

The assessment of DPFP cavity experiment

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Midterm report meeting 2023

Abstract

- I will introduce the current situation of noise budget
- For my research purpose, I was not really pursuing sensitivity. However, It was better than I expected, so I hope to get better sensitivity with this set up
- We designed a suspension last year. I would like to discuss how to make it better
- To save the time to create circuits (soldering, making boxes), I would like to package and design highly versatile circuits.

Contents

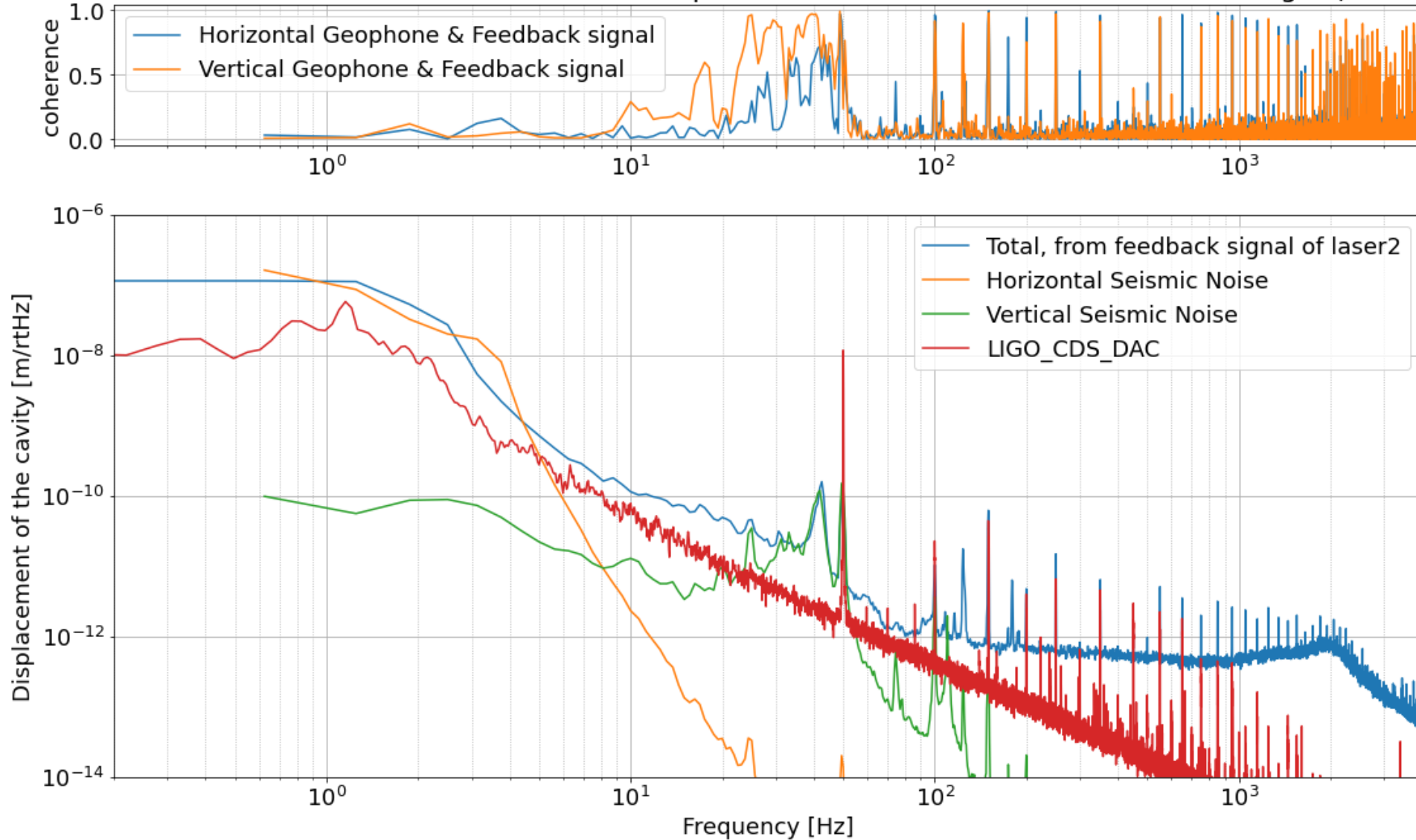
- Current Situation of Noise Budget ノイズバジレットの現状
- Some Update Plans for my experimental setup 実験系のアップデート
- Some Update Plans for Our Suspension サスペンションのアップデート
- Developing Circuits 回路の開発
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Current Status of Noise Budget ノイズバジレットの現状

Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



The roughly estimated spectrum of the displacement of the cavity in the free-running (OPLEV is implemented)

LIGO CDS DAC Noise デジタルシステムのDACの電氣的雜音

To reduce DAC noise...

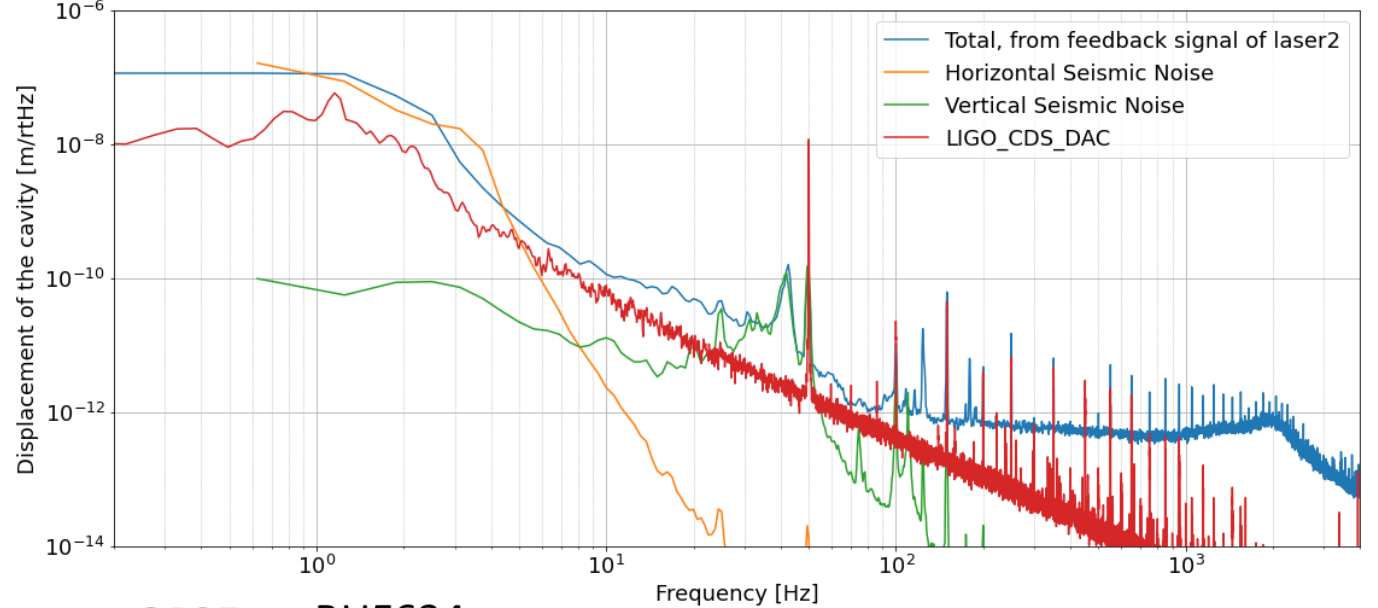
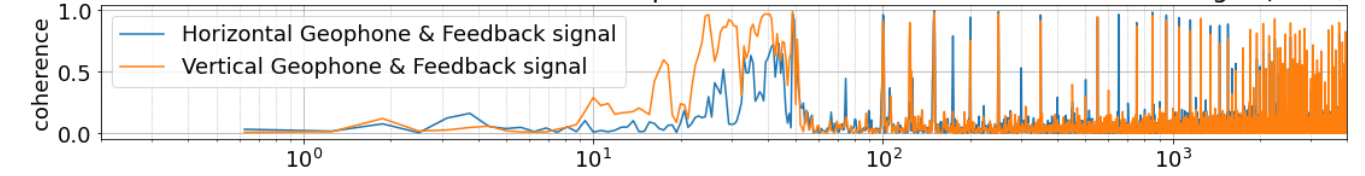
High actuator efficiency of coil-magnet

$$\frac{1}{3} \text{ [N/A]}$$

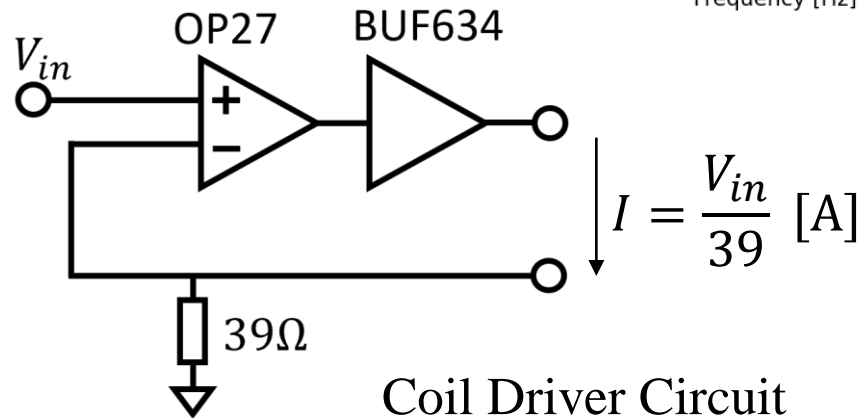
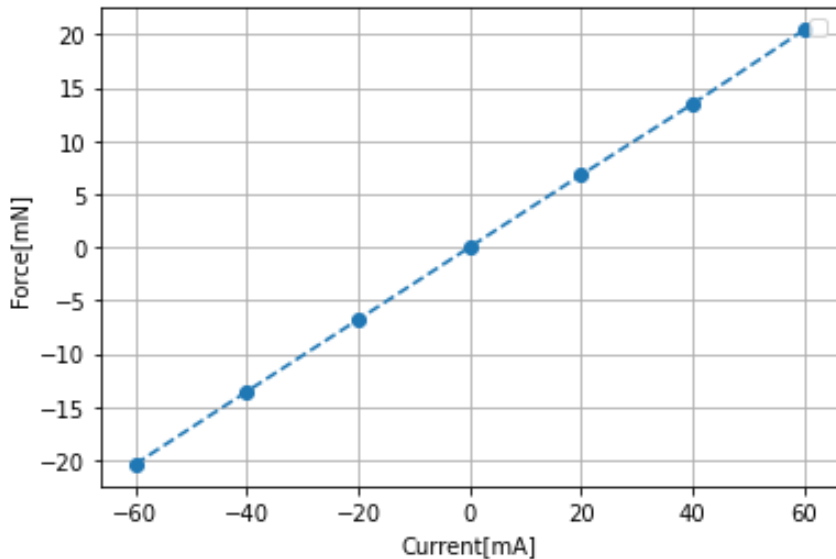
So, replacing with higher value resistor to reduce actuator efficiency

$$39 \text{ } [\Omega] \rightarrow 390 \text{ } [\Omega]$$

Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)

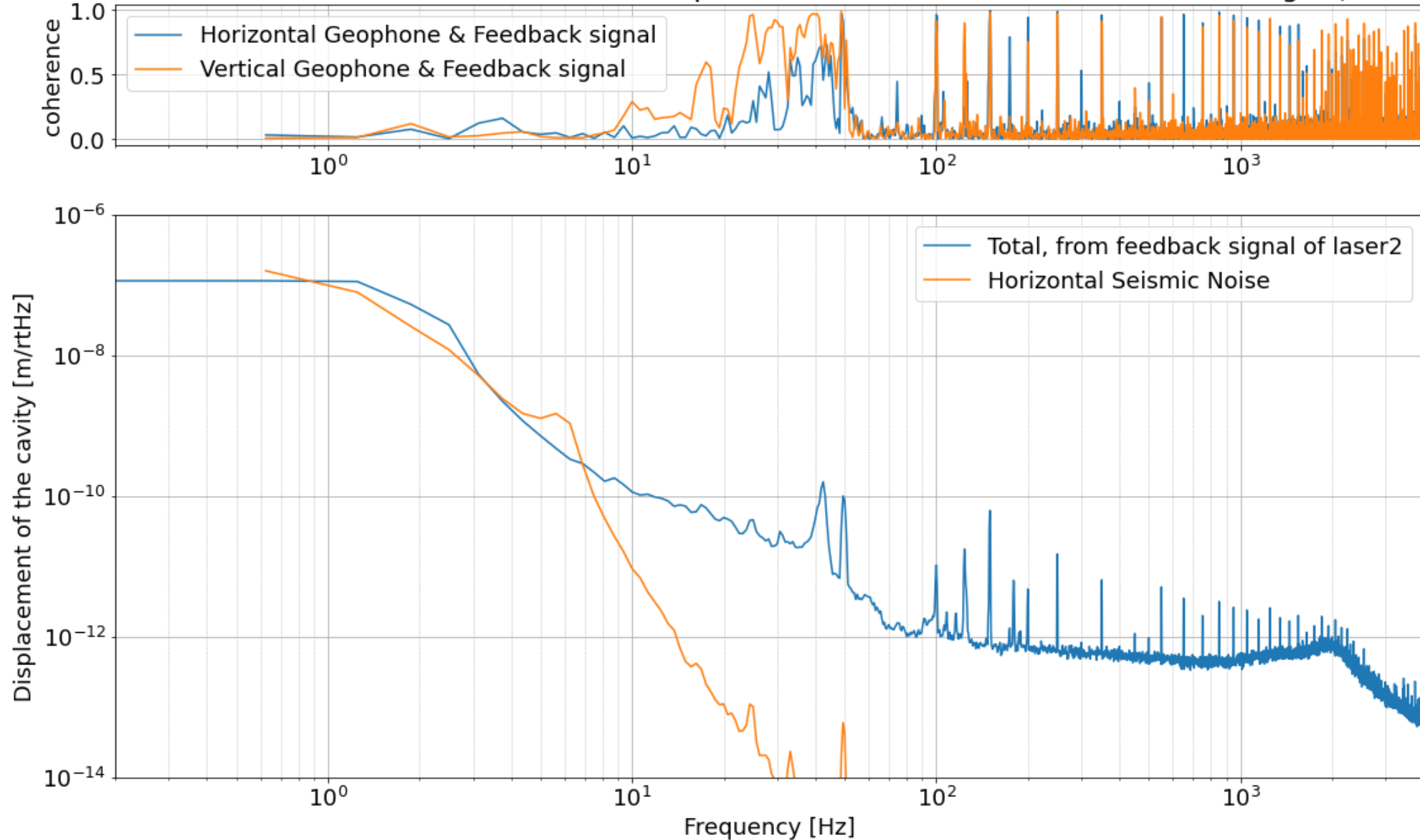


Measured Current to Force of coil magnet actuator



Horizontal Seismic Noise 水平方向の地面振動雑音

Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



Horizontal Seismic Noise 水平方向の地面振動雑音

Assuming, parameters of 2-stage suspension

$$f_0 = 1.28 \text{ [Hz]}$$

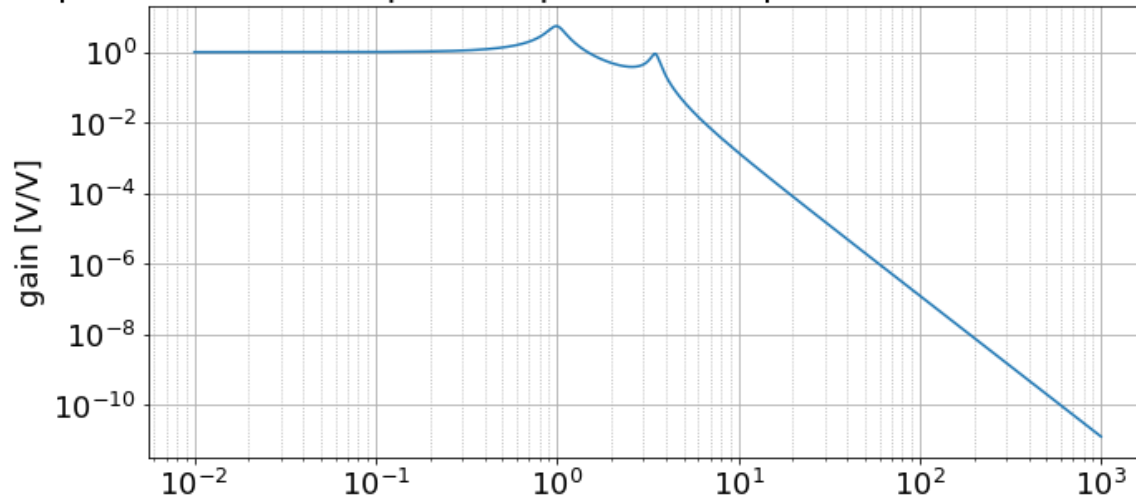
$$Q_0 = 5$$

$$f_1 = 3.5 \text{ [Hz]}$$

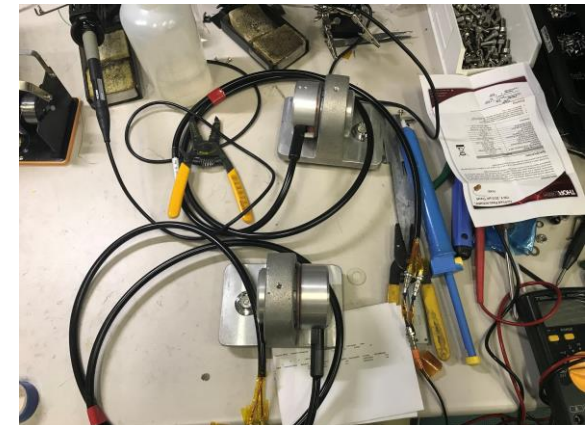
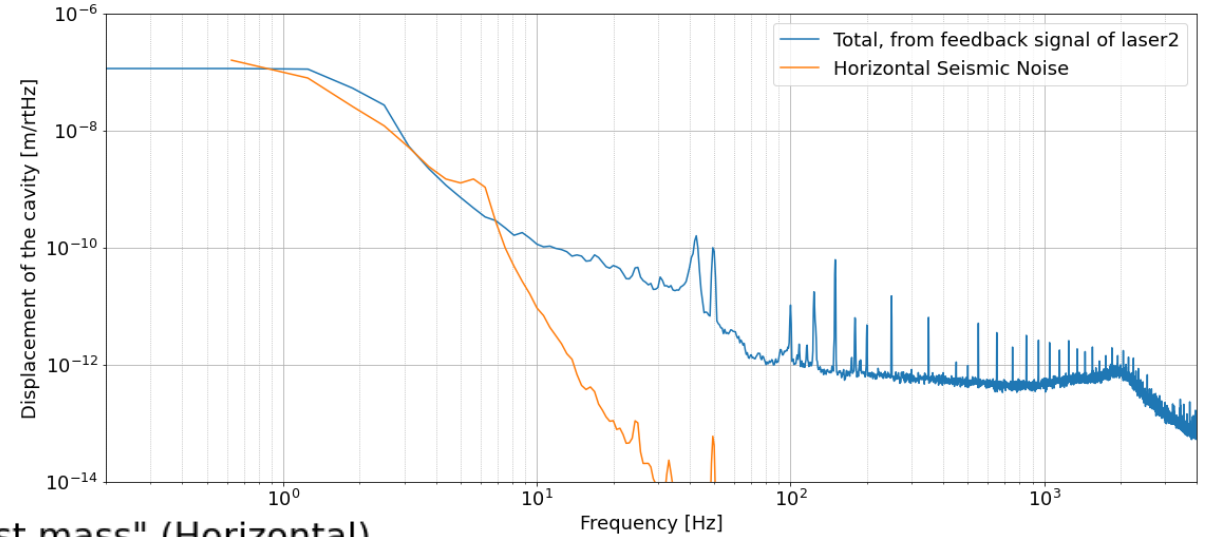
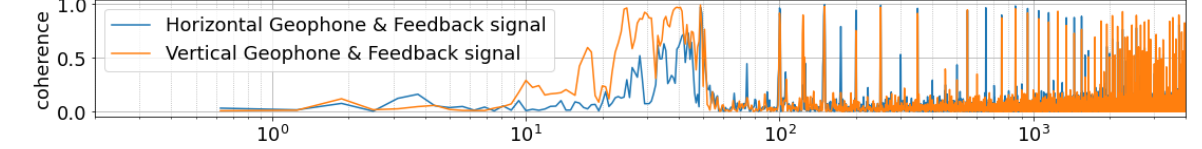
$$Q_1 = 10$$



TF from Displacement of "Suspension point" to Displacement of "Test mass" (Horizontal)



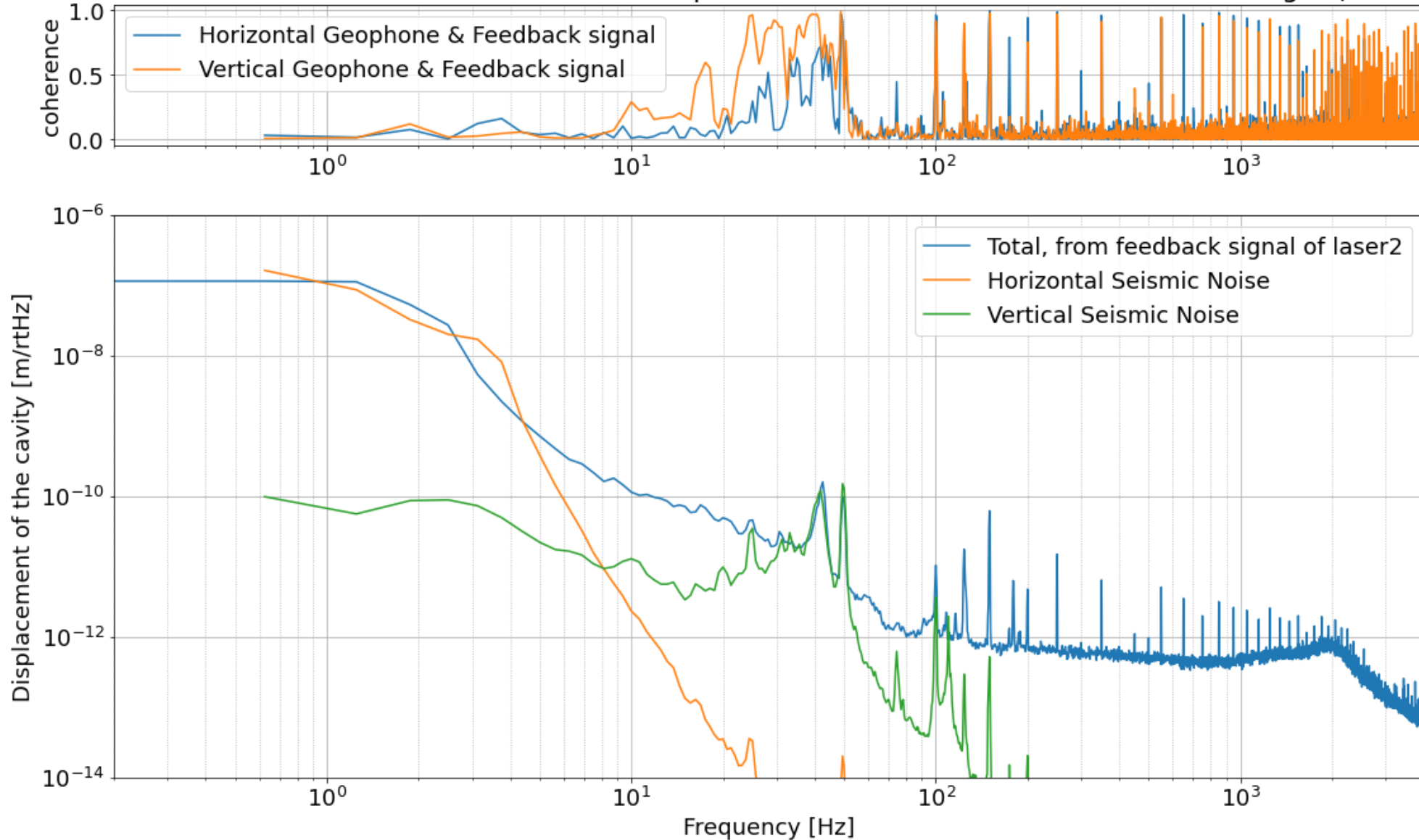
Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



Geophone to measure horizontal seismic noise

Vertical Seismic Noise 鉛直方向の地面振動雑音

Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



Vertical Seismic Noise 鉛直方向の地面振動雑音

Coupling constant
from “Vertical motion” to “Horizontal motion”

$$\gamma_{VH} = 0.00848$$

Resonant frequency of the blade spring

$$f_B = 42 \text{ [Hz]}$$

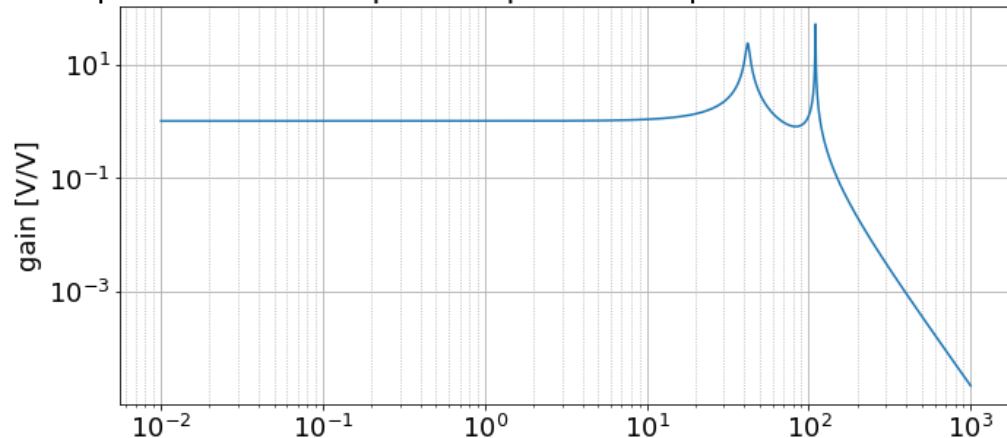
$$Q_B = 20$$

Resonant frequency of tungsten wires

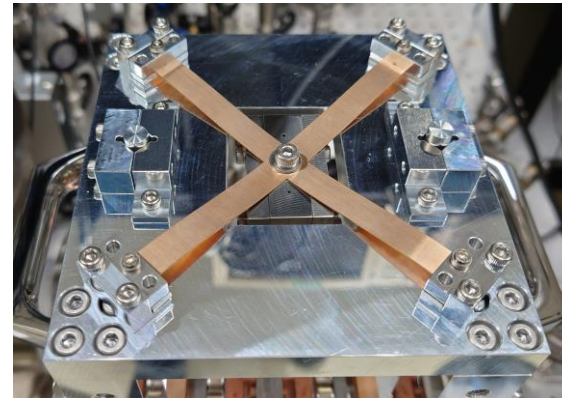
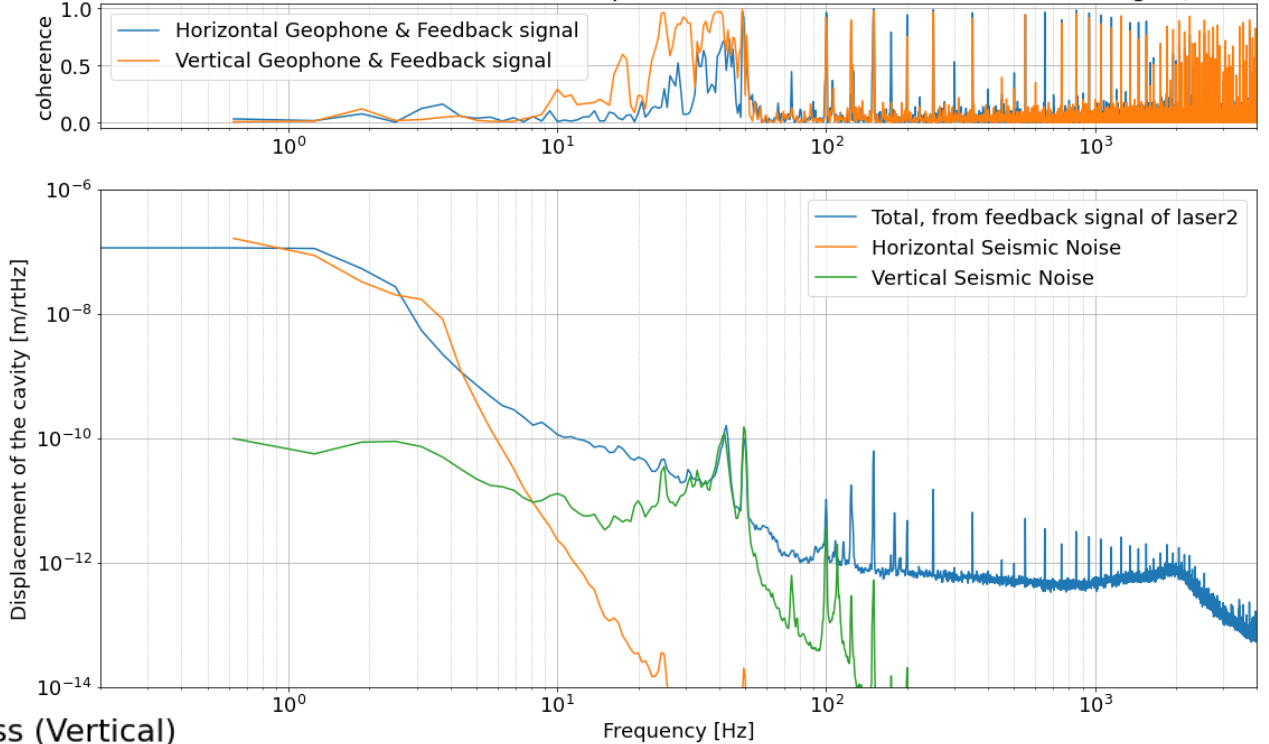
$$f_w = 110 \text{ [Hz]}$$

$$Q_w = 300$$

TF from Displacement of Suspension point to Displacement of Test mass (Vertical)



Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



The blade spring of the suspension

Assessment of RMS and Range of Actuator RMSの評価とレンジのとの比較

In free running,

$$\delta x_{\text{RMS}} = 0.134 \mu\text{m} \\ \leftrightarrow 68 \text{ MHz}$$

1 FSR = 532 nm = 268 MHz

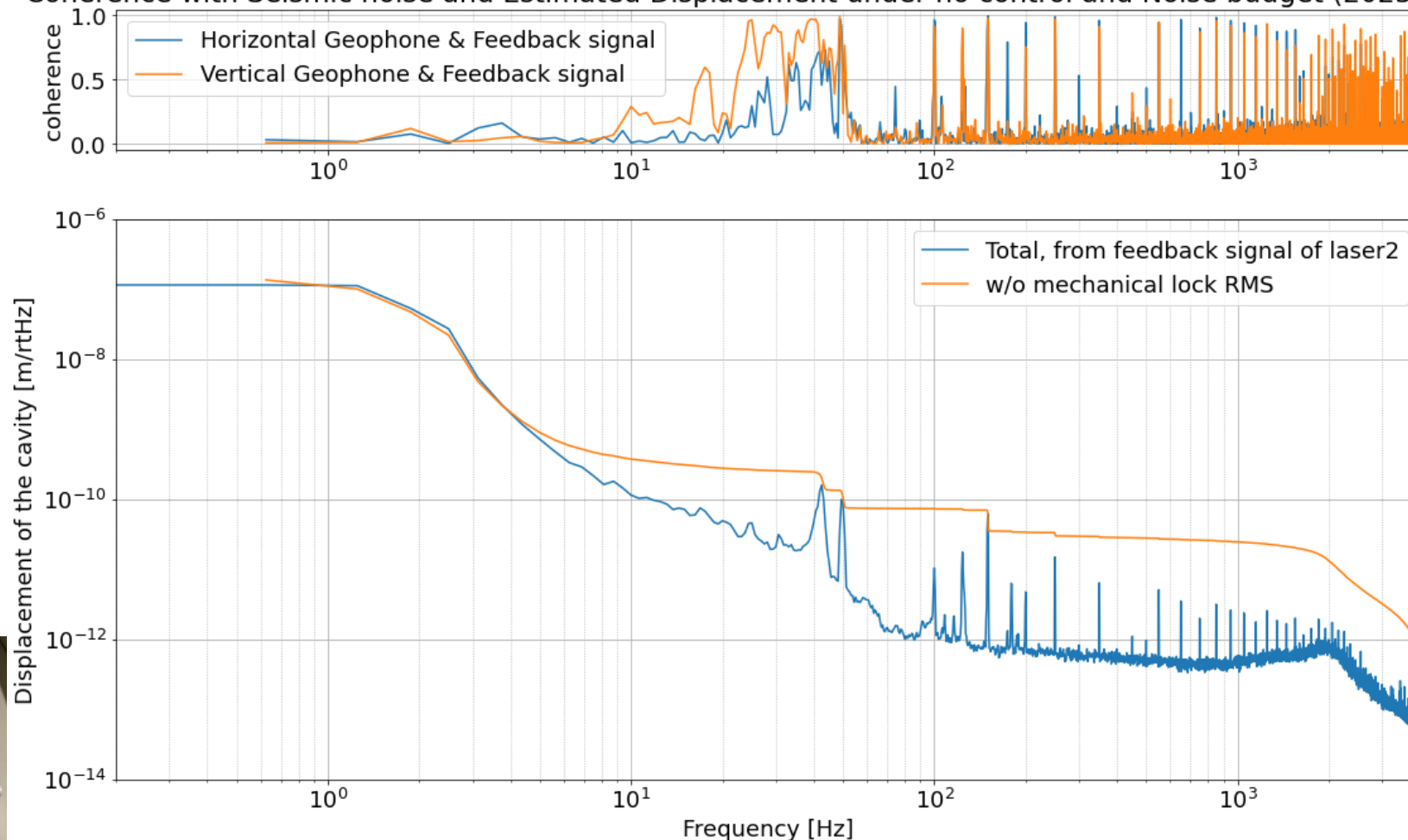
$$\delta x_{\text{RMS}} = \frac{1}{4} \text{FSR}$$

Frequency actuator range
800 MHz



Used laser, Koheras BASIK Y10

Coherence with Seismic noise and Estimated Displacement under no control and Noise budget (2023/04/20)



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Some update plans for My Experimental Setup 実験系のアップデート

So many kinds of noises if we pursue sensitivity

From the environment

Seismic noise => Rubbers under the table

Air turbulence } => A clean room

Sounds } => Walls and roofs

From the lasers

Frequency noise => Frequency stabilization using a reference cavity

Intensity noise => Intensity stabilization using EOAM

From other devices

Mechanical resonance(Bounce mode, Violin mode, etc)

Electrical noise (Diodes, Circuits, Digital system, GND, etc) => Whitening, Dewhitening, optimizing some filters

Beam jitter noise

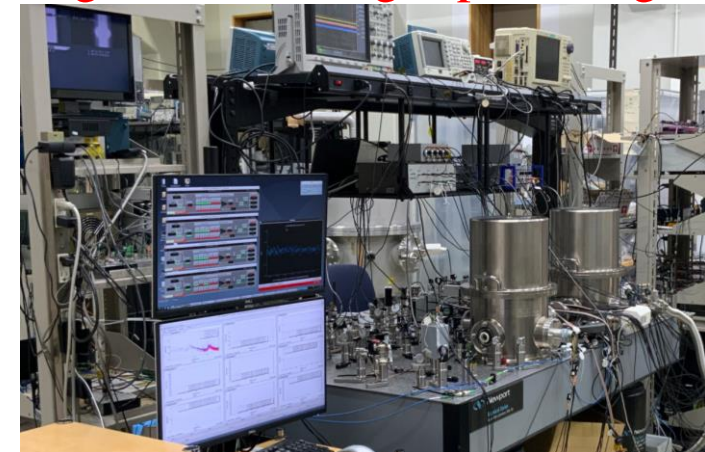
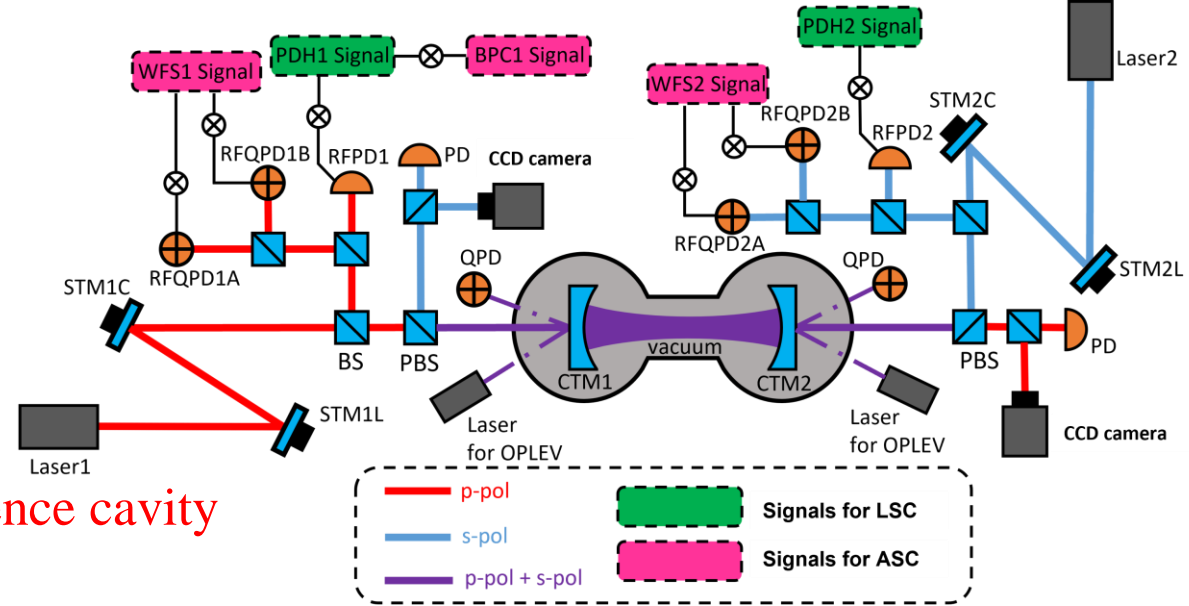
Thermal noise of wires => Making wires thin

Coating thermal noise

Quantum noises

Shot noise

Radiation pressure noise



Isolation from, Air turbulence, sound noise, and seismic noise

To isolate the setup from Air turbulence and sound noise...

Proposal 1

Preparing some walls and roofs surrounding the optical system like DANCE setup and optomechanics setup

Assumed problems

Taking time to design (How to access optical components, What material is better? Acrylic, Aluminum or Styrofoam)

Proposal 2

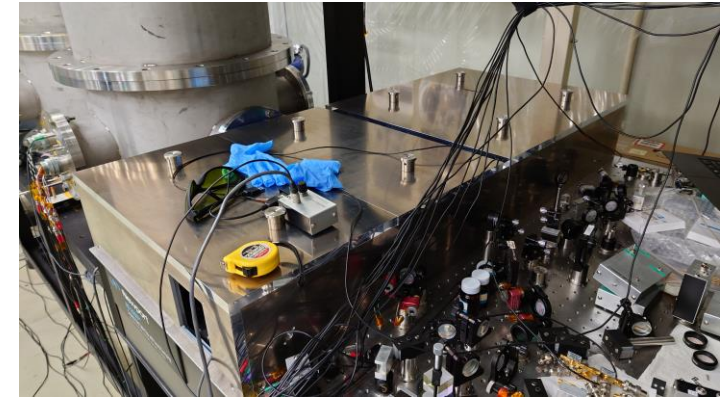
Preparing a clean room like TOBA setup and optomechanics setup

Assumed problems

Space



Ultrasonic bath (Noisy)



Walls and Roofs



Clean room

Isolation from seismic noise, Air turbulence and sound noise

Regarding the vacuum environment

Installing a turbomolecular pump for higher level of vacuum
(1Pa \rightarrow 10^{-4} Pa)

Assumed problems

Vacuum chambers are made of aluminum (How much they leak air, Can they stay rigid?(Distortion, Durability))



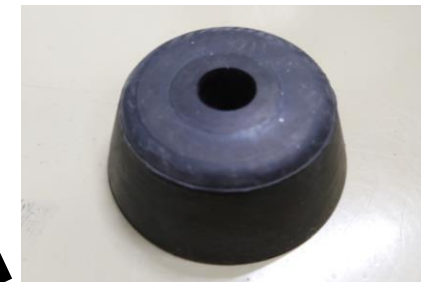
Turbomolecular pump

To isolate the setup from seismic noise...

Putting rubbers under the table



Leg of the table



Rubber

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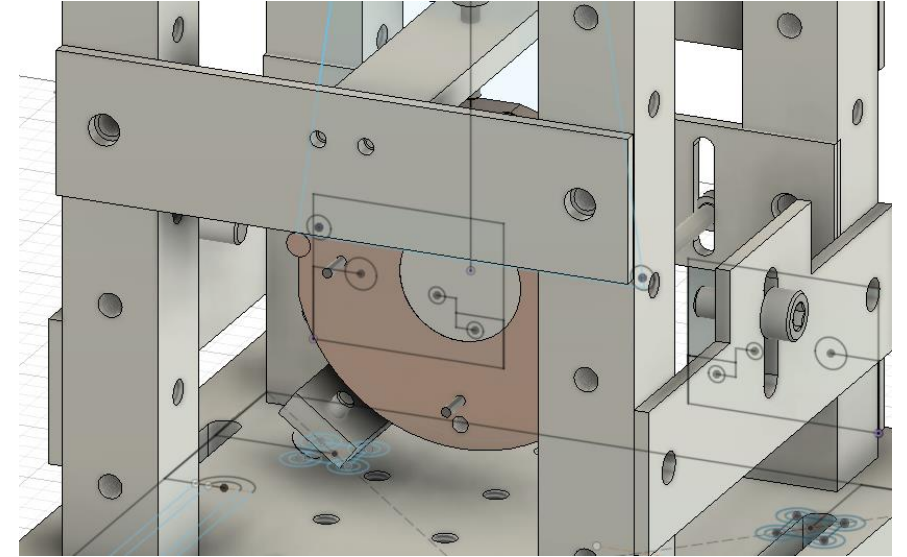
Some update plans for our suspension 振り子のアップデート

Photo sensors

To assess our suspension, adding photo sensors

We can use the suspension 4th-year students used last time

For now, there are safety devices around the test mass, I think it is not necessary unless we use the suspension roughly. So, It is better to replace them with photo sensors

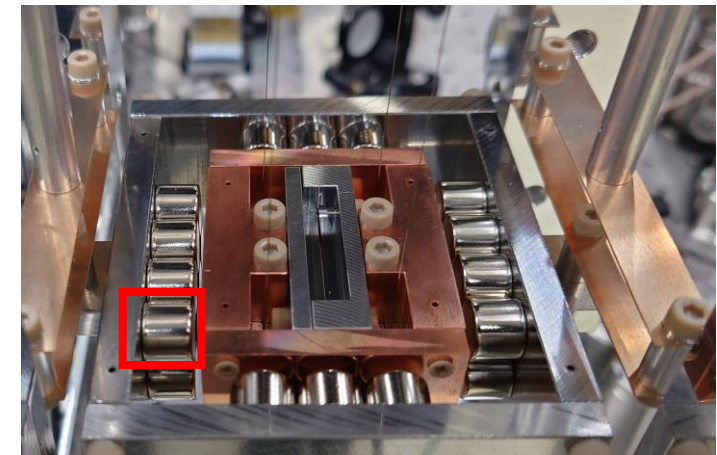


Magnets for Eddy-current damping

Eddy-current damping seems over-damping now.

We use cylinder-shaped $\Phi 10 \text{ mm} \times 8 \text{ mm}$ magnets for Eddy-current damping

Aiming for the optimal damping by making the height of magnets 6 or 7 mm or reduce the number of magnets



Applying the suspension to B-L DM search experiment

Design a new masses

In B-L DM search experiment, we need a small cavity (Length = 5 mm)

We will suspend two pendulums from one roof

In the middle of designing an intermediate mass as the right figures

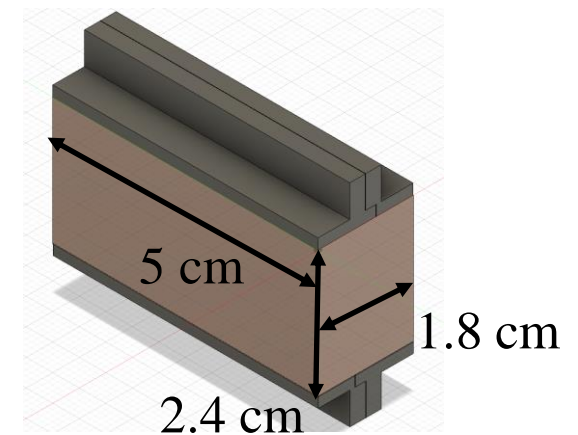
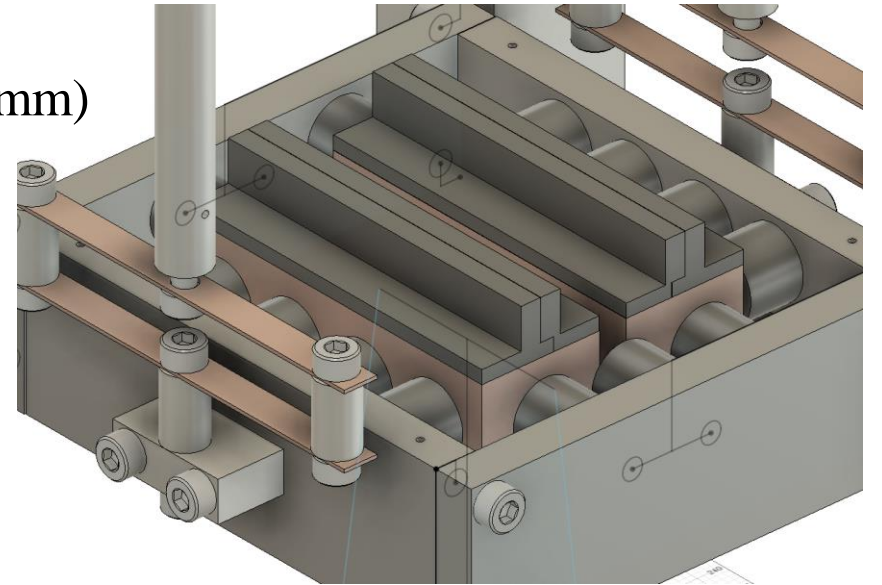
It is still on the level of a conceptual design

Some specific details

High resonant frequency in the pitch direction

Materials : Top and bottom are **stainless steel** while the middle is **Cu**

We still need to consider how to suspend it...(Jigs, Guide)



Update the suspension for Precise Measurement experiment

Re-design blade springs

Now, I found the resonant frequency of the blade spring is 42 Hz

We need to design a new blade spring again

Geometric Anti-Spring will be needed to realize a low resonant frequency

Making pitch resonant frequency higher

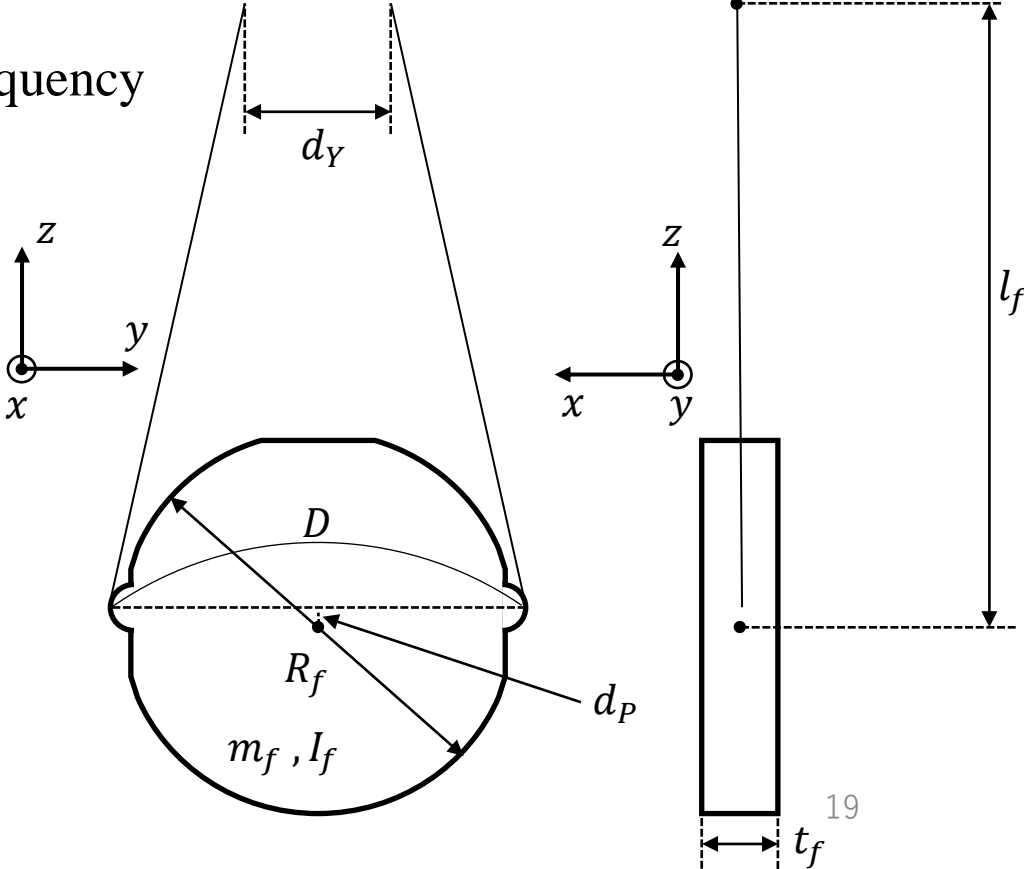
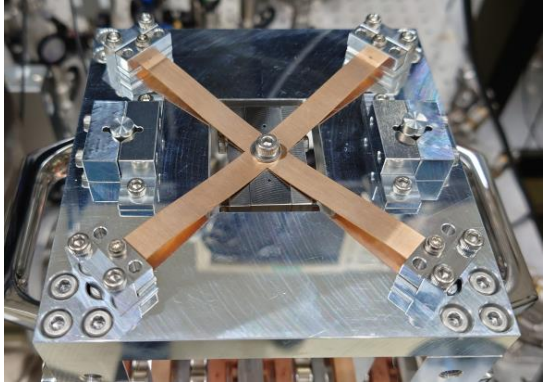
The resonant frequency in the pitch direction is 2 Hz.

It is for the demonstration of ASC of DECIGO

For the precise measurement,

We no longer need the fluctuation in the angle direction

Pitch resonant frequency $f_p = \frac{1}{2\pi} \sqrt{\frac{m_f g (d_p + l_f)}{I_f l_f}}$ [Hz]



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Developing Circuits 回路の開発

Some kinds of circuits we often use should be packaged to save time and share their characteristic

I plan to design Printed Circuit Boards (PCBs) and order to P-ban.com

Now Komori-san and I have been designing PCB of Broadband RFPD

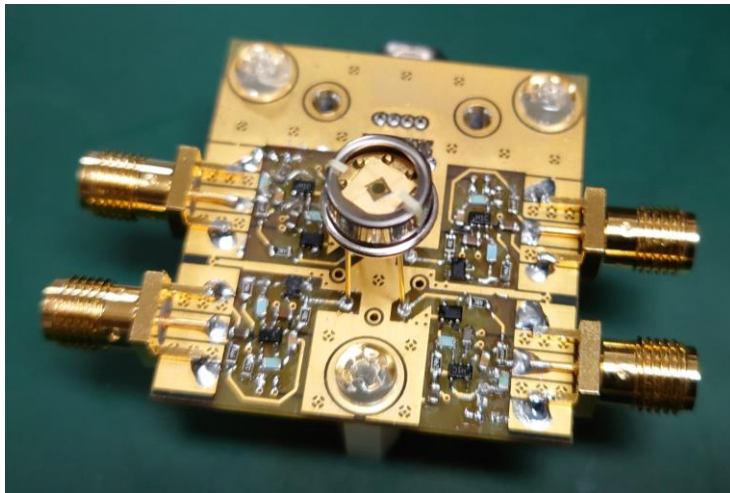


Broadband RFPD

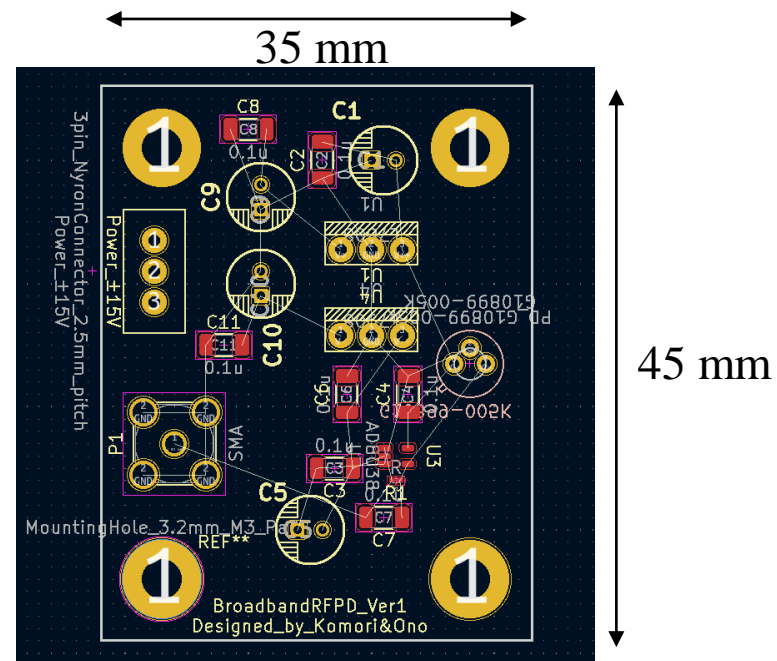
Komori-san developed Broadband RFQPD for LISA at JAXA

We customize the configuration of the RFQPD for the environment of Ando Group

Now Komori-san and I have been designing PCB of Broadband RFPD



Komori-san's RFQPD



New RFPD for us(in designing)

What should be developed ?

- circuits only for adjusting gain
- Offset Circuits
- The Flexible Filter ST560 from Ando Lab Company like SR560
- Analog interfaces for LIGO CDS

We already have ordered...

- Resonant-type RFQPD
- 4ch Demodulator (from TAMA Design)
- Coil Driver Circuit
- D-sub9pin BNC for ADC board (from LIGO and KAGRA)
- D-sub9pin BNC for DAC board (from LIGO and KAGRA)

Please suggest !



ST560 in our group

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Summary

- After realizing a situation seismic noise limits the displacement of the cavity at low frequencies and frequency noise limits it at high frequency, I will start writing a paper
- DECIGO DPFM cavity experiment has a potential to achieve a good sensitivity. So the setup will remain after the demonstration of ASC of DPFM cavity is finished
- Many kinds of noises are expected.
- It is important to take the necessary measures in order from dominant noises we can see