Requirements for B-DECIGO

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- DECIGO is very good detector.
- B-DECIGO is also good detector.
- I considered the feasibility of B-DEICOG and found B-DECIGO requirements seem to be possible if we will do our best.

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Outline

- 1. Overture
- 2. Introduction
- 3. Requirements for B-DECIGO
- 4. Conclusion

Overture

Why do I study on DECIGO?

Overture

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https://en.wikipedia.org/wiki/Eclipse_(horse)

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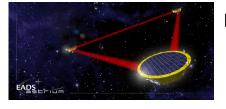
Introduction

- So far, 11 gravitational wave (GW) events have been detected by ground-based detectors.
- For further expansion of the GW physics and astronomy, we have two choices.

Improve ground-based detectors' sensitivity (10 Hz-1 kHz)

Einstein telescope (http://www.et-gw.eu)

Develop space detectors (0.1 mHz-10 Hz)



LISA (Credit: EADS Astrium)



Introduction

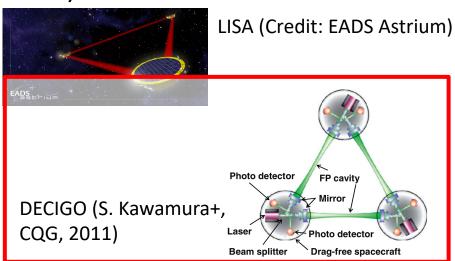
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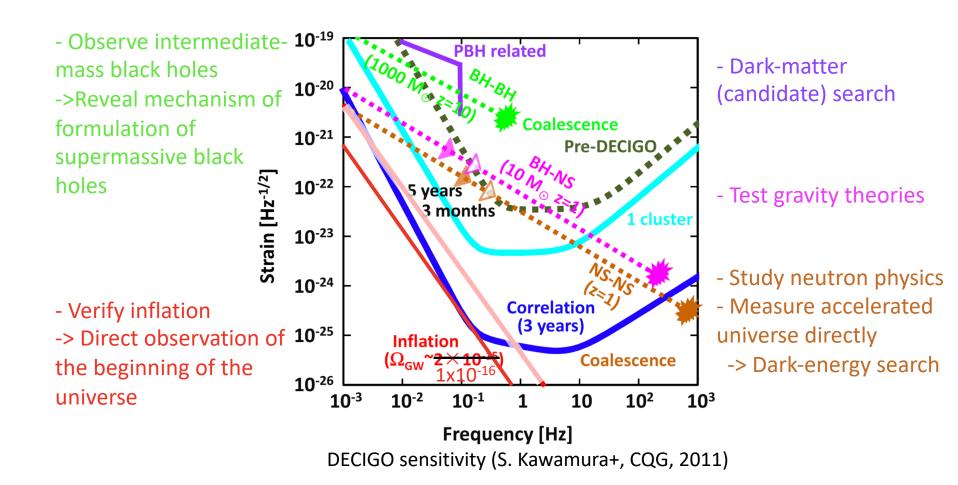
Improve ground-based detectors' sensitivity (10 Hz-1 kHz)

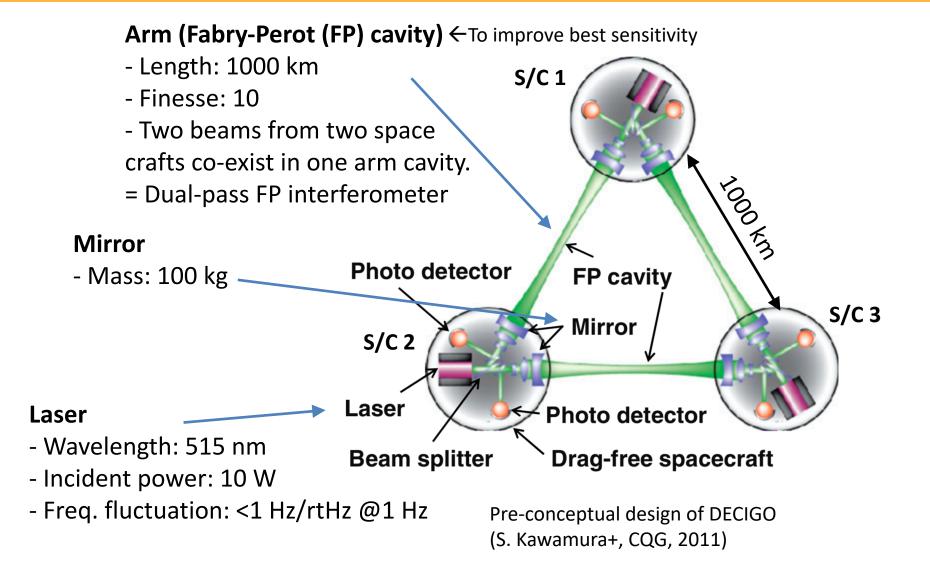
LIGO Livingston (Credit: Caltech/MIT/LIGO Lab)

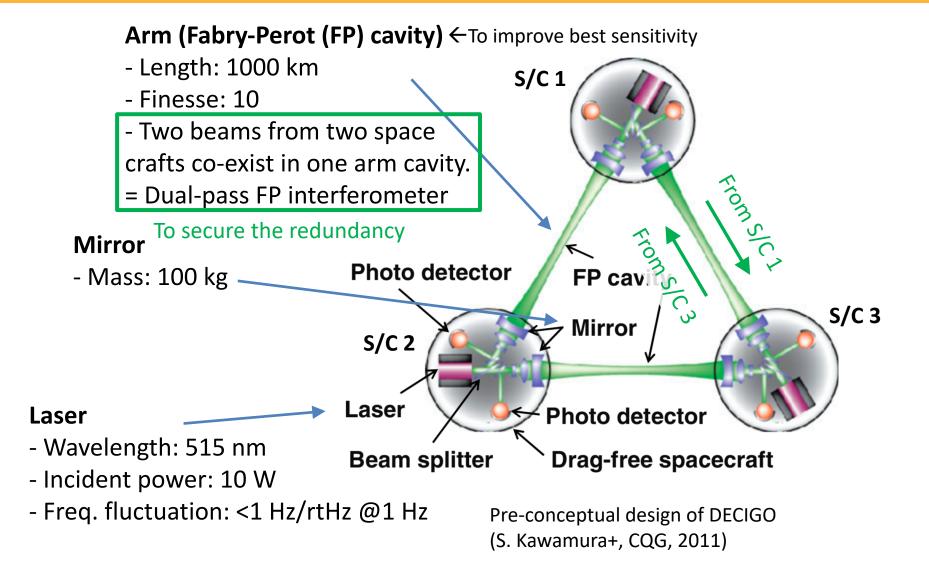
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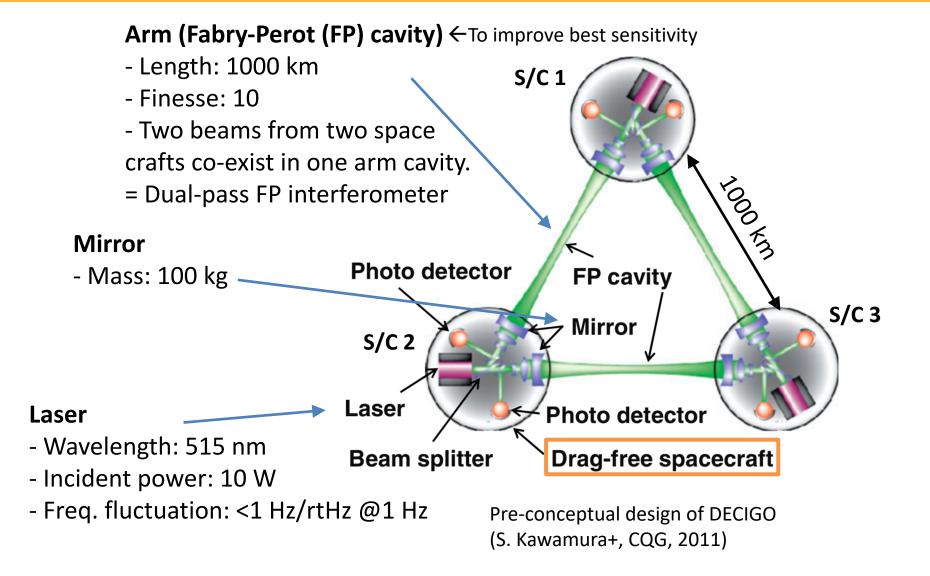
Develop space detectors (0.1 mHz-10 Hz)











DECIGO, LISA, and KAGRA

	LISA	Photo detector FP cavity Mirror Laser Photo detector Beam splitter Prog-free spacecraft DECIGO	KAGRA
Space/Ground	Space	Space	Ground
Arm length	2.5 Gm	1000 km	3 km
Obs. freq.	10 ⁻⁴ -10 ⁻¹ Hz	10 ⁻¹ -10 Hz	10-10 ⁴ Hz
Optical configuration	Optical transponder (In-direct ITF)	Dual-pass FP interferometer (Direct ITF)	RSE interferometer (Direct ITF)
DF control	Necessary	Necessary	Not necessary

DECIGO, LISA, and KAGRA

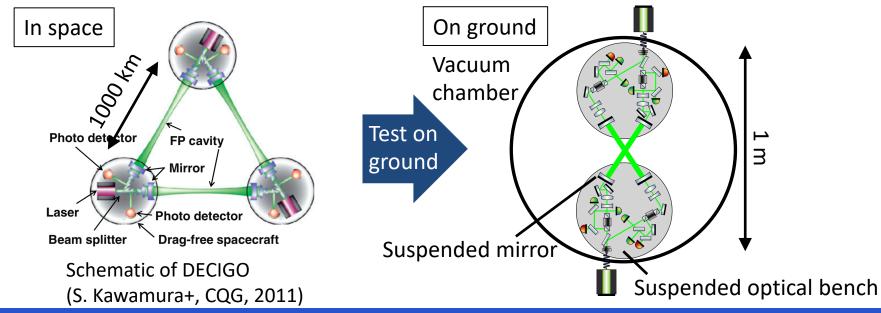
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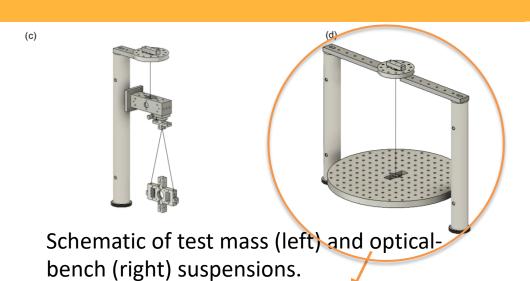
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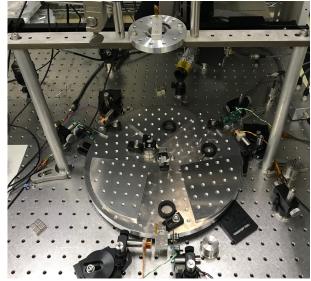
Test bench for interferometer operation

- For demonstration of Fabry-Perot interferometer with drag-free control, a test bench is being constructed.
 - —This test bench has optical (interferometer) and mechanical (drag-free) part.

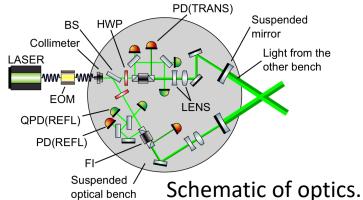


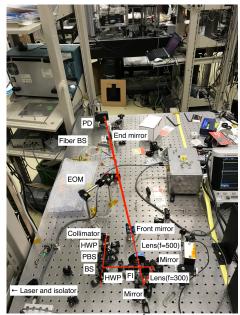
Schematic of the test bench





Picture of suspended optical bench.





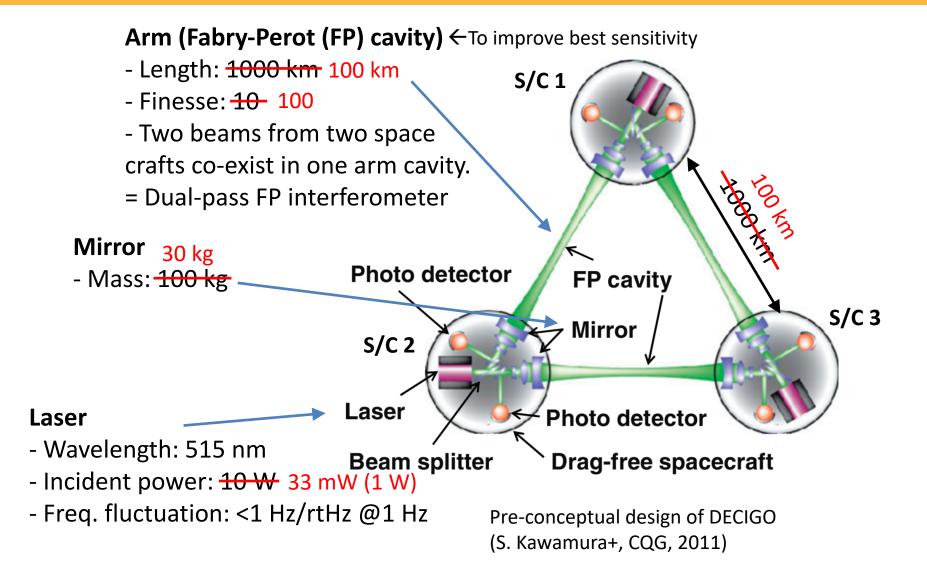
Experiment to demonstrate

Dual-Pass FP interferometer.

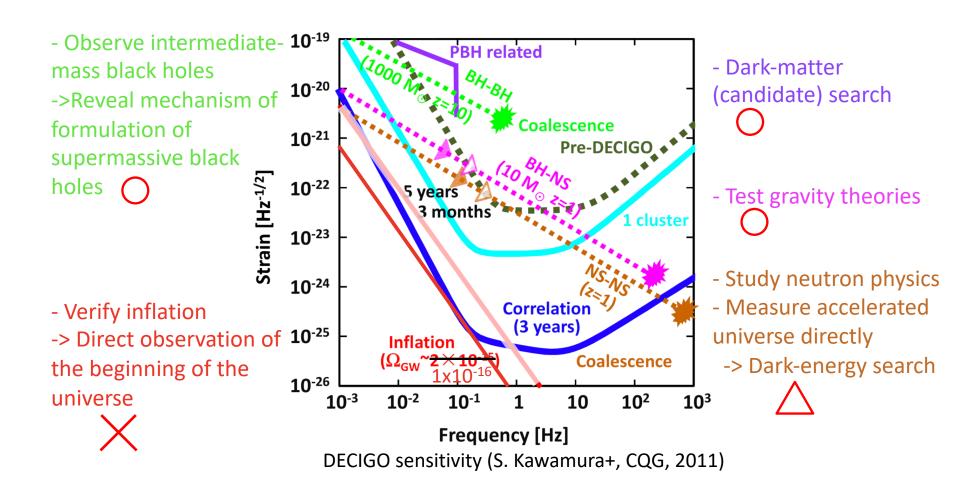
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B-DECIGO

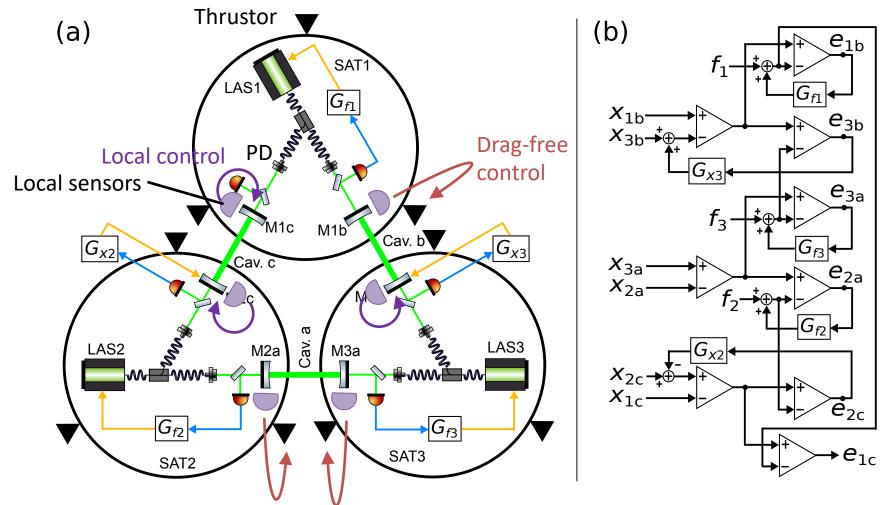


B-DECIGO



Requirement for B-DECIGO

- So far, there is not a base-line design and requirement for B-DECIGO.
 - This is for encouraging for people to consider their original ideas widely.
- Recently, I considered something about B-DECIGO design and requirement.
 - -Sensitivity
 - —Stability
- This time, I want share them and hear your opinions.



Orbit: Geostationary orbit (35,786 km above Earth surface)

Some notes

- In this design, all arms must have the same arm length in the sub-wavelength level (~0.1 um) if the lasers have different wavelength.
- AOM cannot be inserted into the one arm.
- Drag-free controls have large (>1) gain in all frequency.
- Local controls have large gain below observation frequency.
- Along the longitudinal DoF, there is no local control.
- For frequency loop, laser source port is not available. A kind of double pass AOM technique should be used and only the AOM can be actuated.

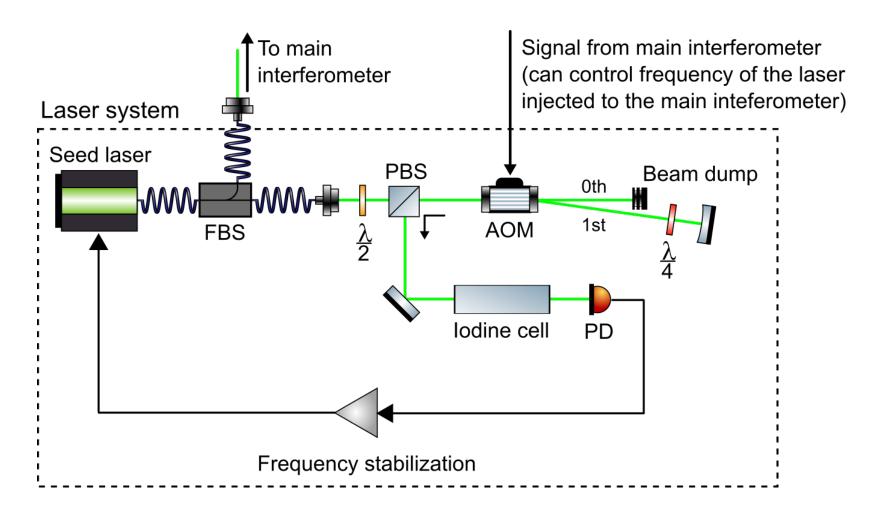


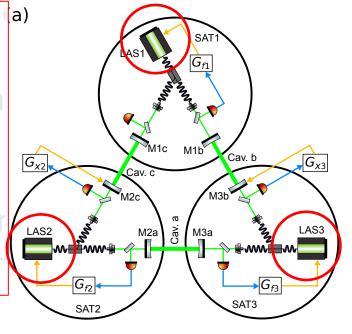
Fig.: Schematic of frequency stabilizing system with double pass AOM.

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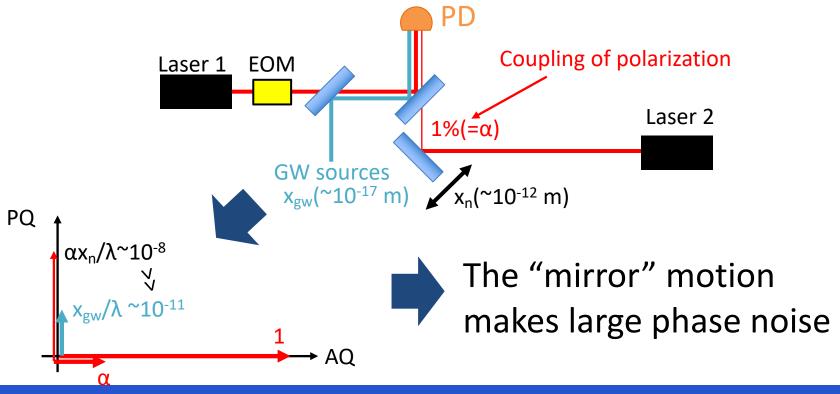
This comes from
the frequency shift of
the laser sources.
Along the longitudinal DoF, there is a
Is this necessary ource por

kind of double pass AOM technique only the AOM can be actuated.

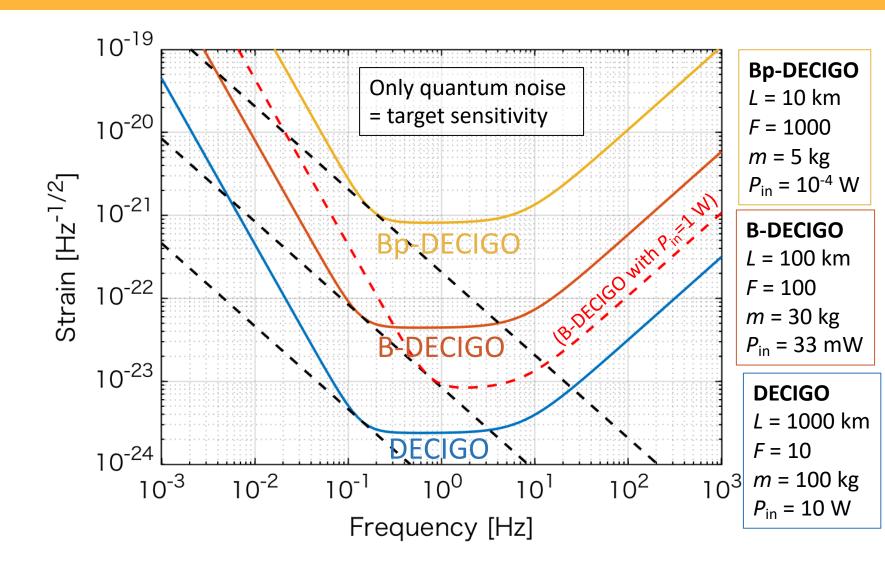


Frequency shift of laser sources

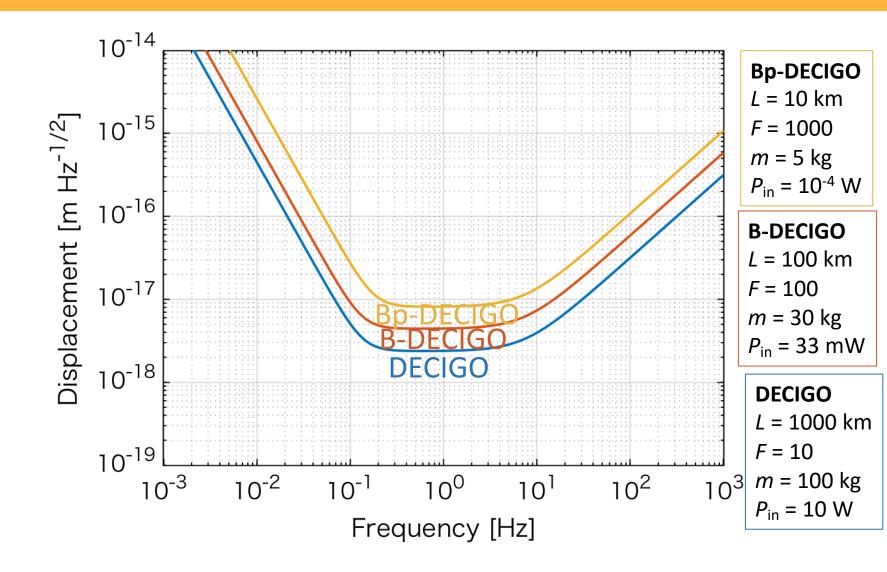
- Answer: This may be necessary.
- If the frequency is same, the situation can be written in the following schematic



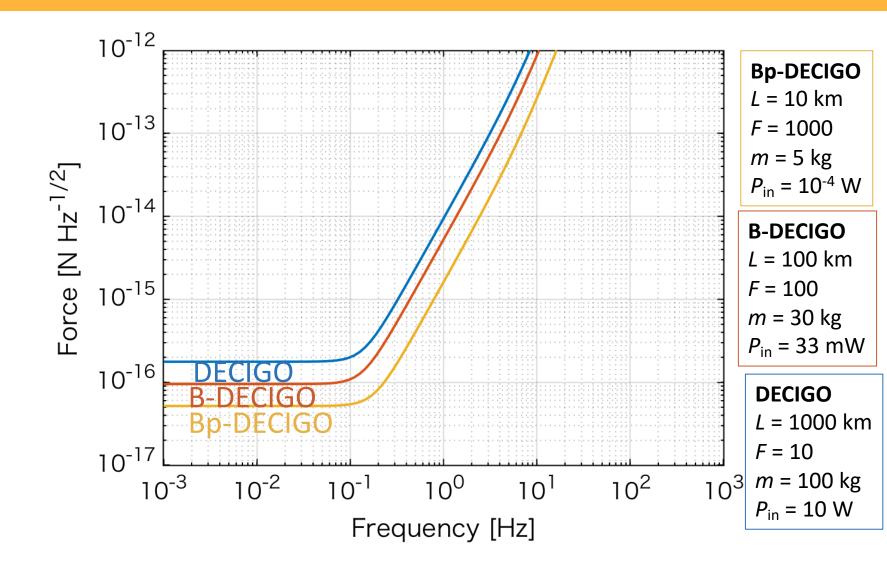
Sensitivity of B-DECIGO



Sensitivity of B-DECIGO



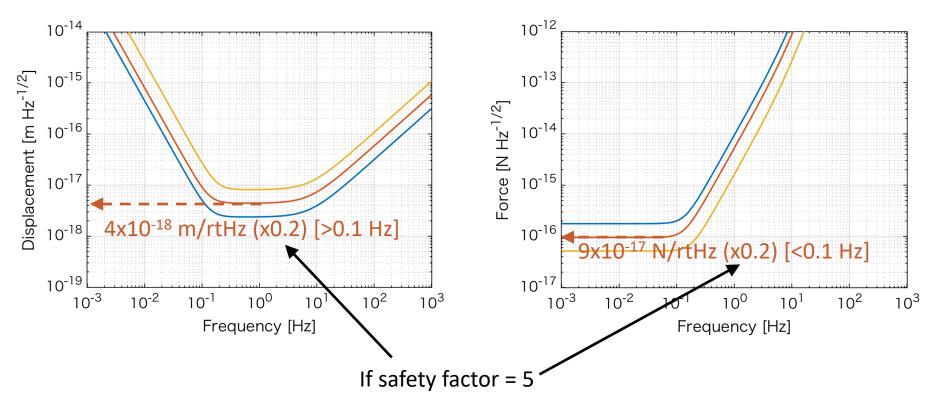
Sensitivity of B-DECIGO



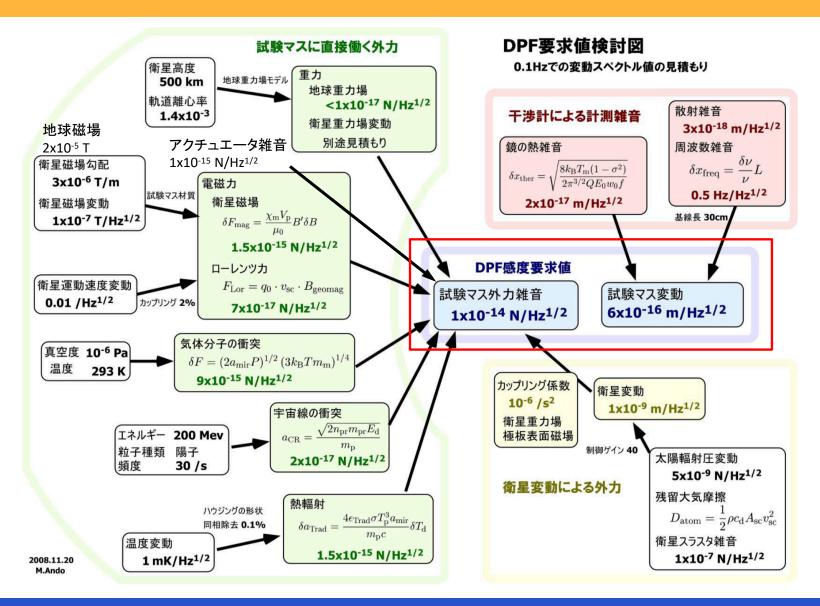
Sensitivity requirement for B-DECIGO

Displacement noise

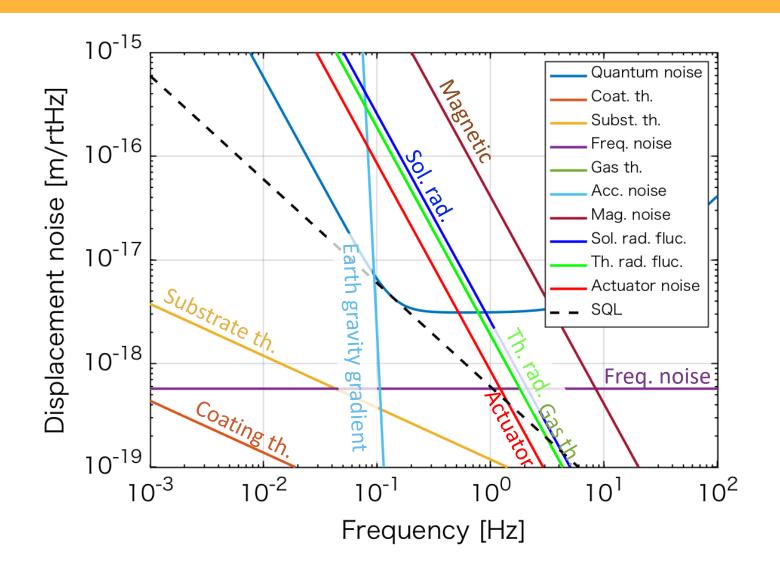
Force noise



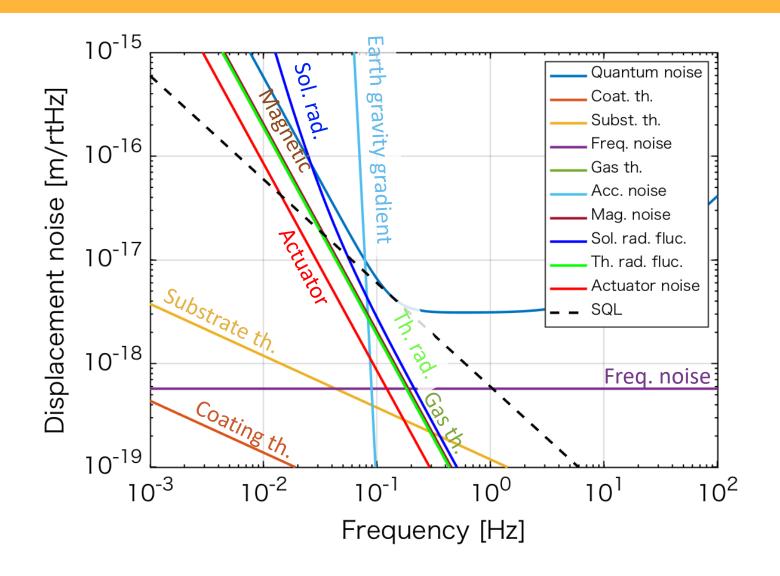
List of expected noises



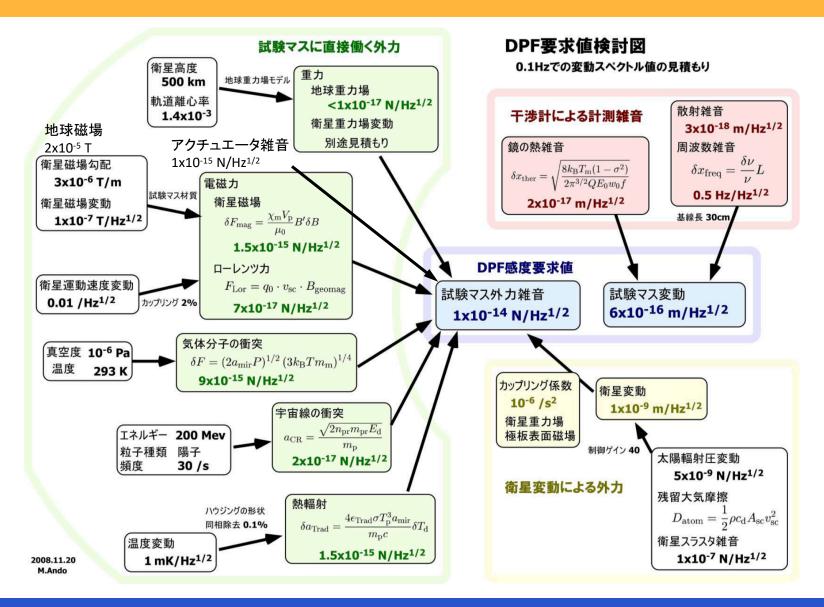
B-DECIGO sensitivity with DPF parameters



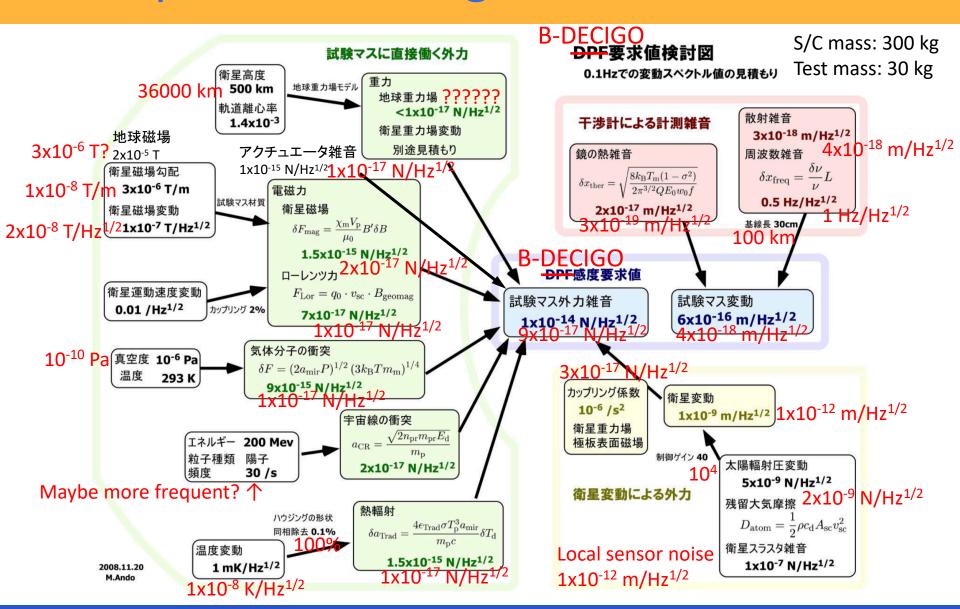
B-DECIGO sensitivity with new parameters



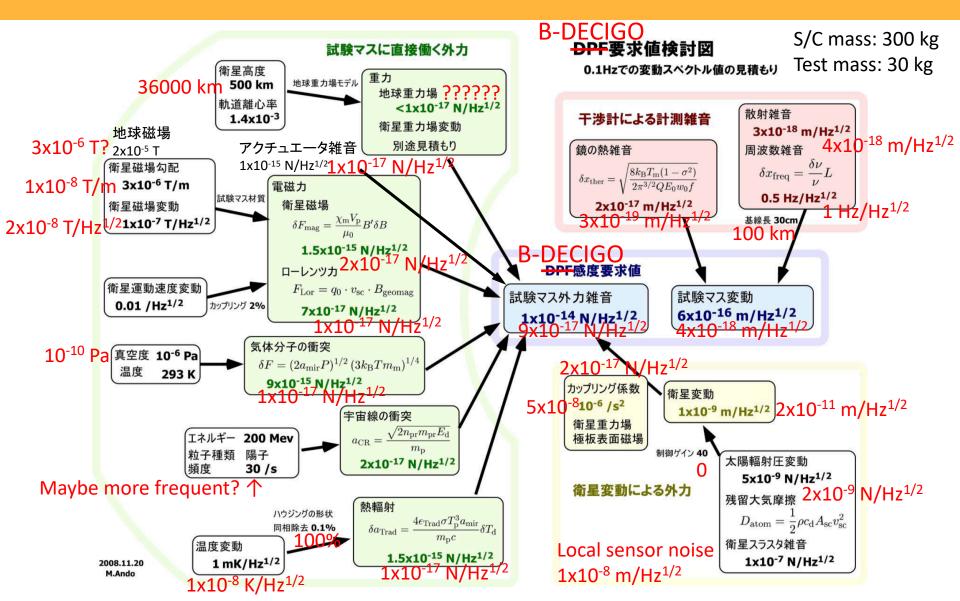
Requirements diagram for DPF



Requirements diagram for B-DECIGO



Requirements diagram for B-DECIGO (2)



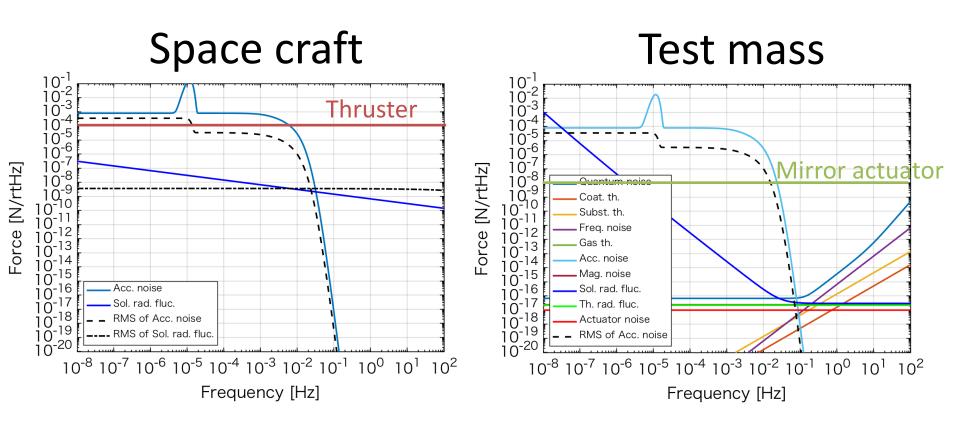
Stability requirement for B-DECIGO

- Usually, it is considered as the fluctuation of the arm length should be within 1% (=+/- 0.5%)
 In B-DECIGO case, +/- 500 m (= 10⁵ [m]x0.005).
- This value comes from range of actuation range of laser sources, 0.1%(?). (←Koheras, AdjustiK Y10)
- However, we should consider the range of AOM, e.g. 1 GHz.
- Range of 1 GHz corresponds to the fluctuation of arm length of 3 ppm (= +/- 0.15 m).
- We should consider how to deal with this problem!!

Stability requirement for B-DECIGO

- Let's assume the actuation range problem will be solved in near future.
- Then we should consider the actuation range of,
 - -Mirror actuators (<10⁻⁸ N)
 - -Thrusters (~<100 uN, 3 year operation?)

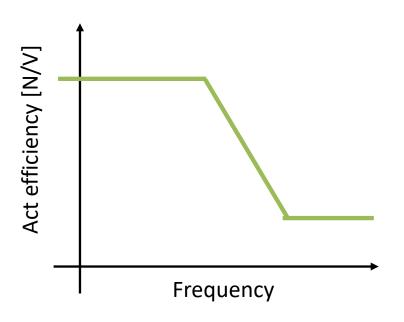
Actuation range

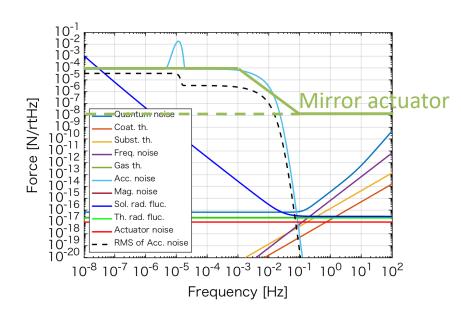


Note: Acceleration noise (Earth's gravity gradient) is not so well estimated that it could be changed especially above 10⁻³ Hz.

Mirror actuator

- Maximum force of 10⁻⁸ N is NOT enough.
- We should consider something.
- For example, frequency dependent actuator range (= frequency dependent impedance).





Thruster

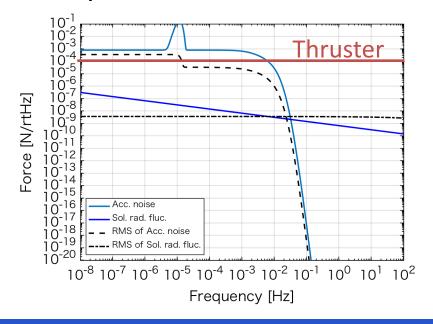
- Maximum force of 100 uN is slightly smaller than requirement. However, If we use several, it meets requirement.
- Operation time is also OK if we use FEEP.

 $-^{4}$ years = 6000 [s] x (9.8/1e-4) x 0.23



FEEP (€ 30,000~)

PARAMETER	VALUE
Dynamic thrust range	10 μN to 0.4 mN
Nominal thrust	350 µN
Specific impulse	2,000 to 6000 s
Propellant mass	230 g
Total impulse	more than 5,000 Ns
Power at nominal thrust	40 W incl. neutralizer
Outside dimensions	100.0 x 100.0 x 82.5 mm
Mass (dry / wet)	670 / 900 g
Total system power	8 – 40 W
Hot standby power	3.5 W
Command interface	RS422/RS485
Temperature envelope	-40 to 105°
(non-operational)	
Temperature envelope	-20 to 40 °C
(operational)	
Supply voltage	12V, 28 V, other
https:/ /www.enpulsio n	voltages upon request .COM



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Conclusion

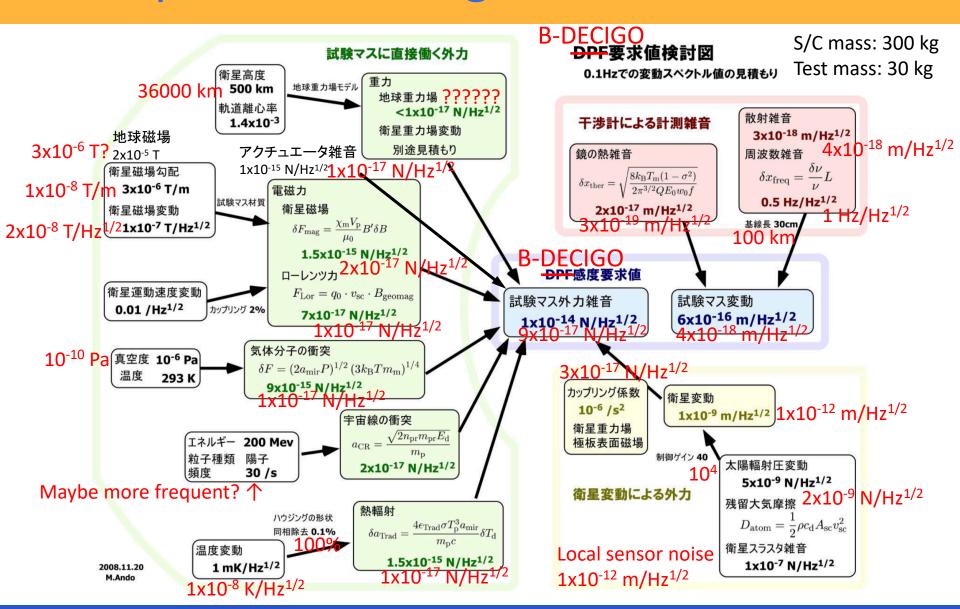
- B-DECIGO seems to be possible if we do our best.
- To do
 - -Estimate Earth's gravity gradient effect
 - Estimate cosmic ray research
 - –(Demonstration)
- Challenges
 - -Vacuum pressure (10⁻¹⁰ Pa)
 - -Magnetic noise (B' and δ B)
 - -Sensitive local sensors (10⁻¹² m/Hz^{1/2})
 - Large range AOM (or other frequency actuator)

Conclusion

- However, I showed just my idea.
- Please consider your B-DECIGO freely!



Requirements diagram for B-DECIGO



Cheat sheet

	DPF	B-DECIGO	Misc
Magnetic noise			
Magnetic fluctuation, δB [T/rtHz]	1e-7	2e-8	Christian Trenkel et al 2017 J. Phys.: Conf. Ser. 840 012006
Magnetic gradient, B' [T/m]	3e-6	1e-8	
Residual gas thermal			
Pressure [Pa]	1e-6	1e-9	
Solar radiation pressure noise			
Solar radiation fluctuation [N/rtHz]	4e-10	4e-10	at 0.1 Hz
Local sensor sensitivity [m/rtHz]	1e-10	1e-13	
Thruster noise, Fth [N/rtHz]	1e-7	1e-7	
Coupling, α [1/s^2]	1e-6	1e-6	
Actuator noise			
Actuator noise, Fact [N/rtHz]	1e-15	1e-17	in KAGRA 1e-14 (Yuta Michimura et al 2017 Class. Quantum Grav. 34 225001)
Thermal radiation fluctuation			
Temperature fluctuation, δT [K/rtHz]	1e-3	1e-6	
Common mode rejection	1e-3	1	
Shield	1	1e-2	
Frequency noise			
Frequency noise [Hz/rtHz]	0.5	1	
Control gain	?	3e8	
Thermal noise			
Substrate loss angle		1e-7	
Costing loss angle (SiO ₂ , Ta ₂ O ₅)		0.5e-4, 2e-4	In Ta ₂ O ₅ , Ti is doped.
Beam radius [cm]		14	