise
 - $5 \times 10^{-6} \text{ m}/\sqrt{\text{Hz}}$ at 0.1 Hz
 - Need to reduce the coupling (transfer function) to <10⁻¹⁰ rad/m

Rotational seismic noise

- Requirement: reduce 6 orders of magnitude
- Multi-stage torsion pendulum can isolate torsional seismic noise
- 3-stage pendulum: 6 orders of magnitude (enough)
- 2-stage pendulum: 4 orders of magnitude
 - Isolate with CMRR for two more orders of magnitude

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 10^{2}

 10^{-2}

10

10

10-8

 10^{-1}

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- CMRR = 1/100
 - \rightarrow Match resonant freq. of TM and OB with the accuracy of 0.5%

 \rightarrow Moment of inertia 1% (10 g scale)

CMRR ~
$$\frac{2\Delta f}{f_{\text{yaw}}}$$
 $f_{\text{yaw}} = \frac{1}{2\pi} \sqrt{\frac{\pi E d^4}{64l(1+\nu)I}}$

Translational seismic noise (1)

- Requirement: coupling < 10^{-10} rad/m
- Coupling path 1: tilt of the two mirrors $\delta \theta_{seis} = \frac{\theta_{mir}}{L} \delta x_{seis} \text{CMRR} = 2 \times 10^{-13} \text{ rad} / \sqrt{\text{Hz}}$

Angle of two mirrors:
$$\theta_{\rm mir} = 10^{-6} \, \rm rad$$

Arm length: $L = 30 \,\mathrm{cm}$

Translational seismic noise:

 $\delta x_{seis} = 5 \times 10^{-6} \text{ m}/\sqrt{\text{Hz}}$ Common mode rejection ratio between TM and OB: CMRR = 1/100

Requirement: $CMRR < 10^{-4}$

Match the distance from the clamping point to the center of gravity for TM and OB with an accuracy of 1 mm



Translational seismic noise (2)

- Requirement: coupling $< 10^{-10}$ rad/m
- Coupling path 2: shift of center of gravity and suspension point

Requirement: $\Delta \phi_P < 2.5 \times 10^{-9}$

(Shimoda-san's M thesis)

- How to reduce
 - Counter-weight
 - Actuate
 - But feasibility is not clear…

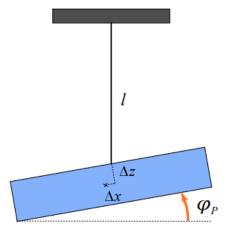
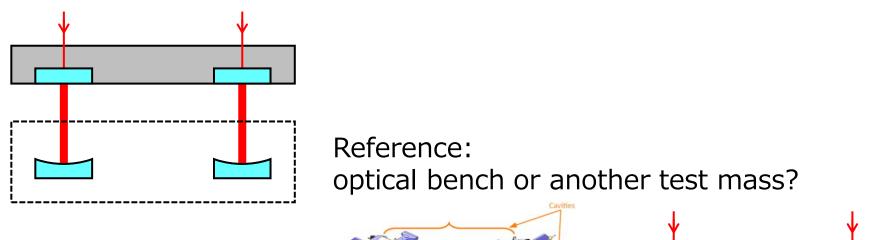
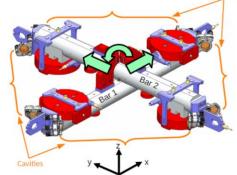
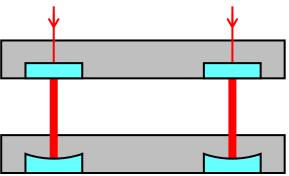


図 4.6: 重心と懸架点のズレ

Two cavities: optical bench





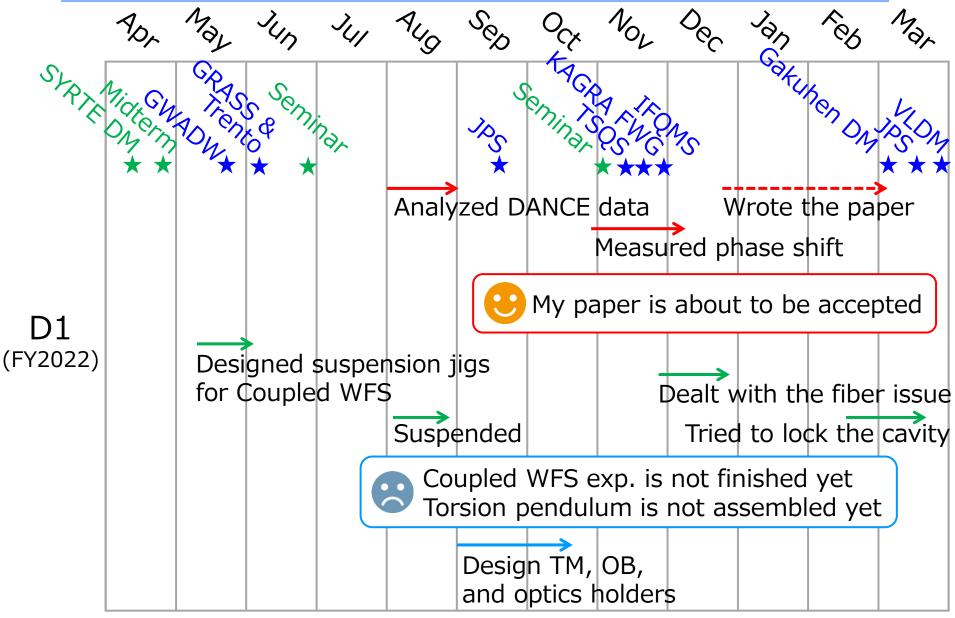


	Optical bench	Another test mass
Experience in Ando Lab	Many (All TOBA)	Few (Ono-kun's M, Komori-san's D?)
Common mode rejection	Difficult because test masses are different	Easier because the same two suspension

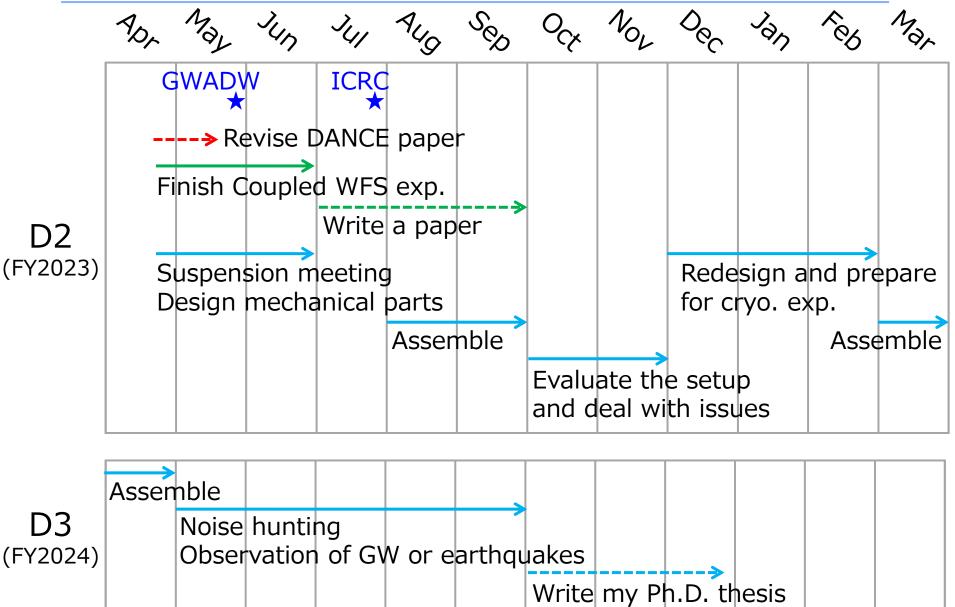
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- Comparison of the readout optical systems
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Reflections on FY2022



Plans of the next two years



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Summary

- Comparison of the readout optical systems
 - MI is quite simple, but two cavities are suitable for my Ph.D.?
- Requirement of the suspension system
- Timeline for the next two years
 - I should start the engine to finish the experiment in a year and a half



