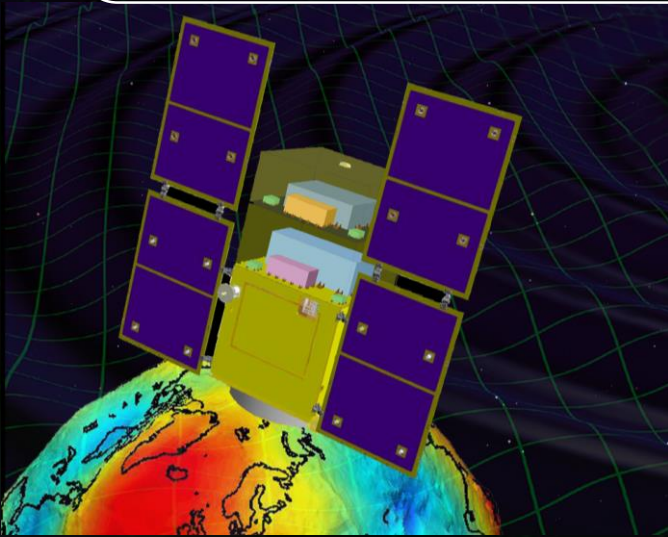


# DECIGO: Space Gravitational-wave Antenna

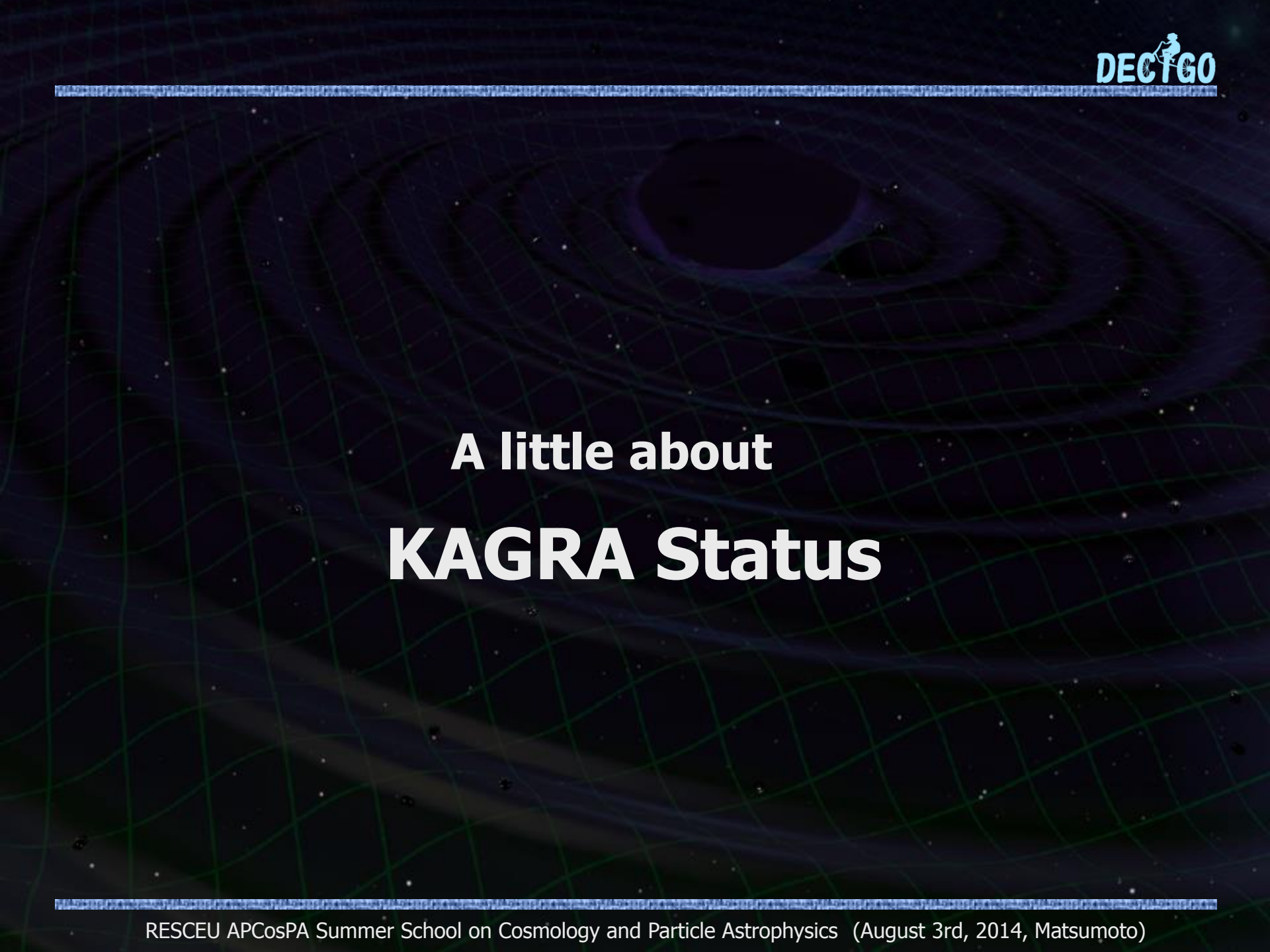


**Masaki Ando**

(Dept. of Physics, Univ. of Tokyo /  
National Astronomical Observatory Japan)

- **KAGRA**
- **DECIGO**
- **DECIGO Pathfinder**





**A little about  
KAGRA Status**



## KAGRA (かぐら)

2<sup>nd</sup> Generation Large-scale  
Gravitational-Wave Telescope  
at Kamioka underground site

(Funded 2010-, Obs. : 2017-)



Open a new field of  
'Gravitational-Wave Astronomy'



219 Collaborators from more than 60 institutes

※ on April 2013



•Host:

ICRR/U-Tokyo

•Co-host :

NAOJ and KEK

•Collaborations

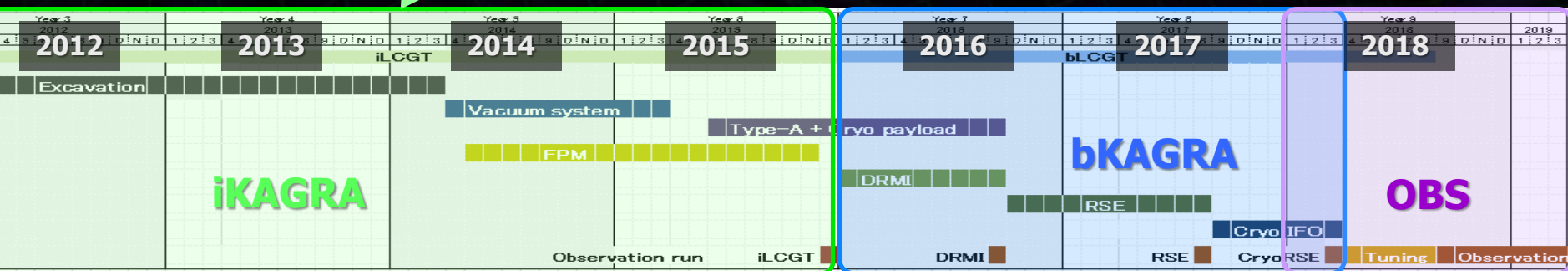
U-Tokyo, ERI/U-Tokyo,  
Osaka-CU, TITEC, Osaka-U,  
Kyoto-U, NICT, AIST, UEC,  
Hosei-U, Ochanomizu-U,  
Niigata-U, Kyusyu-U, Nihon-  
U, Toyama-U, Caltech,  
MPQ, UWA, LSU, ...

# KAGRA Schedule

## • **iKAGRA** (2010.10 – 2015.12)

3-km FPM interferometer

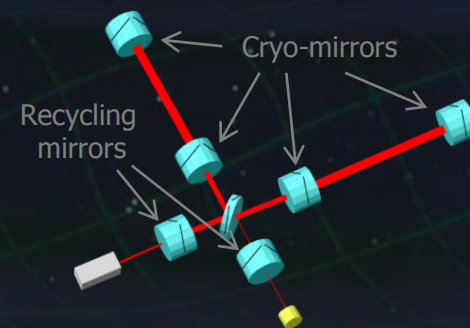
- Baseline 3km room temp.
- Operation of total system with simplified IFO and VIS.



## • **bKAGRA** (2016.1 – 2018.3)

Operation with full config.

- Final IFO+VIS configuration
- Cryogenic operation.





# Current Status of KAGRA



## *Tunnel excavation completed!*

At the end of March 2014, the excavation of the KAGRA tunnel has been completed.



July 4, 2014: KAGRA tunnel visit.

From presentation file by  
T.Kajita, KAGRA face-to-face Meeting (July 31th, Toyama)

# Current Status of KAGRA

## *i*KAGRA schedule (2014-2015)

	2013		2014				2015				
	III	IV	I	II	III	IV	I	II	III	IV	
electricity				wiring							
ventilation				duct							
drainage				tubing							
crane				girder							
hanging anchor				drilling							
dust prevention coating	tunnel excavation				laser room	c-room					
clean booth					laser room	c-room, e-room					
network and PHS											
arm tube											
laying a chalk line											
carrying and anchoring											
flange fastening/leak test											
chamber											
marking											
anchoring					cryo	other chambers					
mirror suspension						Type-C, Type-Bp, BS					
Install / tune in chambers											
input/output optics						laser setup	PMC to MC				
optical baffle (arm)						during flange fastening/arm					
target monitor (arm)						during flange fastening/arm					
vac pumping						bidding	during flange fastening/arm				
Geophysics interferometer							inst.	test/operation			
Environment monitor								test/operation			

Dec 2015  
operation

(Slide from Y. Saito (PM), June KAGRA International video meeting)

4

From presentation file by  
T.Kajita, KAGRA face-to-face Meeting (July 31th, Toyama)



# KAGRA and DECIGO

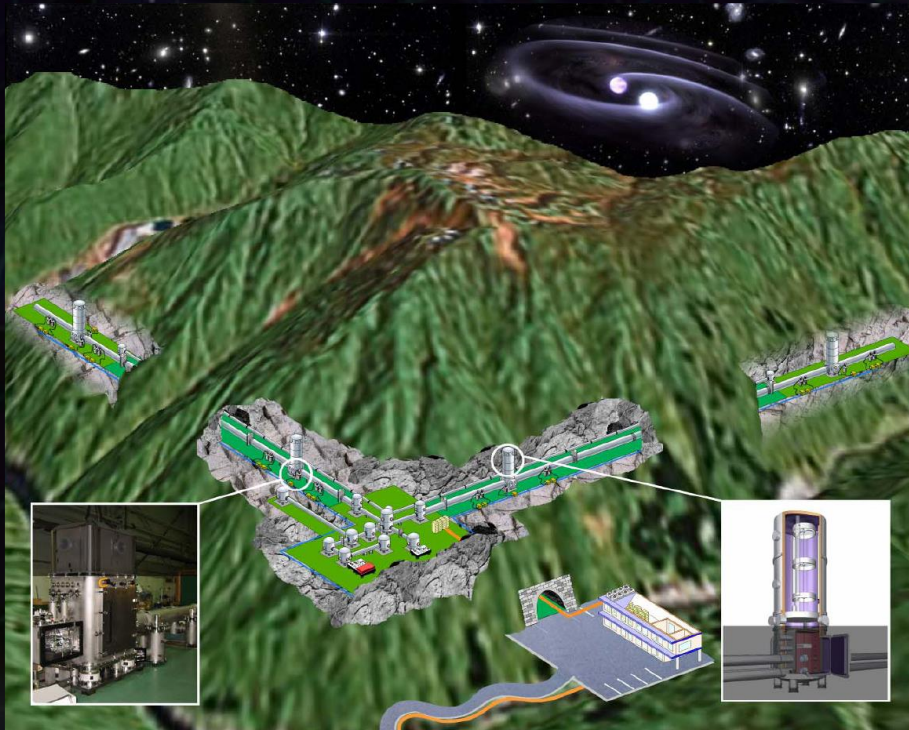


## KAGRA (~2017)

Ground-based Detector

→ High-freq. GW events

Target : Detection, Astrophysics

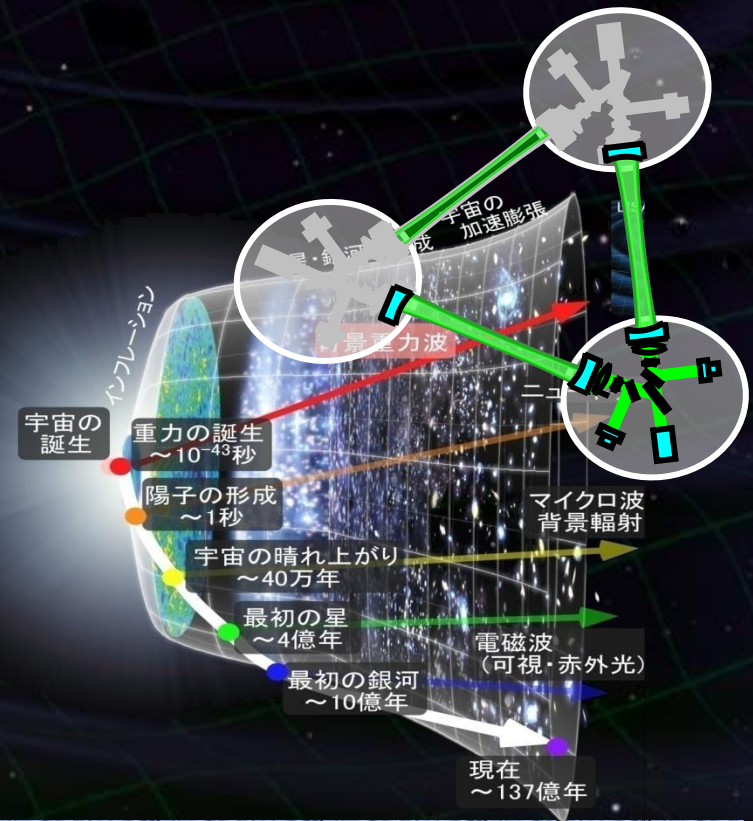


## DECIGO (~2027)

Space observatory

→ Low-freq. GW

Target : Cosmology



# DECIGO



# Space GW Antenna DECIGO



**DECIGO** (DECI-hertz interferometer Gravitational wave Observatory)

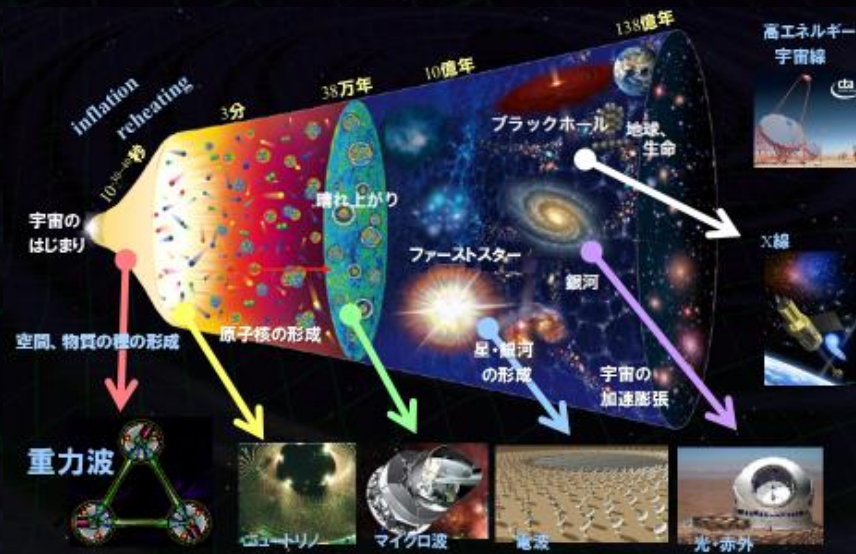
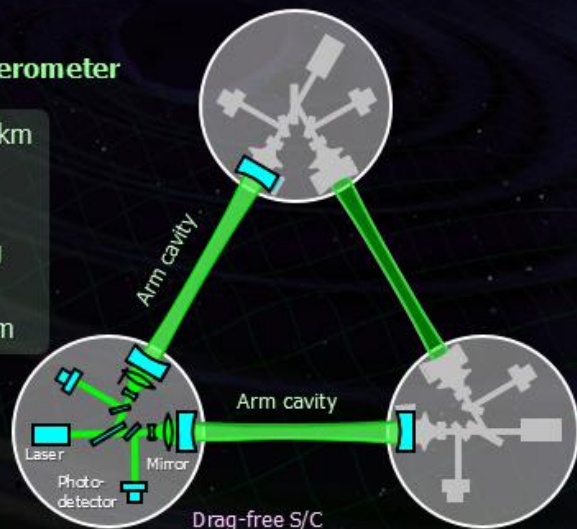
**Purpose: To Obtain Cosmological Knowledge.**

Direct observation of the origin of space-time and matter in Big-bang Universe.

**Interferometer Unit:**  
**Differential FP interferometer**

Arm length: 1000 km  
Finesse: 10  
Mirror diameter: 1 m  
Mirror mass: 100 kg  
Laser power: 10 W  
Laser wavelength: 532 nm

S/C: drag free  
3 interferometers



背景画: 福井康雄監修「宇宙史を物理学で読み解く  
-素粒子から物質・生命まで」(名古屋大学出版会)より



# DECIGO Members



Koh-suke Aoyanagi, Kazuhiro Agatsuma, Tomotada Akutsu, Hideki Asada, Yoichi Aso, Koji Arai, Akito Araya, Masaki Ando, Kunihito Ioka, Takeshi Ikegami, Takehiko Ishikawa, Hideharu Ishizaki, Hideki Ishihara, Kiwamu Izumi, Kiyotomo Ichiki, Hiroyuki Ito, Yousuke Itoh, Kaiki T. Inoue, Akitoshi Ueda, Ken-ichi Ueda, Takafumi Ushiba, Masayoshi Utashima, Satoshi Eguchi, Yumiko Ejiri, Motohiro Enoki, Toshikazu Ebisuzaki, Yoshiharu Eriguchi, Naoko Ohishi, Masashi Ohkawa, Masatake Ohashi, Kenichi Oohara, Yoshiyuki Obuchi, Kenshi Okada, Norio Okada, Koki Okutomi, Nobuki Kawashima, Fumiko Kawazoe, Isao Kawano, Seiji Kawamura, Nobuyuki Kanda, Kenta Kiuchi, Naoko Kishimoto, Hitoshi Kuninaka, Hiroo Kunimori, Kazuaki Kuroda, Sachiko Kuroyanagi, Hiroyuki Koizumi, Feng-Lei Hong, Kazunori Kohri, WataruKokuyama, Keiko Kokeyama, Yoshihide Kozai, Yasufumi Kojima, Kei Kotake, Shiho Kobayashi, Rina Gondo, Motoyuki Saijo, Ryo Saito, Shin-ichiro Sakai, Masaaki Sakagami, Shihori Sakata, Norichika Sago, Misao Sasaki, Shuichi Sato, Takashi Sato, Masaru Shibata, Kazunori Shibata, Ayaka Shoda, Hisaaki Shinkai, Aru Suemasa, Naoshi Sugiyama, Rieko Suzuki, Yudai Suwa, Naoki Seto, Kentaro Somiya, Hajime Sotani, Takeshi Takashima, Tadashi Takano, Kakeru Takahashi, Keitaro Takahashi, Tadayuki Takahashi, Hirotaka Takahashi, Fuminobu Takahashi, Ryuichi Takahashi, Ryutaro Takahashi, Takamori Akiteru, Hideyuki Tagoshi, Hiroyuki Tashiro, Takahiro Tanaka, Nobuyuki Tanaka, Keisuke Taniguchi, Atsushi Taruya, Takeshi Chiba, Dan Chen, Shinji Tsujikawa, Yoshiki Tsunesada, Kimio Tsubono, Morio Toyoshima, Yasuo Torii, Kenichi Nakao, Kazuhiro Nakazawa, Shinichi Nakasuka, Hiroyuki Nakano, Shigeo Nagano, Kouji Nakamura, Takashi Nakamura, Yoshinori Nakayama, Atsushi Nishizawa, Erina Nishida, Kazutaka Nishiyama, Yoshito Niwa, Kenji Numata, Taiga Noumi, Tatsuaki Hashimoto, Kazuhiro Hayama, Tomohiro Harada, Wataru Hikida, Yoshiaki Himemoto, Hisashi Hirabayashi, Takashi Hiramatsu, Mitsuhiro Fukushima, Ryuichi Fujita, Masa-Katsu Fujimoto, Toshifumi Futamase, Ikkoh Funaki, Mizuhiko Hosokawa, Hideyuki Horisawa, Kei-ichi Maeda, Hideo Matsuhara, Nobuyuki Matsumoto, Yuta Michimura, Osamu Miyakawa, Umpei Miyamoto, Shinji Miyoki, Shinji Mukohyama, Mitsuru Musha, Toshiyuki Morisawa, Mutsuko Y. Morimoto, Shigenori Moriwaki, Kent Yagi, Hiroshi Yamakawa, Toshitaka Yamazaki, Kazuhiro Yamamoto, Jun'ichi Yokoyama, Shijun Yoshida, Taizoh Yoshino, Chul-Moon Yoo, Yaka Wakabayashi

(On February 28<sup>th</sup>, 2014)



# GWs from Early Universe

BICEP2, (WMAP, Planck,...)

Observation of  
**CMB B-mode Polarization**  
with radio telescope.

DECIGO, (KAGRA, aLIGO,...)

Observation of  
**Gravitational-wave background**  
with GW telescope.

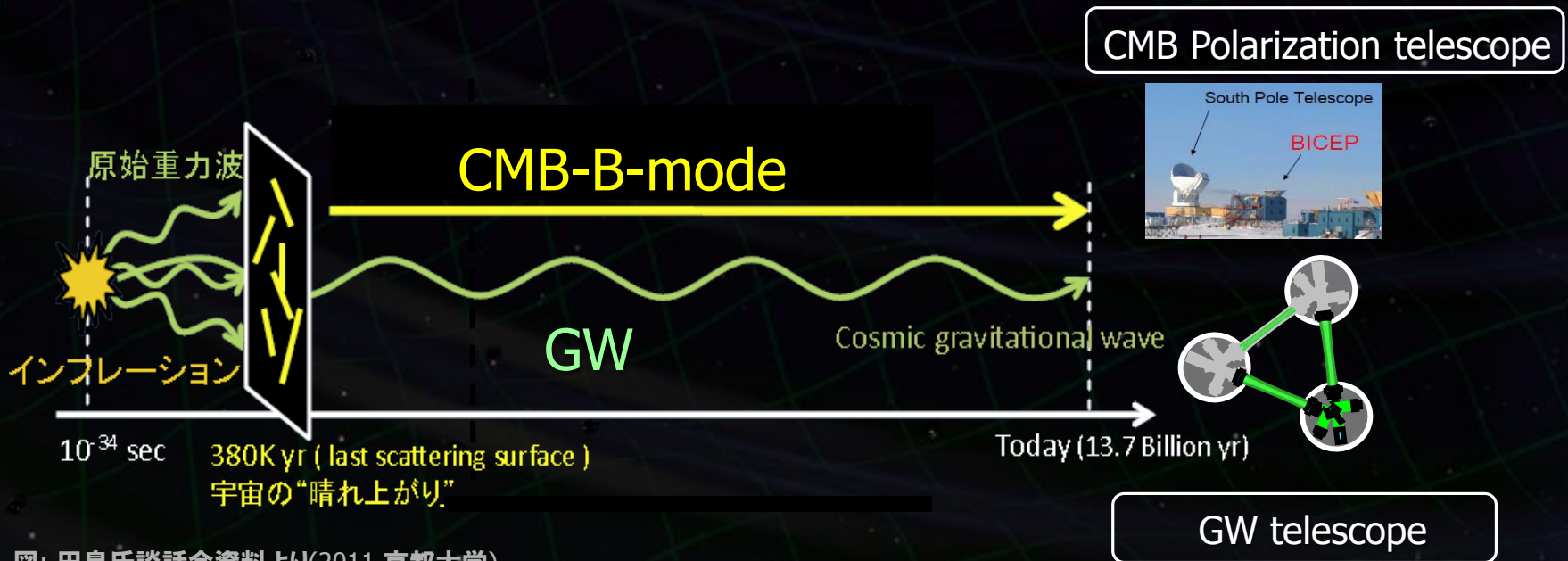
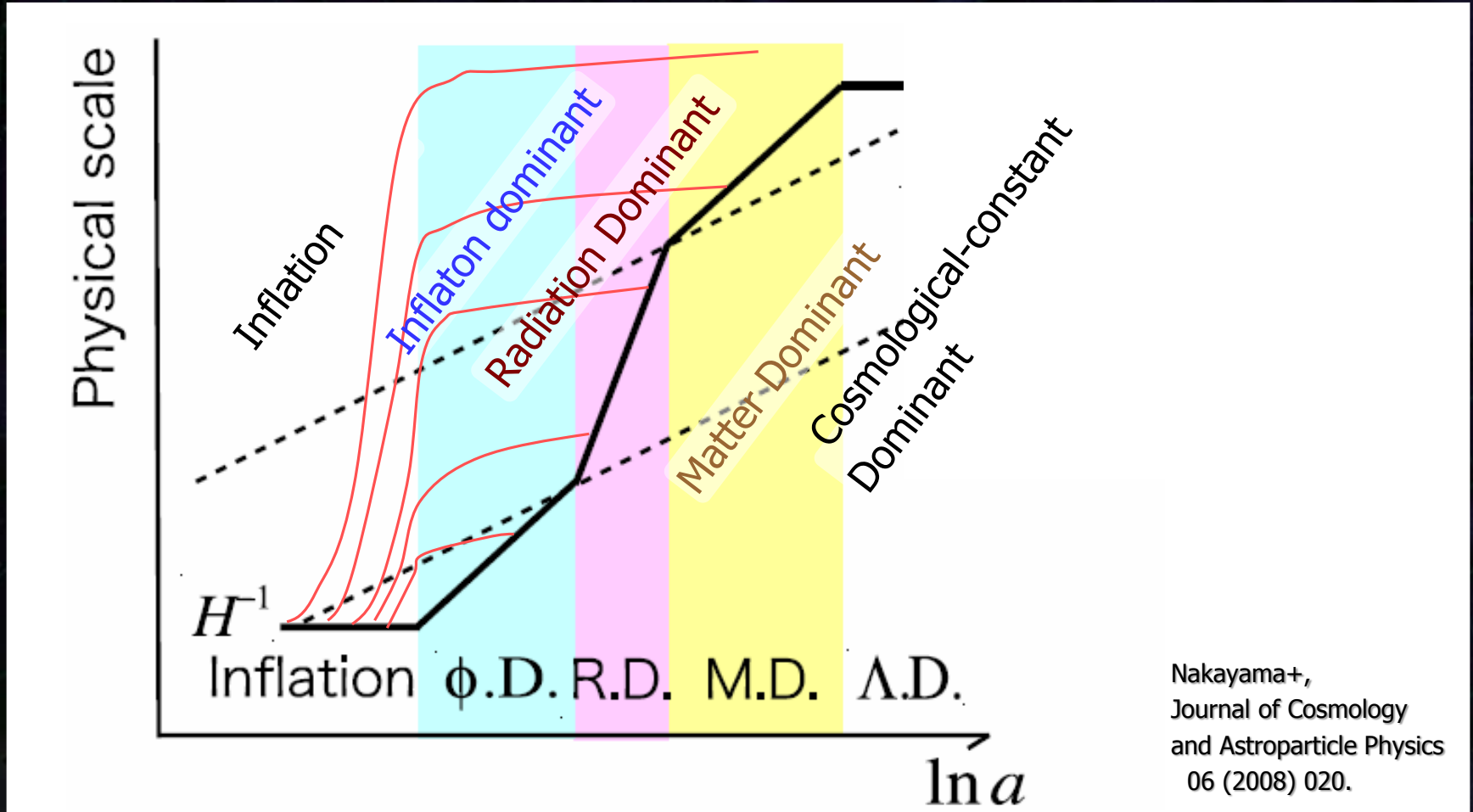


図: 田島氏談話会資料より(2011 京都大学)

# GW from Inflation

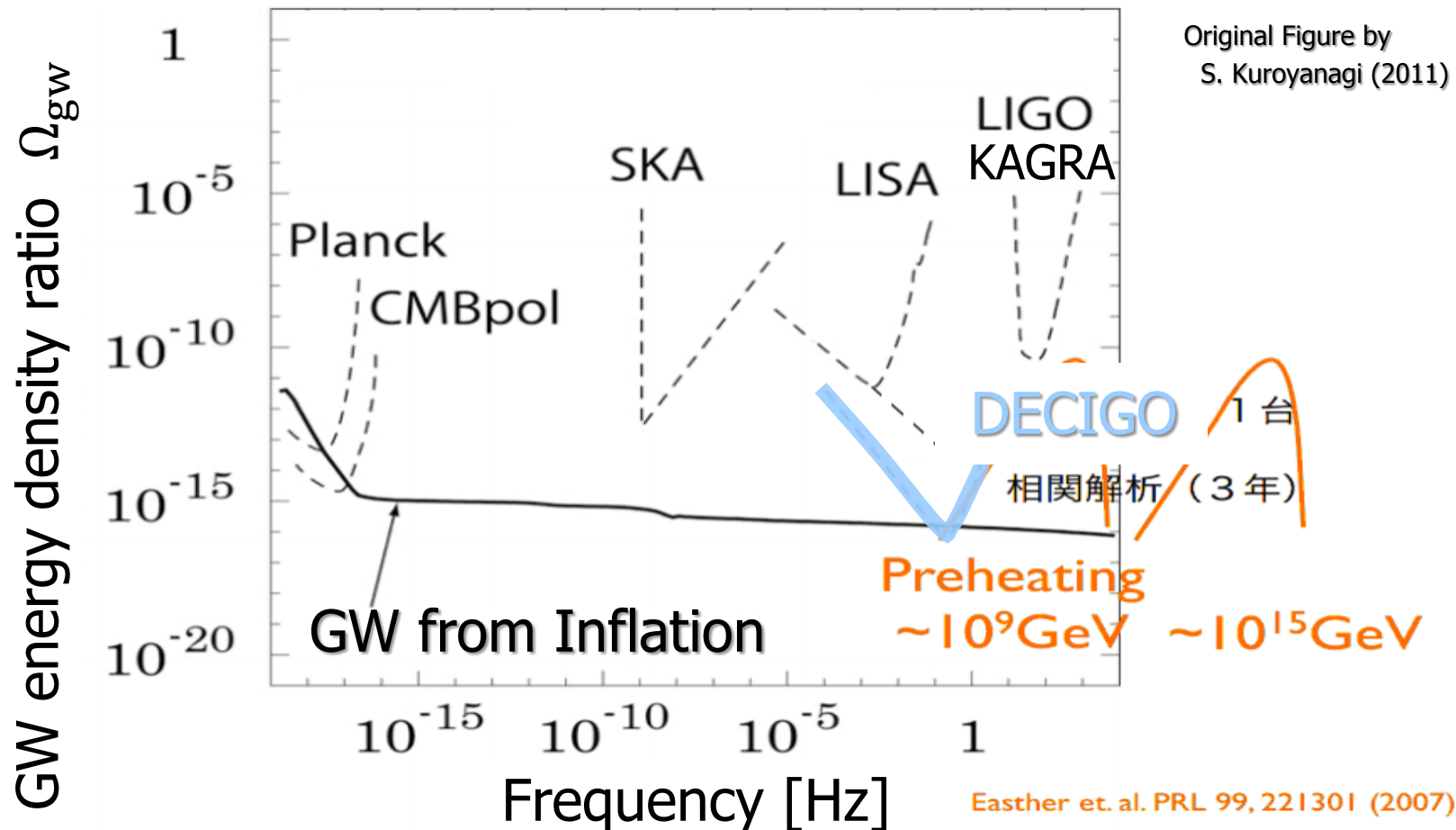
GWs in early phase of inflation  $\rightarrow$  Expanded more in inflation and re-enter to the horizon later  $\rightarrow$  Lower freq. GWs.





# Primordial GW

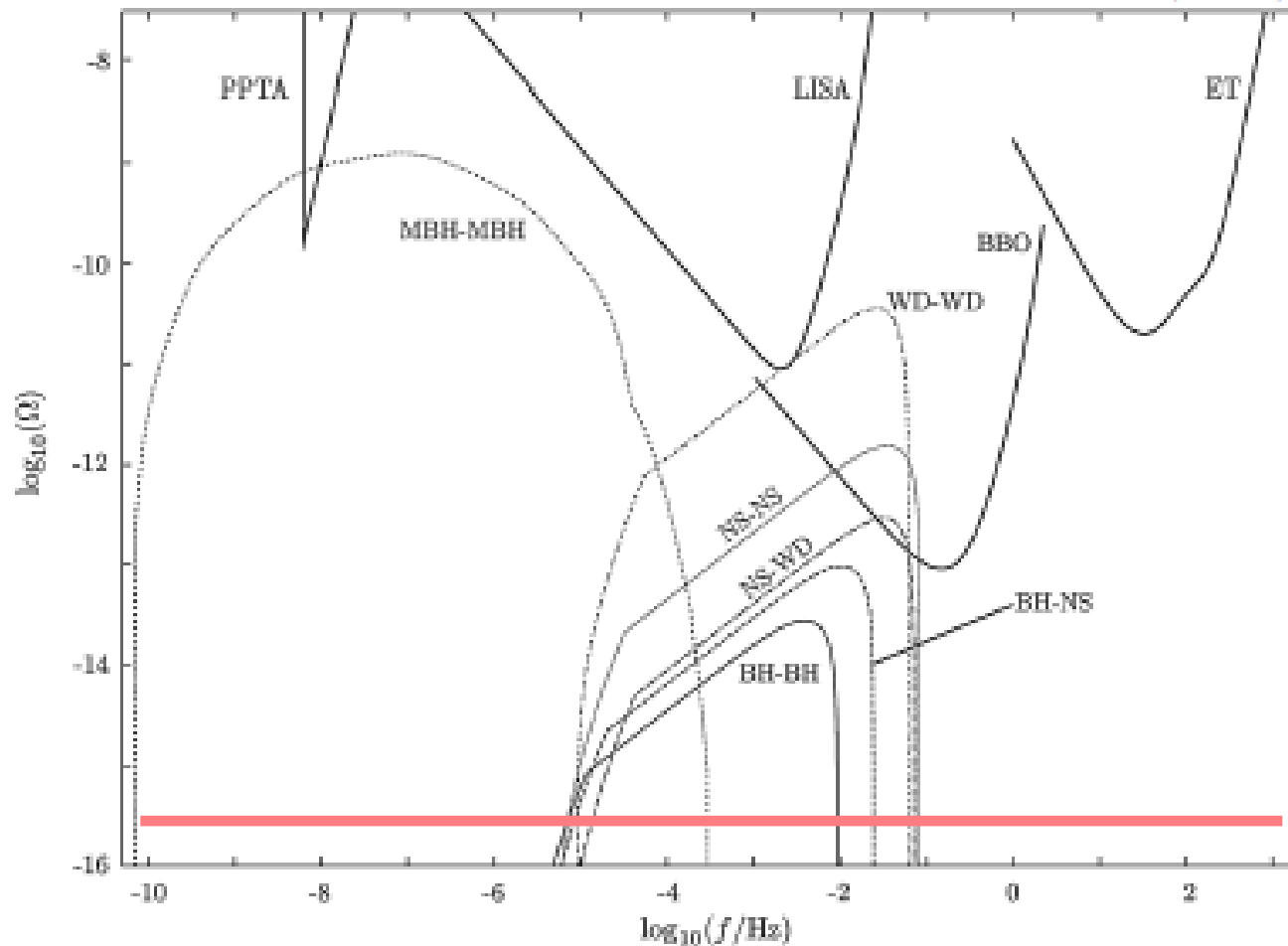
Earlier universe  $\rightarrow$  Smaller horizon scale  $\rightarrow$  High GW freq.



# GW Foreground

PABLO A. ROSADO

PHYSICAL REVIEW D 84, 084004 (2011)



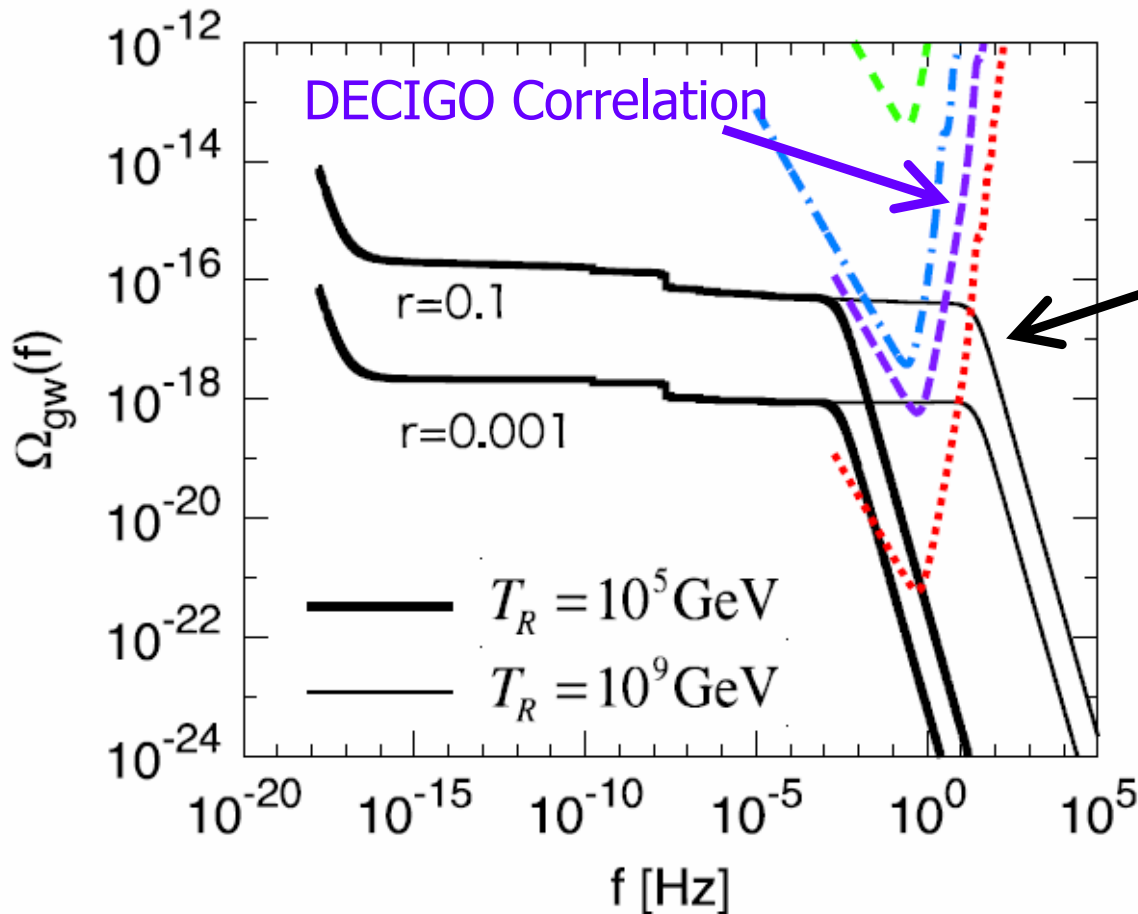
PABLO A. ROSADO PHYSICAL REVIEW D 84, 084004 (2011)



# GW from Inflation

Energy density  $\propto$  Tensor-Scalar Ratio ( $r$ ).

Power spectrum : Evolution history of the Universe.



- Spectrum Power.  
→ Energy scale of inflation
- Cut-off freq.  
→ Energy scale of Reheating

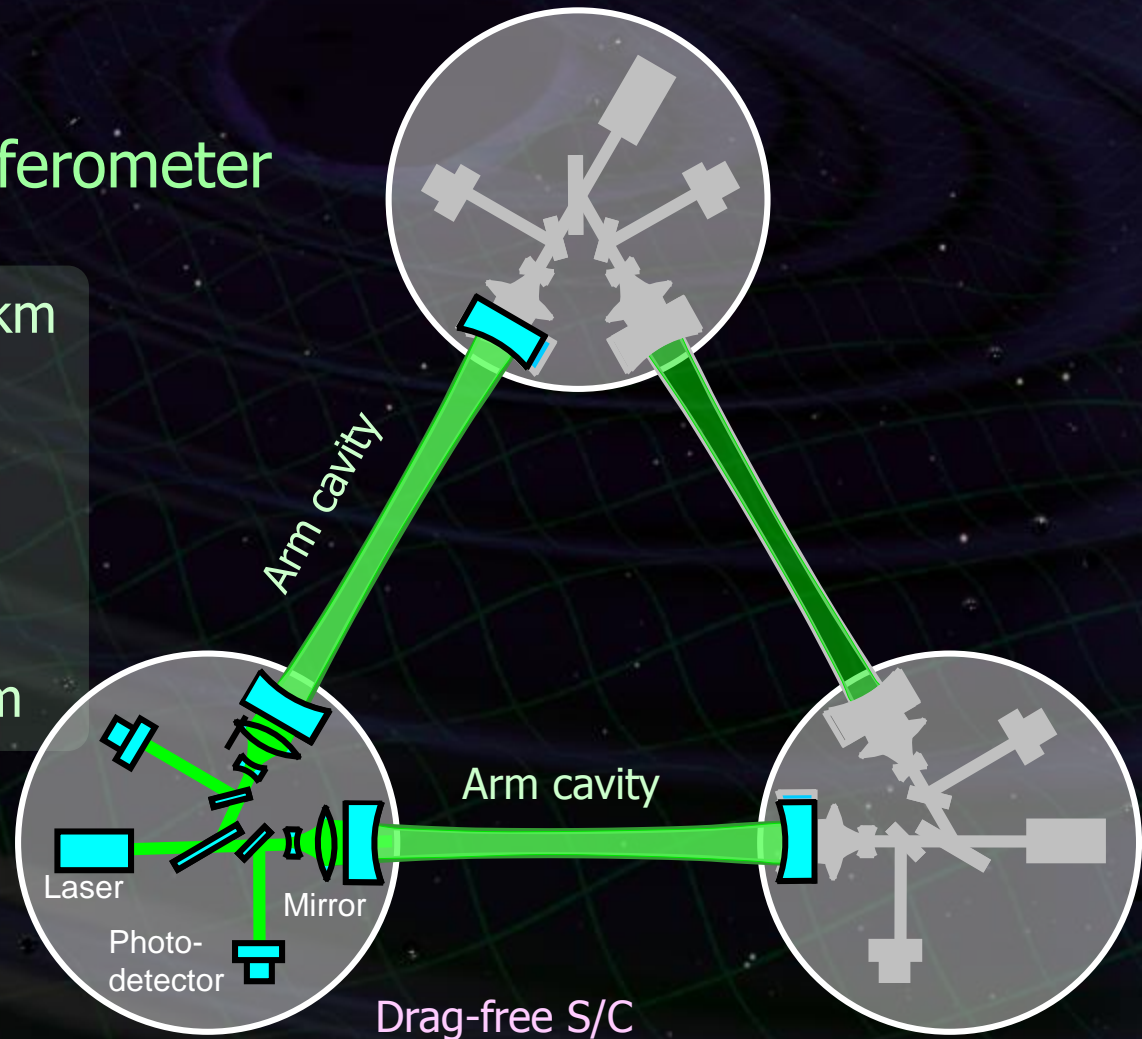
Nakayama+,  
Journal of Cosmology  
and Astroparticle Physics  
06 (2008) 020.

Interferometer Unit:

Differential FP interferometer

Arm length:	1000 km
Finesse:	10
Mirror diameter:	1 m
Mirror mass:	100 kg
Laser power:	10 W
Laser wavelength:	532 nm

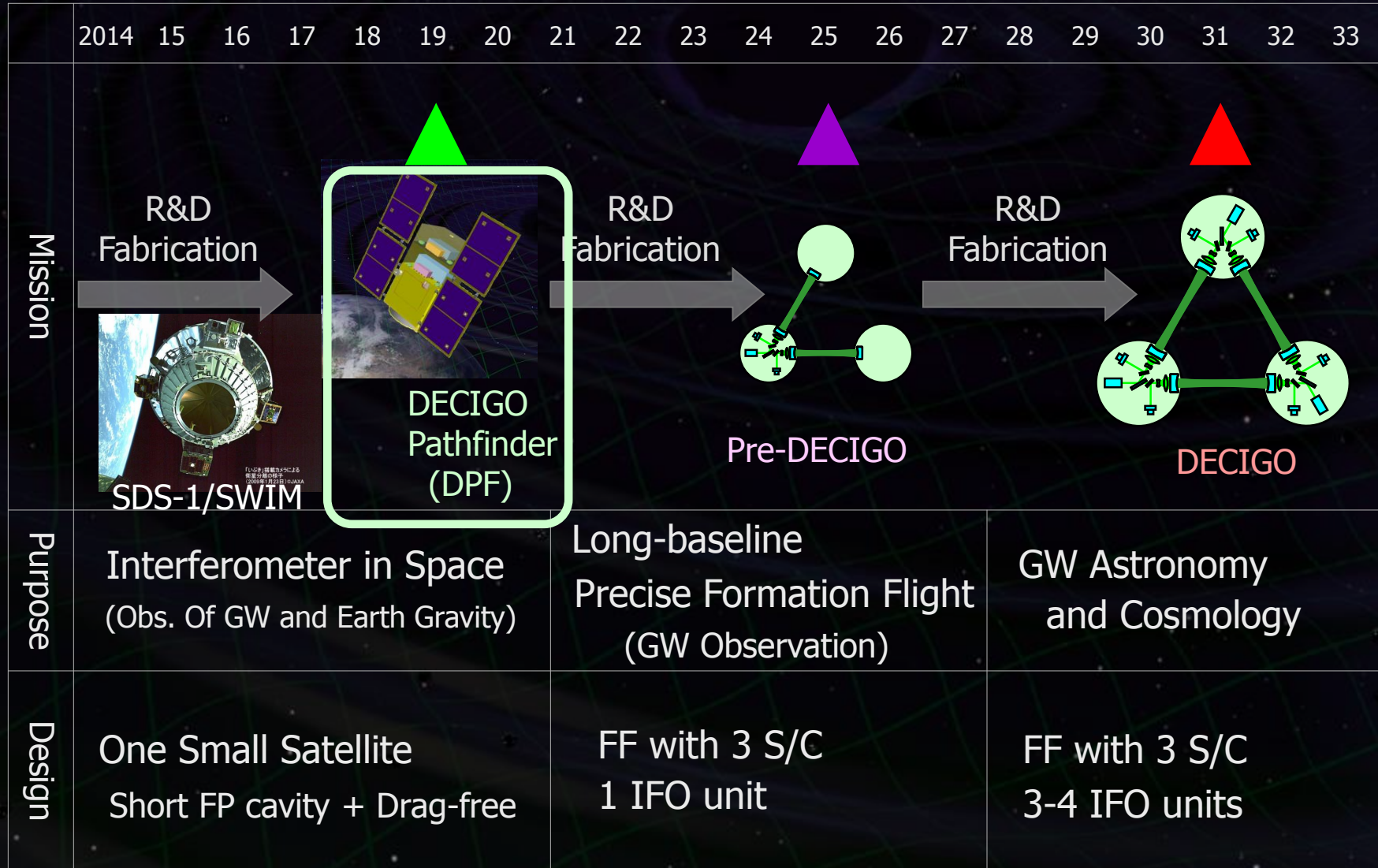
S/C: drag free  
3 interferometers





# Roadmap for DECIGO

Figure: S.Kawamura



# DECIGO Pathfinder



- Key technologies for DECIGO

- (1) Precise measurement by laser interferometer.

Operation of Fabry-Perot interferometer  
in Space environment and Drag-free control.

⇒ Demonstration by DPF

- (2) Long-baseline formation flight.

Realization of precise formation flight  
with more than km scale

⇒ Demonstration by Pre-DECIGO

## DECIGO Pathfinder (DPF)

First milestone mission for DECIGO

Shrink arm cavity

DECIGO 1000km  $\rightarrow$  DPF 30cm

### Purpose

- FP interferometer in space
- Stabilized laser source
- Drag-free control
- Continuous data-processing





# DPF satellite

## DPF Payload

Size : 950mm cube  
Weight : 200kg  
Power : 130W  
Data Rate: 800kbps  
Mission thruster x10

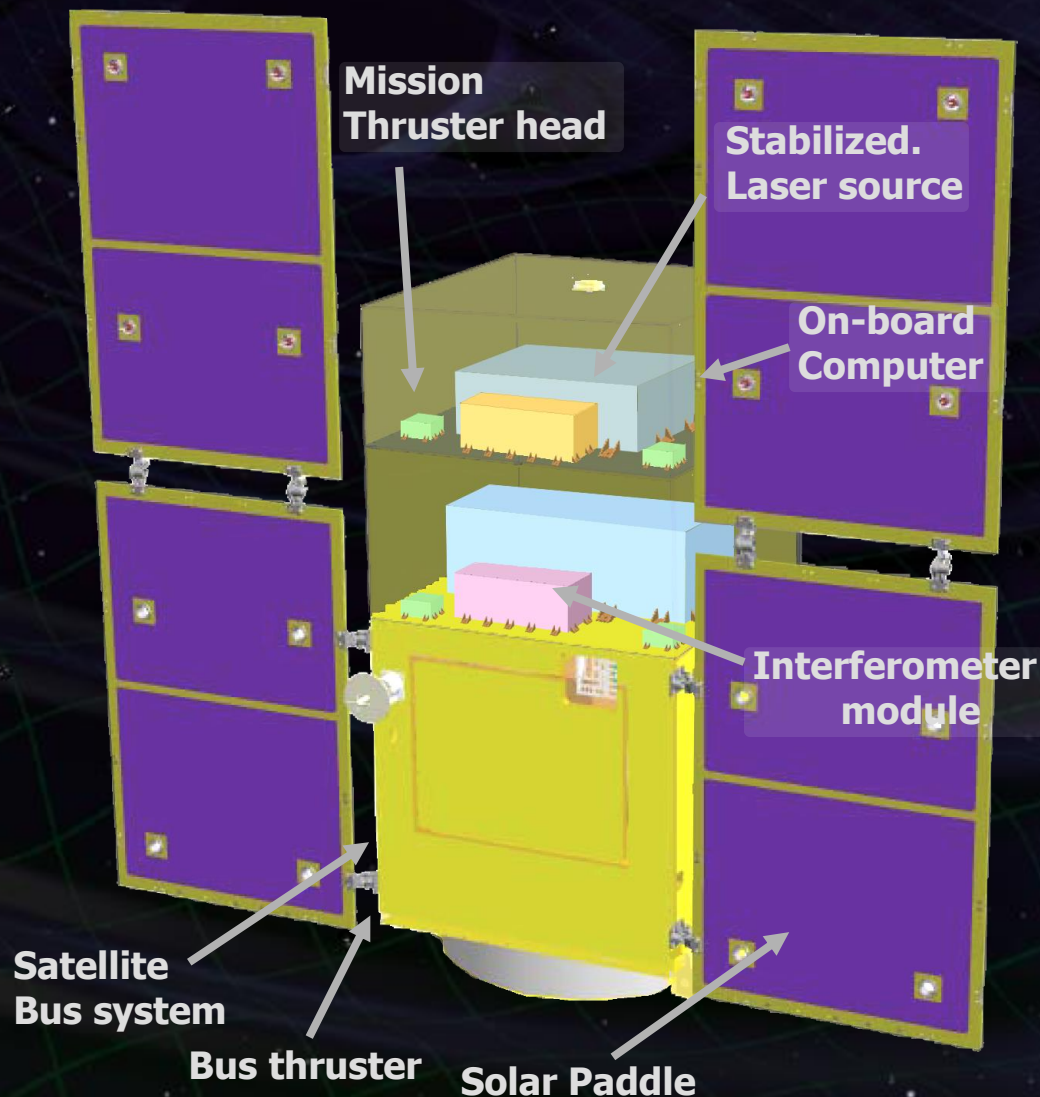
Power Supply  
SpW Comm.



## Satellite Bus

(‘Standard bus’ system)

Size :  
950x950x1100mm  
Weight : 250kg  
SAP : 960W  
Battery: 50AH  
Downlink : 2Mbps  
DR: 1GByte  
3N Thrusters x 4

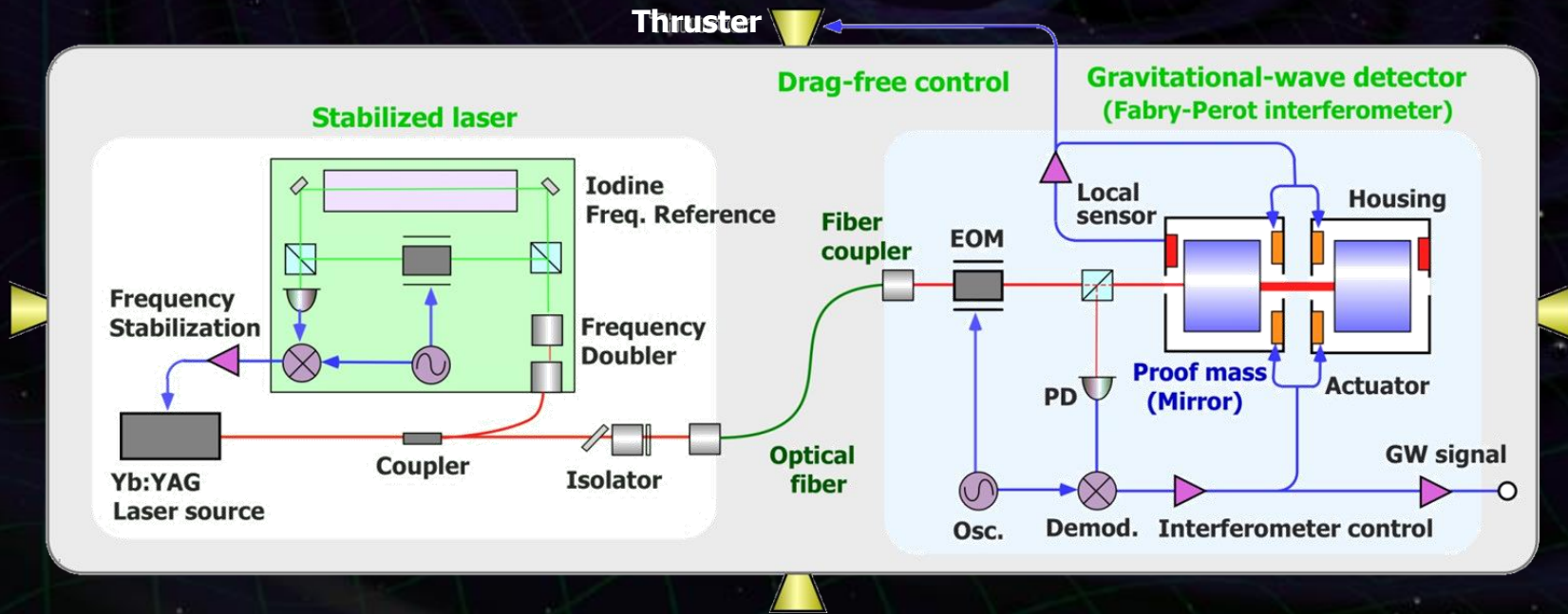


# DPF mission payload

**Mission weight :**  $\sim 200\text{kg}$   
**Mission space :**  $\sim 95 \times 95 \times 90 \text{ cm}$

## Drag-free control

Local sensor signal  
→ Feedback to thrusters



## Laser source

Yb:YAG laser (1030nm)  
Power : 25mW  
Freq. stab. by Iodine abs. line

## Fabry-Perot interferometer

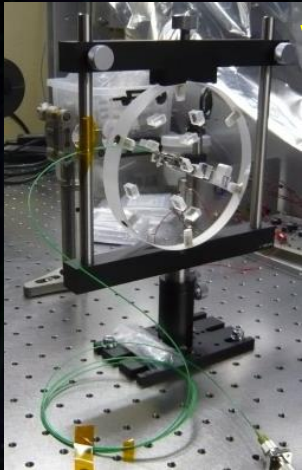
Finesse : 100  
Length : 30cm  
Test mass :  $\sim$ a few kg  
Signal extraction by PDH



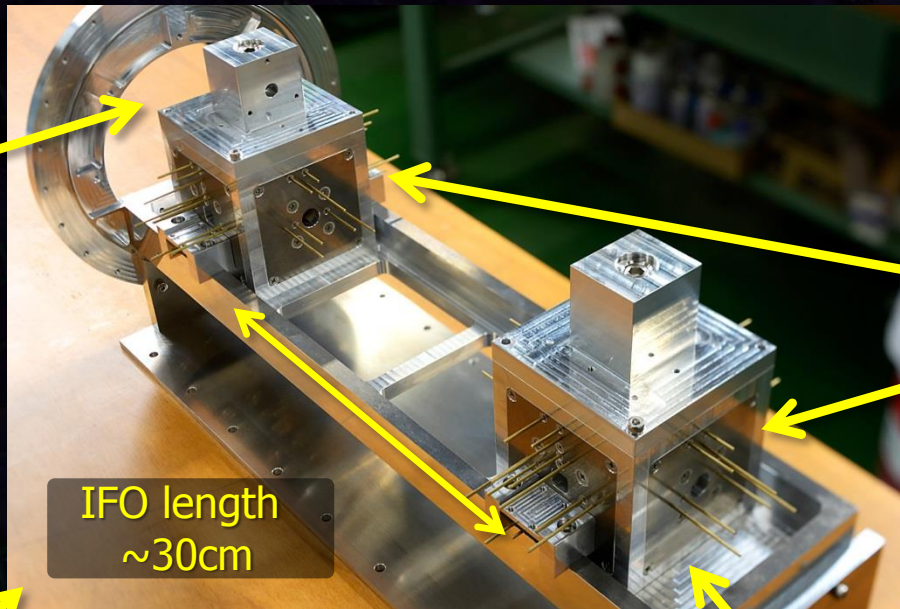
# Interferometer Module

## IO Optics

Monolithic opt. bench by silicate bonding

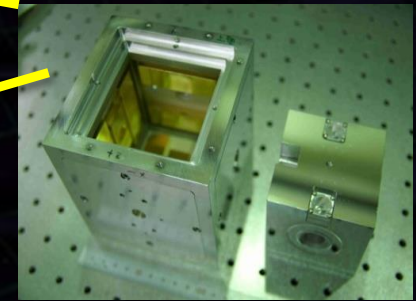


## Interferometer Module



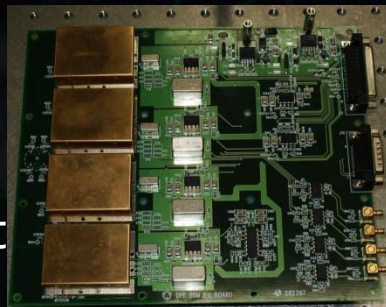
## Test mass module

TM, Capacitive Sensor/Actuator, Launch lock



## Quad-RFPD

Quadrant PD + Demod. circuits for length and alignment control signals



## SpW signal-processing board

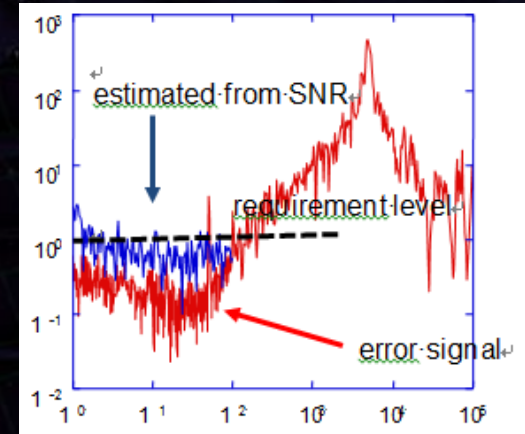
SpW FPGA + 16bit AD/DA



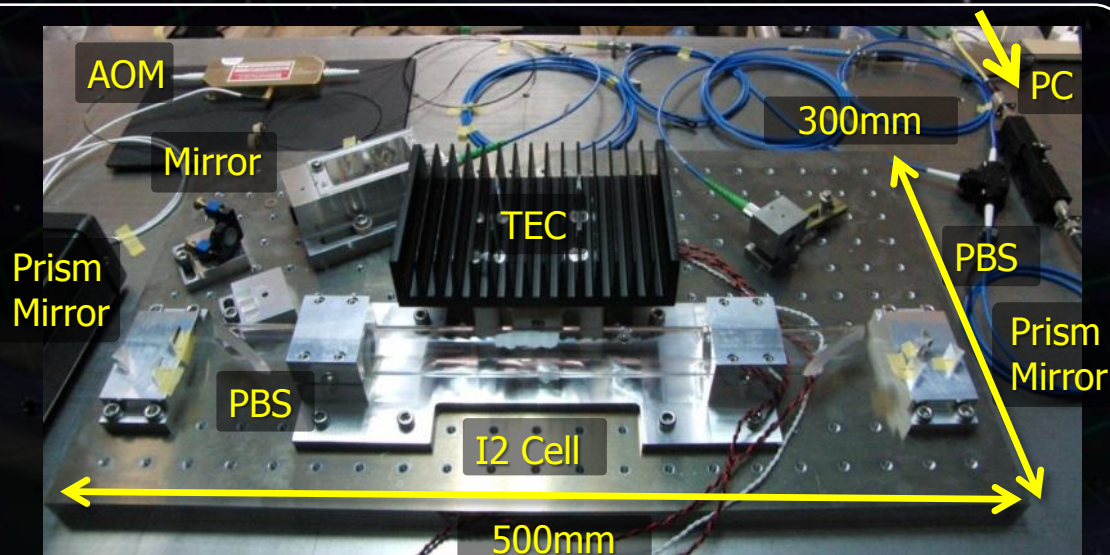
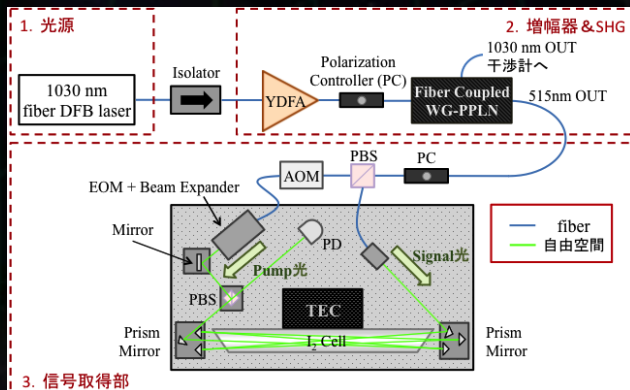


# Frequency Stabilization Module

- Frequency Stabilization module BBM2 (at UEC)
  - Use absorption line of Iodine molecule.
  - Satisfy requirement ( $0.5 \text{ Hz/Hz}^{1/2}$ ) in error-signal measurement.
  - Preparing one-more module for relative stability evaluation.



## Freq. Stab module





# DPF mission status

DPF : One of the candidate of  
JAXA's small satellite program

~150M\$ -scale mission opportunity

Standard Bus + Epsilon rocket

1<sup>st</sup> mission (2012): SPRINT-A/EXCEED

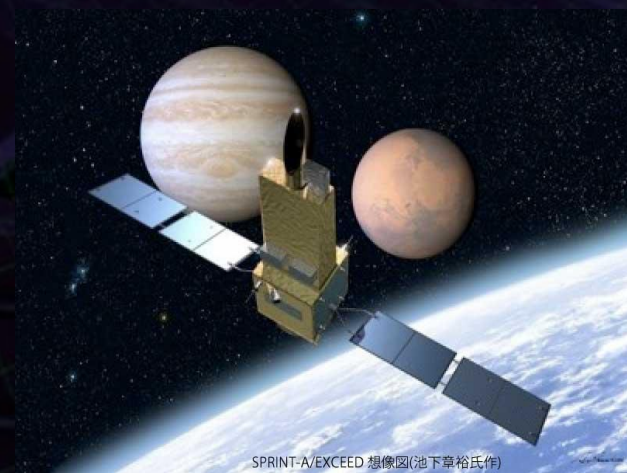
2<sup>nd</sup> mission (~2015) : SPRINT-B/ERG

**DPF survived until final two**

3<sup>rd</sup> mission (~2019) : TBD

Call for proposal : 2014

↑ DPF proposal submitted



SPRINT-A /EXCEED  
UV telescope mission



Epsilon rocket Fig. by JAXA

# Mission Selection Result

- AO from JAXA (December 2013)
  - for small science mission using epsilon rocket.
  - The program framework was changed:
    - ~10 M\$ payload mission → ~150 M\$ mission
  - Deadline : End of February.
  - 7 mission proposals including DPF.



DPF was dropped in the first down-selection (May)

- Started discussions on the next strategy.



# Restructure of Space Program

- ISAS/JAXA decided a new plan for space science and exploration program (2014)
  - Three categories
    - \* **Strategic medium-scale missions (~300 M\$)**  
Hayabusa-2, ASTRO-H
    - \* **Small-scale missions (100 - 150 M\$)**  
AO in every two years  
HISAKI, ERG, ...
    - \* **Various small projects (~10 M\$/year)**  
ISS missions, International collaboration,  
Small rocket, Balloon, ...



'Small-scale' mission became core program in JAXA

# Summary



## **DECIGO : Fruitful Sciences**

Very beginning of the Universe

Dark energy, Dark matter

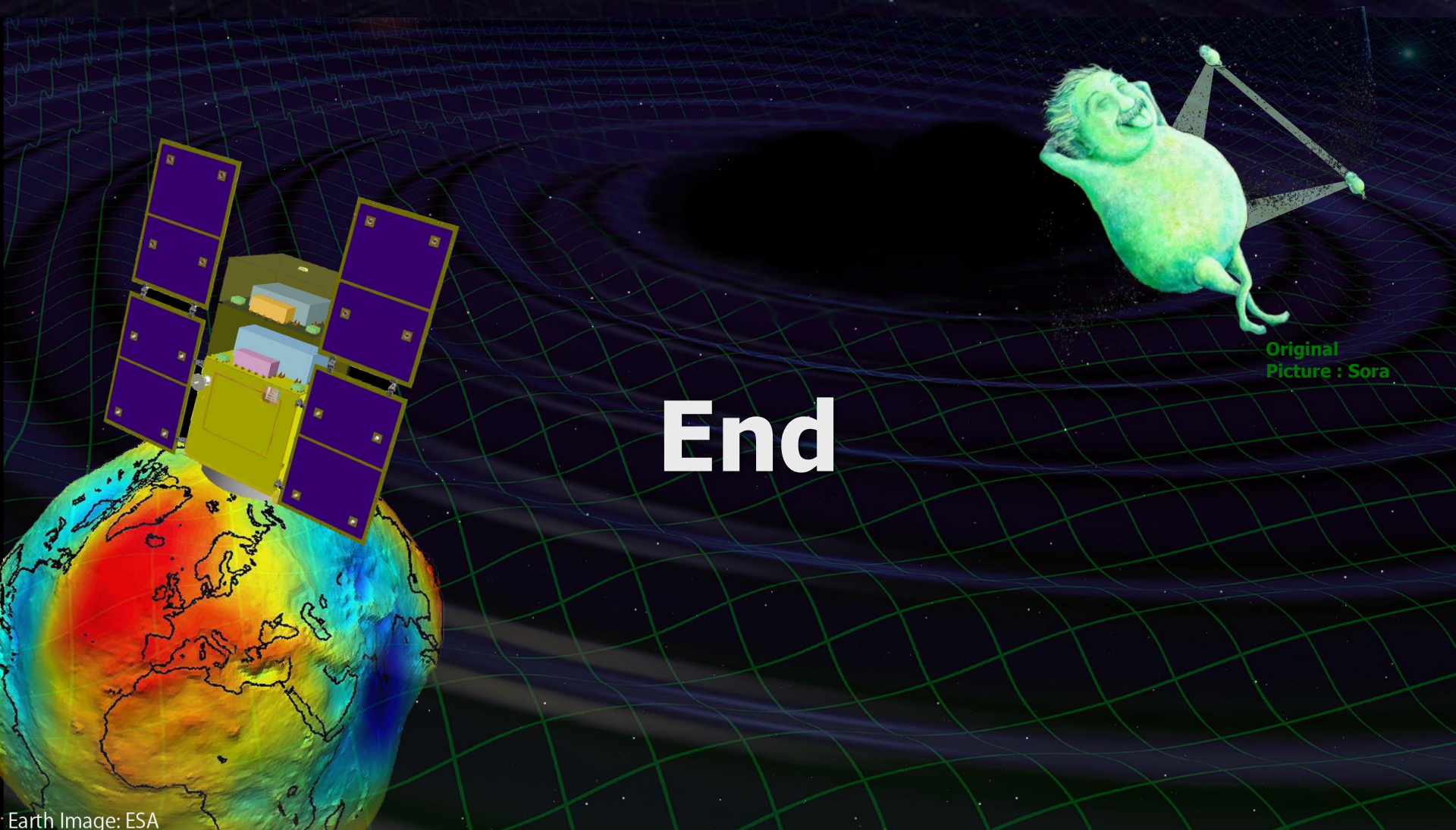
Galaxy formation

→ Will be realized at last.

## **DECIGO Pathfinder**

Submitted mission proposal,  
but failed in the selection.

→ Start discussions on the next strategy.



End

Original  
Picture : Sora

Earth Image: ESA



# Mission Plan by JAXA



From file submitted to the government by ISAS/JAXA

(内閣府・宇宙政策委員会・宇宙科学・探査部会 2013年9月19日)

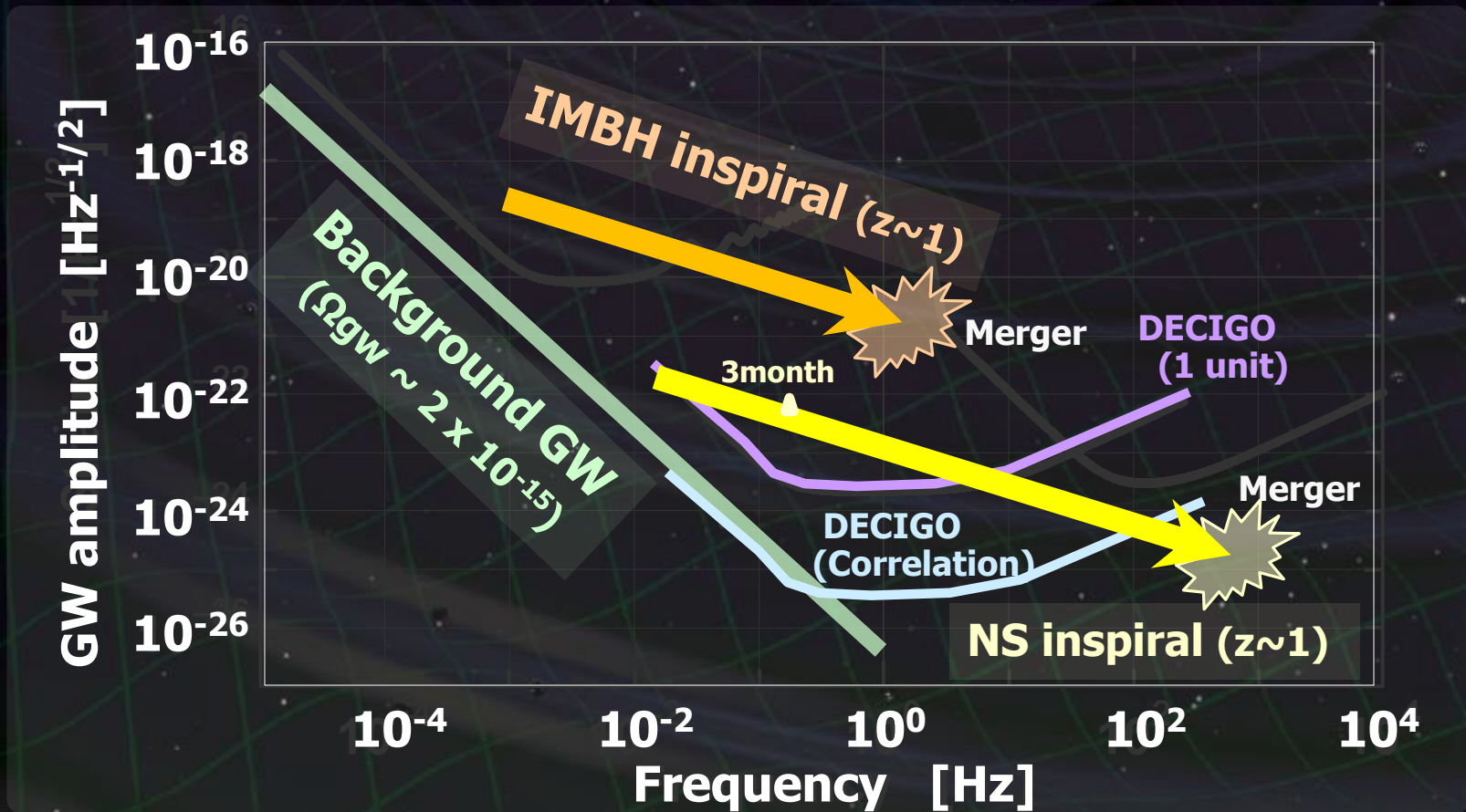
分類	ミッション・事業名称	状況	第2期中期計画				第3期中期計画				第4期中期計画				第5期中期計画				備考
			FY2010	FY2011	FY2012	FY2013	FY2014	FY2015	FY2016	FY2017	FY2018	FY2019	FY2020	FY2021	FY2022	FY2023	FY2024	FY2025	
戦略的に実施する 中型計画	はやぶさ2	開発中	▲PJ準備 ▲PJ移行		▲打上		▲打上		▲小惑星到着 ▲地球帰還										
	ASTRO-H	開発中	▲PJ移行 ▲PDR ▲COR1-2		▲打上		▲打上												
	将来計画 (仮称:M1-M4) 4年に1回AO発出 開発期間6年 (5~7年)	計画中			★公募(AO) ▲PJ移行		▲打上		★公募(AO) ▲PJ移行		▲打上		▲打上		FY2021(20-22)▲				
		計画中							★公募(AO) ▲PJ移行		▲打上		▲打上		FY2023(26-28)▲				
計画中										★公募(AO) ▲PJ移行		▲打上		FY2029(28-30)▲					
公募型 小型計画	惑星分光衛星衛星	開発中	▲SOR/PJ移行		▲打上		▲打上												
	ジオスペース探査衛星	開発中	▲MDR/SOR ▲RSP ▲SDR ▲POR		▲打上		▲打上												
	BepiColombo	開発中	▲COR		▲打上 ▲打上		▲打上		▲打上		▲打上		▲水星到着						
	将来計画 (仮称:S1-S7) 2年に1回AO発出 開発期間4年	計画中			★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2019▲				
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2020▲					
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2022▲					
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2024▲					
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2026▲					
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2028▲					
計画中				★公募(AO) ▲PJ移行		▲打上		▲打上		▲打上		▲打上		FY2030▲					
多様な小規模 プロジェクト群	計画中			★計画決定		再探査探査等の状況に応じて、随時AO発出・計画決定・実行する。													
基盤的 活動費	学術研究・実験等 軌道上衛星の運用 宇宙科学施設維持	継続的に 実施中	将来のミッション発出につながる学術研究・実験等の推進や衛星運用、施設維持の実施に必要な活動費。 従前より効率化努力を行って来たところ、更なる効率的な執行に努める。																

# Targets and Science

IMBH binary inspiral  
NS binary inspiral  
Stochastic background



Galaxy formation (Massive BH)  
Cosmology (Inflation, Dark energy)  
Fundamental physics



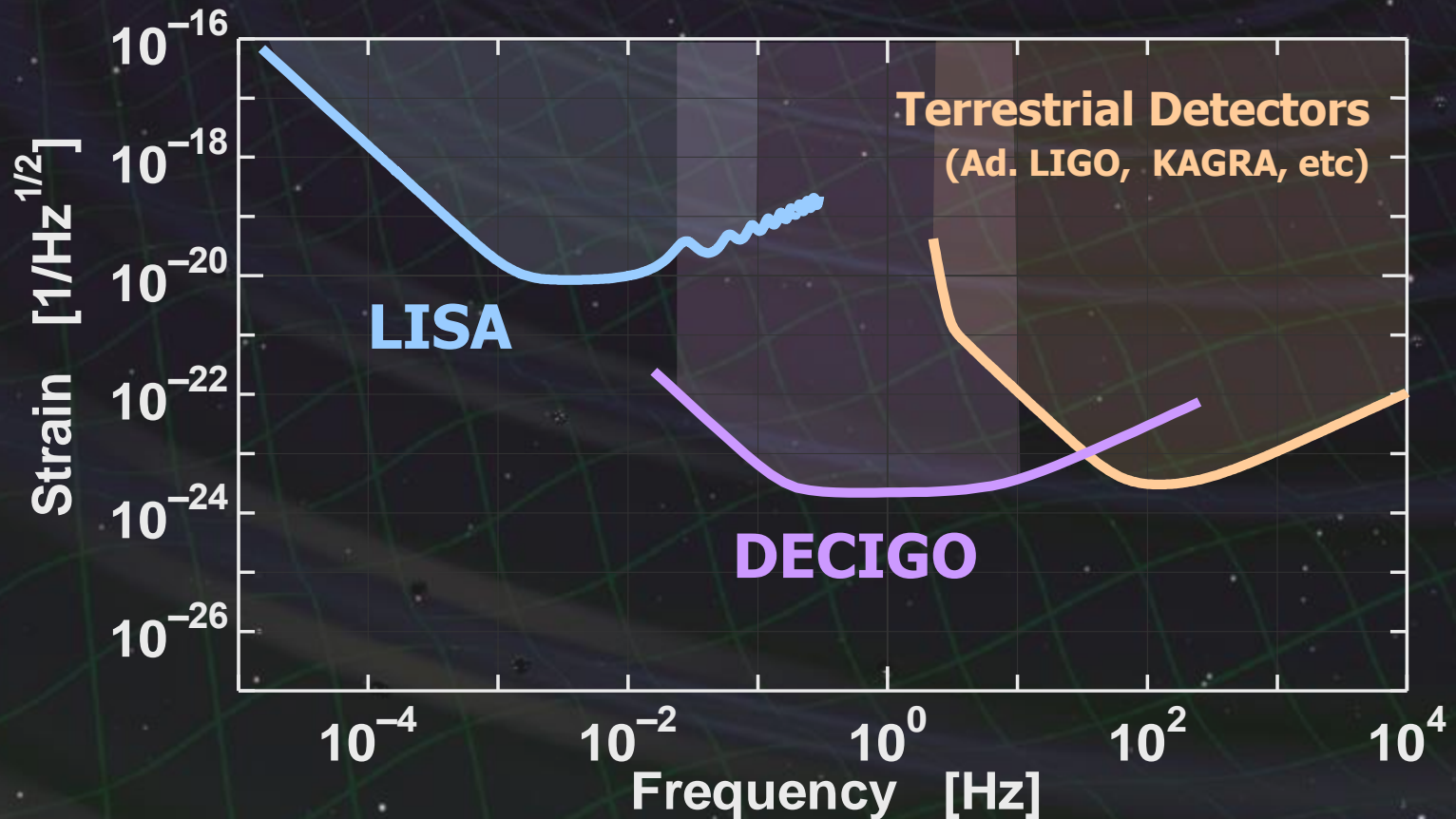


## DECIGO (Deci-hertz interferometer Gravitational wave Observatory)

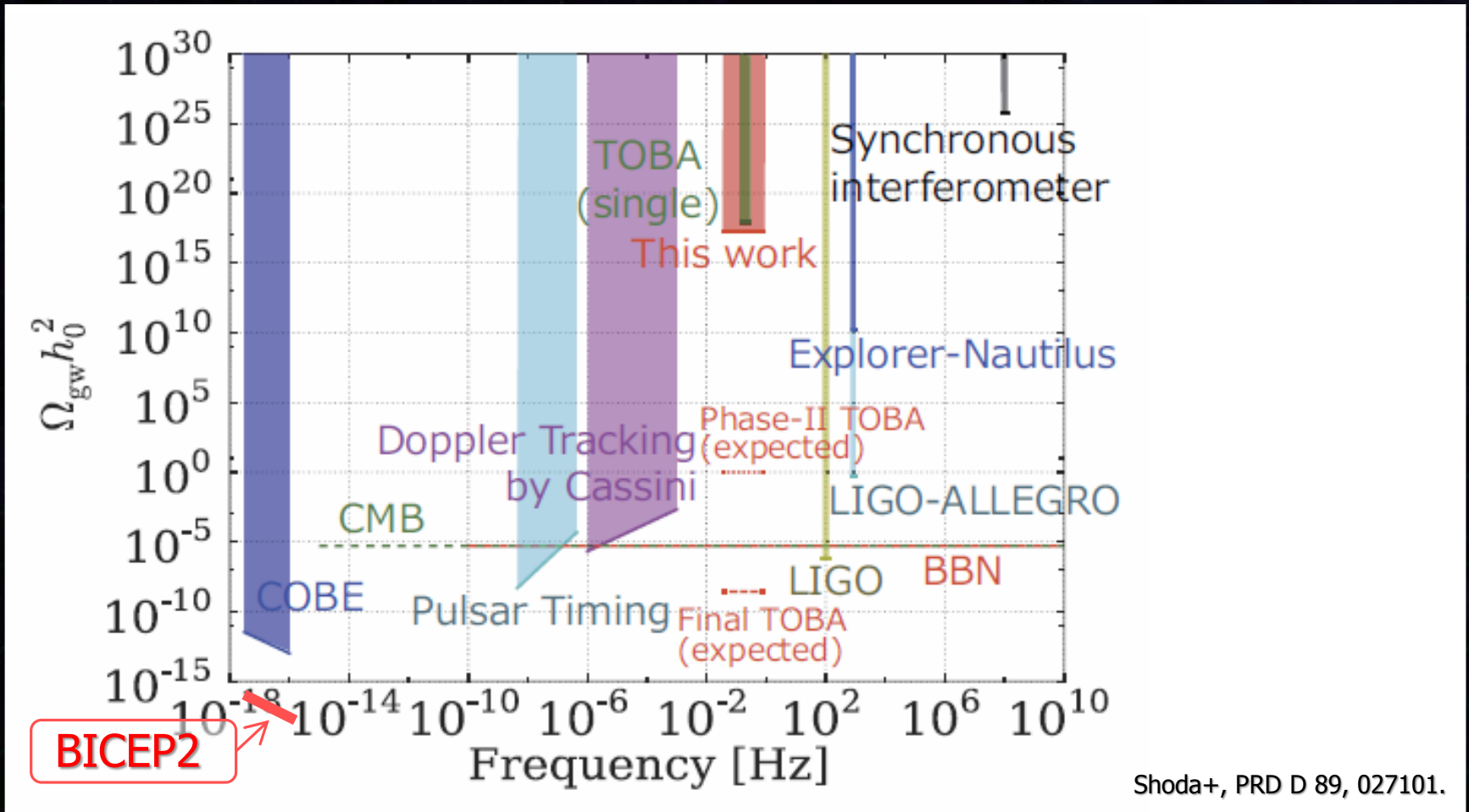
Space GW antenna (~2030)  
Obs. band around 0.1 Hz



'Bridge' the obs. gap between  
LISA and Terrestrial detectors



# 背景重力波探査の現状





# Technical Steps for DECIGO

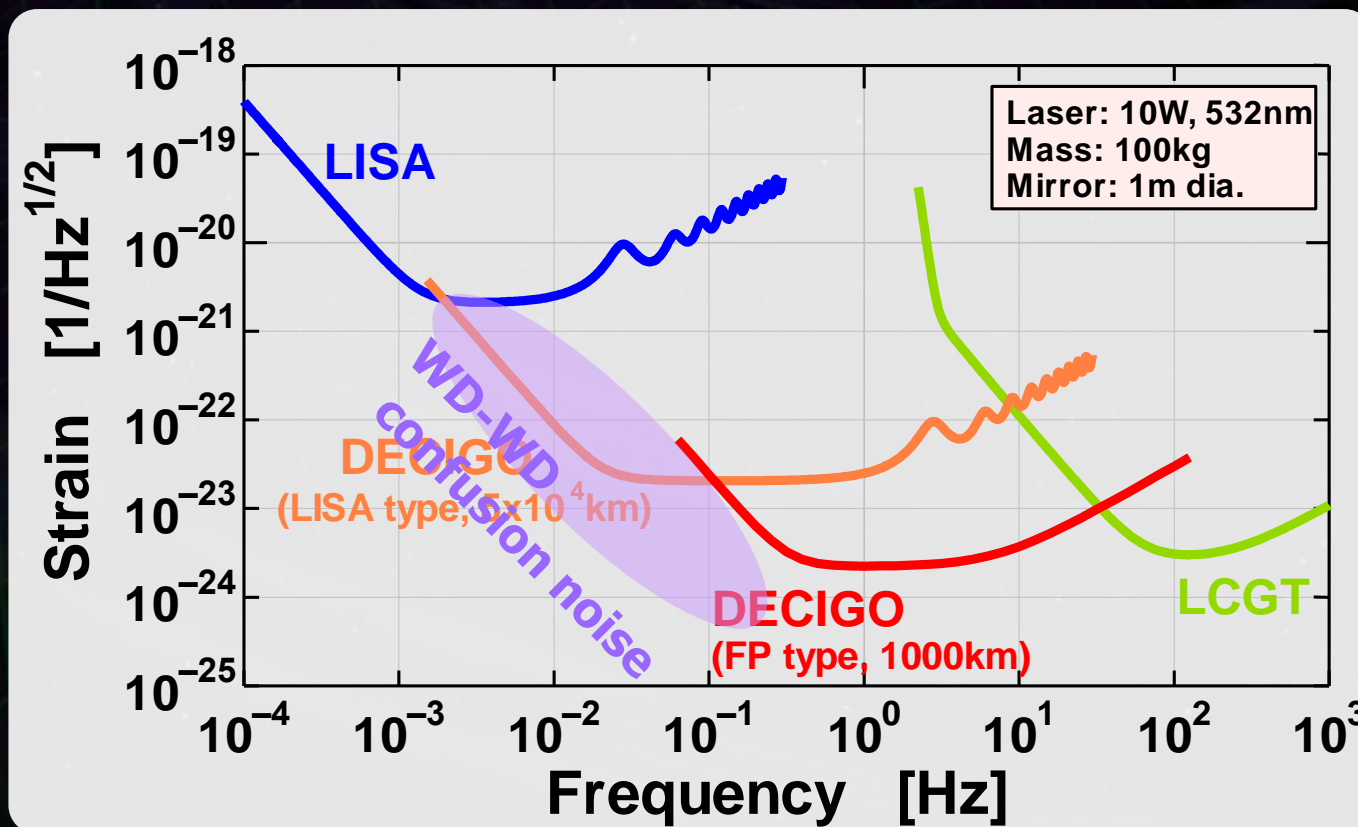


	DPF target	Pre-DECIGO target	DECIGO Requirement
Space FP	First demonstration of FP cavity (30cm) in space. Disp. noise $\sim 10^{-16} \text{m/Hz}^{1/2}$ , Acc. Noise $10^{-15} \text{N/Hz}^{1/2}$ .	FP operation with long-base line (100km). Disp. noise $10^{-17} \text{m/Hz}^{1/2}$ . Acc. noise $10^{-16} \text{N/Hz}^{1/2}$ .	Disp. $3 \times 10^{-18} \text{m/Hz}^{1/2}$ . Acc. $10^{-17} \text{N/Hz}^{1/2}$ . Baseline length 1000km.
Stab. Laser source	Freq. stability of $0.5 \text{Hz/Hz}^{1/2}$ in space environment. Output pow. : 100mW.	Freq. stability of $0.5 \text{Hz/Hz}^{1/2}$ . Output pow. : 1W.	Freq. Stab. of $0.5 \text{Hz/Hz}^{1/2}$ . Output pow. : 10W.
Drag-free Control and FF	Realize all DoF drag-free control with $1 \times 10^{-9} \text{m/Hz}^{1/2}$ .	All DoF DF control $1 \times 10^{-9} \text{m/Hz}^{1/2}$ . Long-baseline Formation Flight 100km.	All DoF DF control $1 \times 10^{-9} \text{m/Hz}^{1/2}$ . Long-baseline FF 1000km.

## Transponder type vs Direct-reflection type

Compare : Sensitivity curves and Expected Sciences

⇒ Decisive factor: Binary confusion noise





# Arm length

## Cavity arm length : Limited by diffraction loss

Effective reflectivity ( $TEM_{00} \rightarrow TEM_{00}$ )

Laser wavelength : 532nm

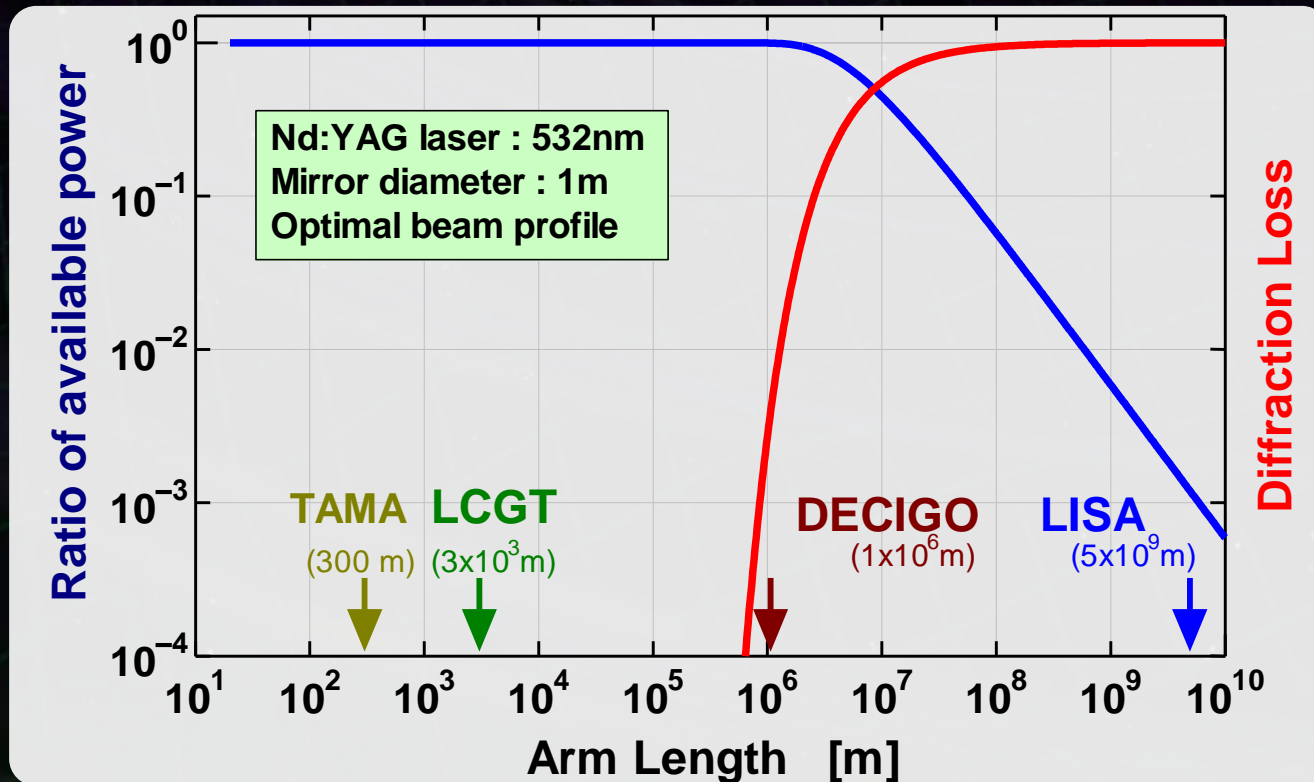
Mirror diameter: 1m

Optimal beam size



1000 km

is almost max.



# Cavity and S/C control

## Cavity length change

PDH error signal  $\rightarrow$  Mirror position (+Laser freq.)

Relative motion between mirror and S/C

Local sensor  $\rightarrow$  S/C thruster

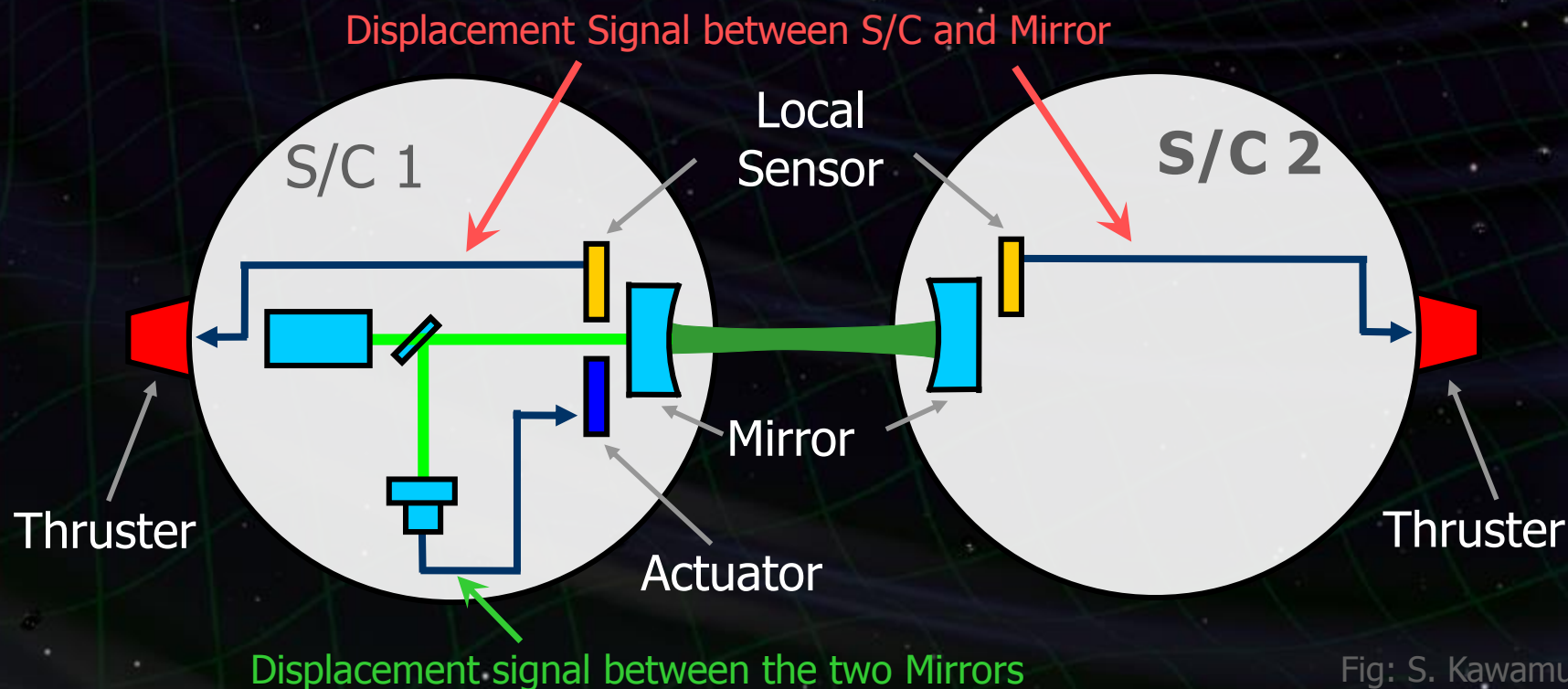


Fig: S. Kawamura



## Displacement Noise

Shot noise  $3 \times 10^{-18} \text{ m/Hz}^{1/2}$  (0.1 Hz)

⇒ x 10 of KAGRA in phase noise

Other noises should be well below the shot noise

Laser freq. noise:  $1 \text{ Hz/Hz}^{1/2}$  (1Hz)

Stab. Gain  $10^5$ , CMRR  $10^5$

## Acceleration Noise

Force noise  $4 \times 10^{-17} \text{ N/Hz}^{1/2}$  (0.1 Hz)

⇒ x 1/50 of LISA

External force sources

Fluctuation of magnetic field, electric field,  
gravitational field, temperature, pressure, etc.

# Foreground Cleaning

DECIGO obs. band: free from WD binary foreground  
→ Open for cosmological observation

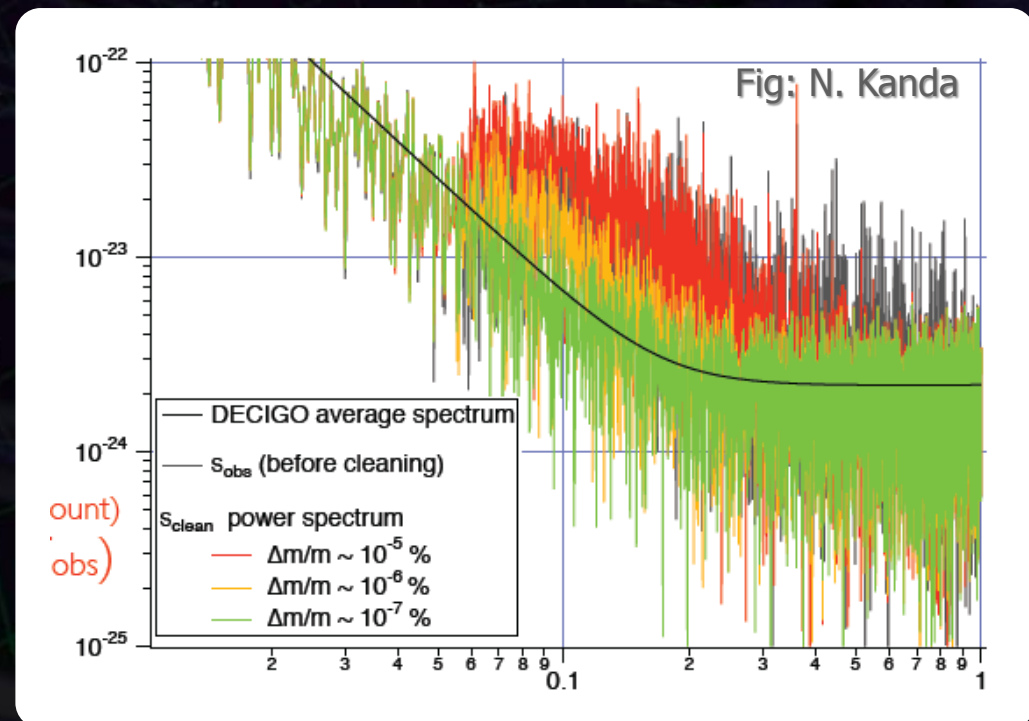
DECIGO will watch  
 $\sim 10^5$  NS binaries

⇒ **Foreground for GWB**

In principle, possible  
to remove them.

Require waveform

Accuracy  $\Delta m/m < \sim 10^{-7}$  %





## Considering “Conceptual design”

By T.Akutsu

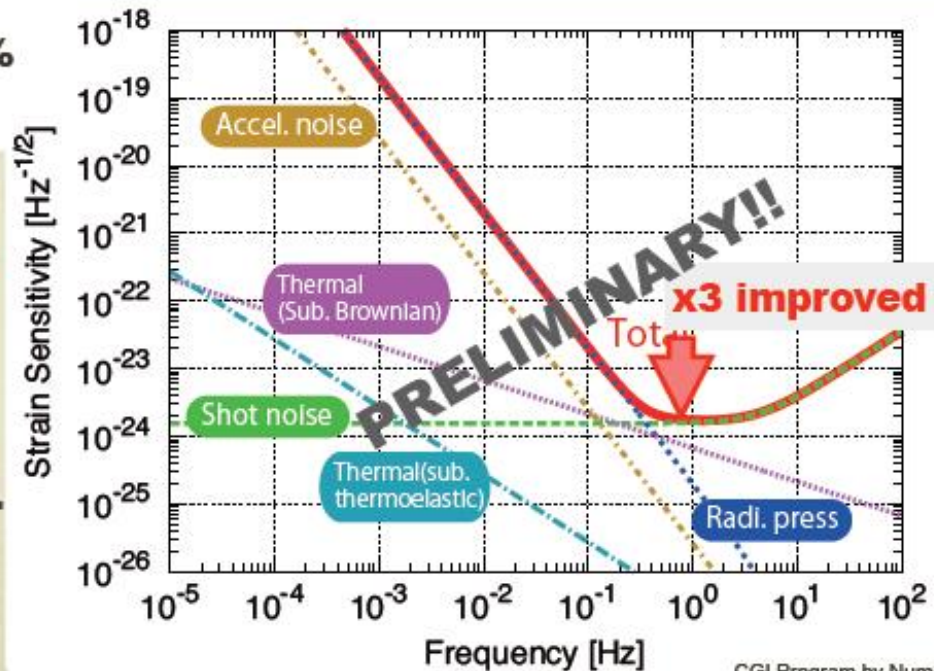
- Arm length: **1,500 km**
- Laser power: **30 W**
- Laser wavelength: **532 nm**
- Mirror diameter: **1.5 m**
- Mirror mass: **100 kg**
- Mirror reflectivity: **77.3%**
- Cavity g-param: **0.1**

Preliminary  
← Parameters tuned

This is the first step to considering the **conceptual design**.

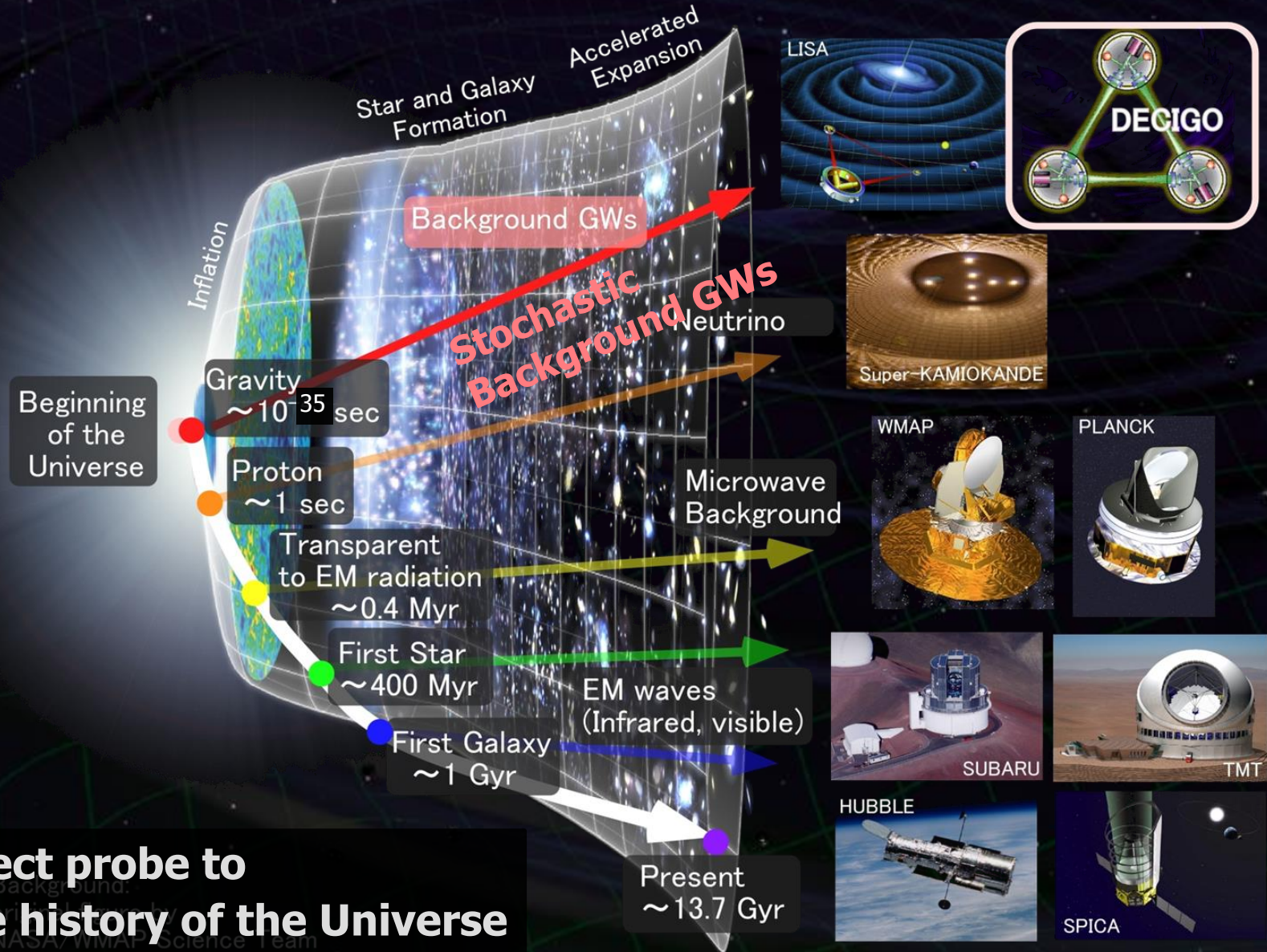
### Next:

- ➔ Confirm the calculations.
- ➔ Find the realistic way to realize this!





# Characterization of inflation

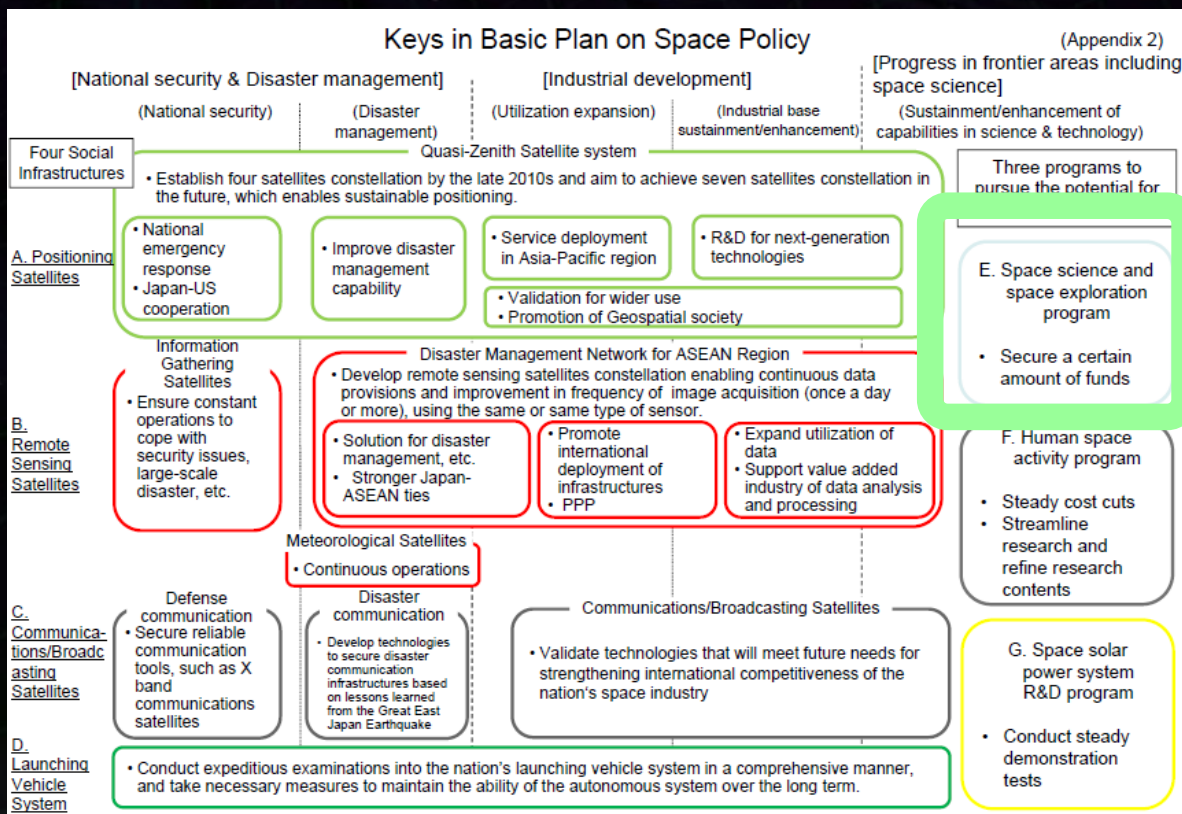


**Direct probe to the history of the Universe**



# Restructure of space sections

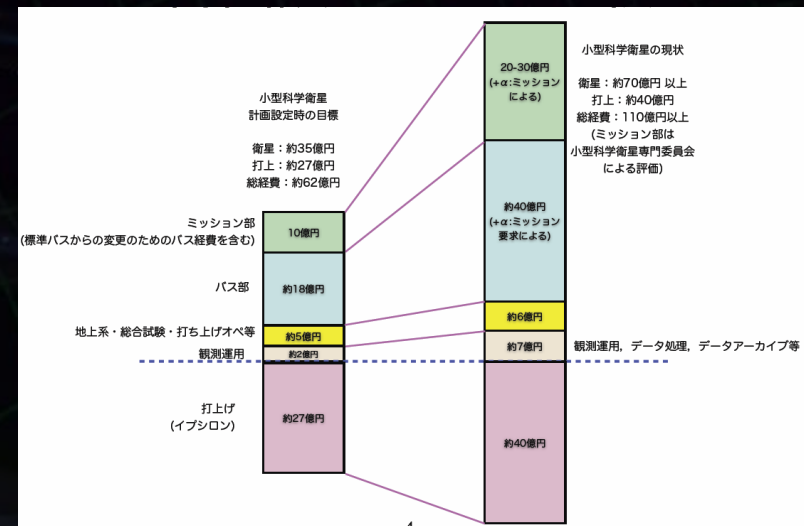
- Restructure of space sections in Japan (2008)  
Based on a new law : Basic Plan on Space Policy  
ISAS/JAXA : MEXT → Cabinet Office (CAO)



Space Science and space exploration program

From CAO Web Page : <http://www8.cao.go.jp/space/plan/plan-eng.pdf>

- 小型科学衛星シリーズの位置づけが見直された。
  - 小型科学衛星プログラムは「**特徴ある宇宙科学ミッションを迅速かつ高頻度を実現する**」目的で進められた。
  - しかし、2011年にERG（小型科学衛星2号機）の想定資金からの大幅超過をきっかけとして、**小型科学衛星シリーズとしてのプロジェクトは Termination された。**
  - 小型科学衛星専門委員会によるコスト評価、および、SE推進室の評価。
    - 検討中のWGのミッション実現には、**マージン無しで70から120億円の衛星コスト**（当初想定 of 1.7から3.4倍）が必要であることが示唆された。
  - これまで: ミッション部 10億円以内
    - 今後 ミッション部 20~30+a億円.

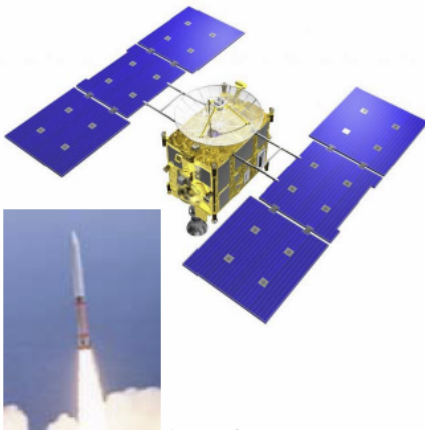




内閣府・宇宙政策委員会・宇宙科学・探査部会 資料より (2013年9月19日)

## Ⅲ. 今後の宇宙科学・探査プロジェクトの推進方策

宇宙科学における宇宙理工学各分野の今後のプロジェクト実行の戦略に基づき、厳しいリソース制約の中、従来目指してきた大型化の実現よりも、中型以下の規模をメインストリームとし、中型(H2クラスで打ち上げを想定)、小型(イプシロンで打ち上げを想定)、および多様な小規模プロジェクトの3クラスのカテゴリーに分けて実施する。



2000年代前半までの  
典型的な科学衛星ミッション  
M-Vロケットによる打ち上げ

戦略的に実施する中型計画(300億程度)  
世界第一級の成果創出を目指し、各分野のフラッグ  
シップ的なミッションを日本がリーダーとして実施する。  
多様な形態の国際協力を前提。

公募型小型計画(100-150億規模)  
高頻度な成果創出を目指し、機動的かつ挑戦的に実施  
する小型ミッション。地球周回/深宇宙ミッションを機動的  
に実施。現行小型衛星計画から得られた経験等を活か  
し、衛星・探査機の高度化による軽量高機能化に取り組  
む。等価な規模の多様なプロジェクトも含む。

多様な小規模プロジェクト群(10億/年程度)  
海外ミッションへのジュニアパートナーとしての参加、海外  
も含めた衛星・小型ロケット・気球など飛翔機会への参  
加、小型飛翔機会の創出、ISSを利用した科学研究など、  
多様な機会を最大に活用し成果創出を最大化する。

# Collaboration and support



- **Supports from LISA**

  - Technical advices from LISA/LPF experiences

  - Support Letter for DECIGO/DPF, Joint workshop (2008.11)

- **Collab. with Stanford univ. group**

  - Drag-free control of DECIGO/DPF

  - UV LED Charge Management System for DPF

- **Collab. with NASA/GSFC**

  - Fiber Laser , Earth's gravity observation

- **Collab. with JAXA Trajectory and Navigation group**

  - Formation flight of DECIGO, DPF drag-free control

- **Geophysics group (Kyoto, ERI, UEC, NAOJ)**

- **Advanced technology center ( ATC) of NAOJ**

- **JAXA's fund for small satellite development**

- **Research Center for the Early Universe (RESCEU), Univ. of Tokyo**



- **Verification of the alternative theories of gravity**

Test Brans-Dicke theory by NS/BH binary evolution

→ Stronger constraint by  $10^4$  times

K. Yagi and T. Tanaka, Prog. Theor. Phys. 123, 1069 (2010)

- **Black hole dark matter**

Gravitational collapse of the primordial density fluctuations

→ Primordial black holes (PBHs)

as a candidate of dark matter

R. Saito and J. Yokoyama, Phys. Rev. Lett. 102 161101 (2009)

- **Neutron-star physics**

Determine masses of  $10^5$  NSs per year

→ Constrain the EoS of NS

Formation process of NS from the spectrum

# GW observation roadmap





# インフレーションの重力波観測

BICEP2, (POLARBEAR,...)

マイクロ波望遠鏡を用いた  
宇宙背景放射 B-mode偏光  
成分の観測.

DECIGO, (KAGRA, aLIGO,...)

重力波望遠鏡を用いた  
宇宙背景重力波の観測.



図: 田島氏談話会資料より(2011 京都大学)

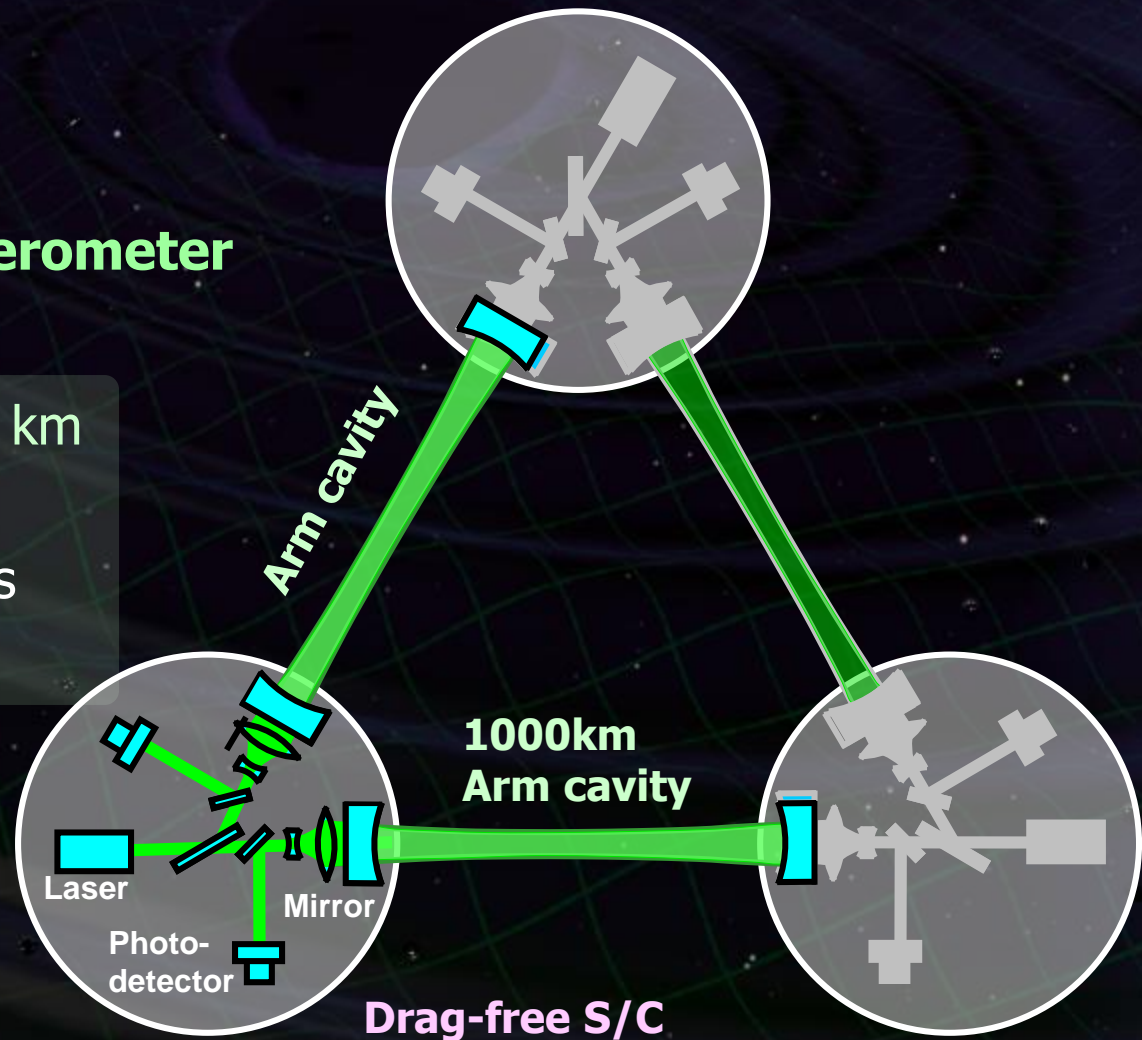
## Interferometer Unit: Differential FP interferometer

Baseline length: 1000 km

3 S/C formation flight

3 FP interferometers

Drag-free control





# Organization



**PI: Nakamura (Kyoto)**  
**Deputy: Ando (Tokyo), Seto (Kyoto)**

**Executive Committee**  
Kawamura (ICRR), Ando (Tokyo), Seto (Kyoto), Nakamura (Kyoto),  
Tsubono (Waseda), Tanaka (Kyoto), Funaki (ISAS), Numata  
(Maryland), Sato (Hosei), Kanda (Osaka city), Takashima (ISAS),  
Ioka (KEK), Yokoyama (Tokyo), Akutsu (NAOJ)

**Pre-DECIGO**  
Sato (Hosei)

**Detector**  
Akutsu (NAOJ)  
Numata  
(Maryland)

**Science, Data**  
Tanaka (Kyoto)  
Seto (Kyoto)  
Kanda (Osaka city)

**Satellite**  
Funaki (ISAS)

## Design phase

**DECIGO pathfinder**  
**Leader: Ando (Tokyo)**

## Mission phase

**Detector**  
Sato (Hosei)  
Akutsu (NAOJ)  
Ueda (NAOJ)  
Aso (Tokyo)

**Laser**  
Musha (ILS)  
Ueda (ILS)

**Drag free**  
Sato (Hosei)

**Thruster**  
Funaki  
(ISAS)

**Satellite**  
Sato  
(Hosei)

**Data**  
Kanda  
(Osaka  
city)

# Orbit and Constellation

## Candidate of orbit:

Record-disk orbit around the Sun

Relative acc.  $4 \times 10^{-12} \text{ m/s}^2$

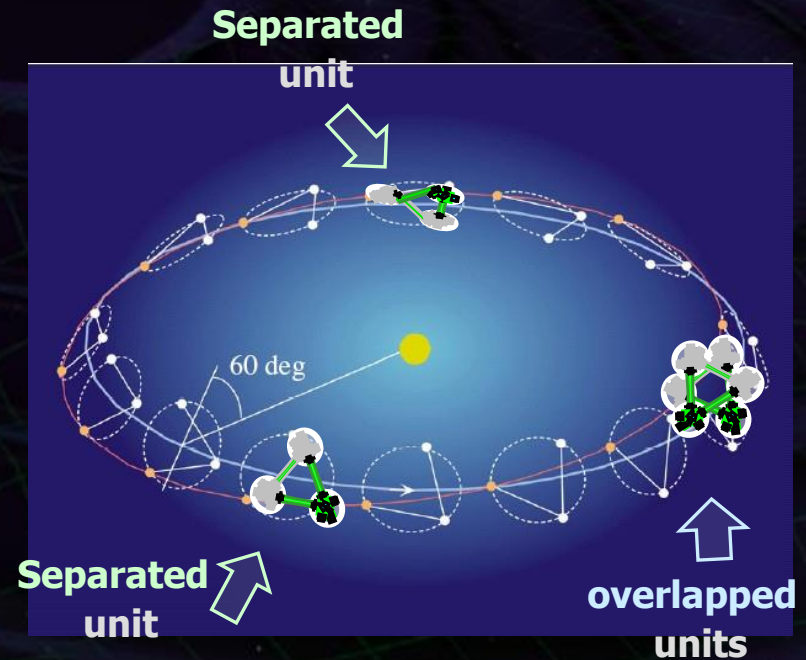
(Mirror force  $\sim 10^{-9} \text{ N}$ )

## Constellation

4 interferometer units

2 overlapped units  $\rightarrow$  Cross correlation

2 separated units  $\rightarrow$  Angular resolution





## Scientific observations

### Gravitational Waves from BH mergers

→ BH formation mechanism

### Gravity of the Earth

→ Geophysics, Earth environment

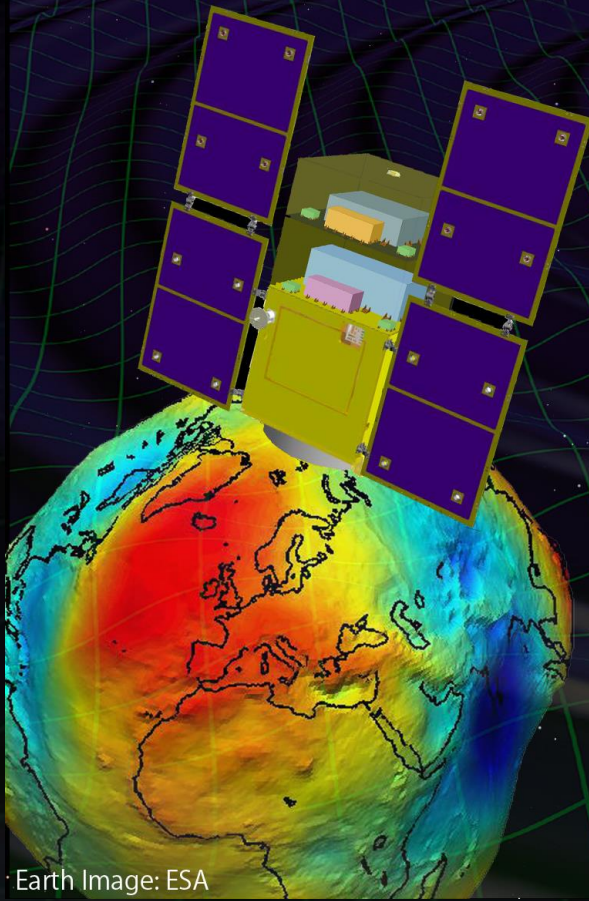
## Science technology

### Space demonstration for DECIGO

→ Most tech. with single satellite  
(IFO, Laser, Drag-free)

### Precision measurement in orbit

→ IFO measurement  
under stable zero-gravity



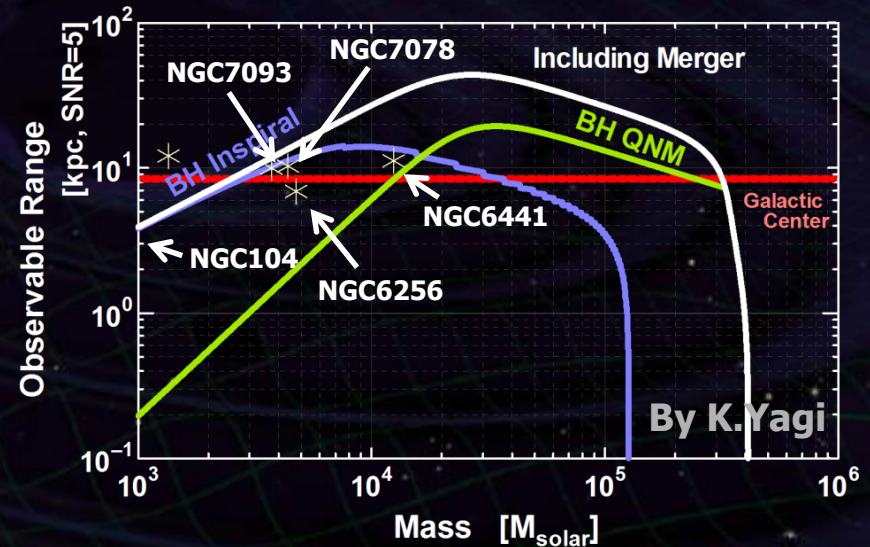
Earth Image: ESA



## Astronomical observation

GW from merger of IMBHs  
 → Formation mechanism  
 of supermassive BHs

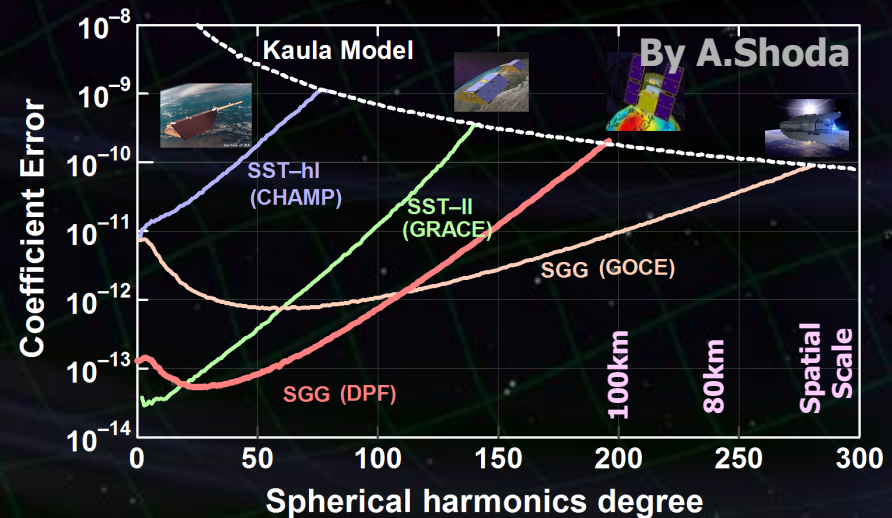
~30 GCs within DPF range



## Observation of the earth

Gravitational potential  
 → Shape of the earth  
 Environment monitor

Comparable sensitivity  
 with other missions





干渉計モジュールについて

# 光学系部品だけでの動作テスト

この状態でのFabry-Perot光共振器の動作は確認済み。

← 1030 nm laser source + fiber coupler

Fibered EOM

Input optics (BBM2)

Cavity (300mm)

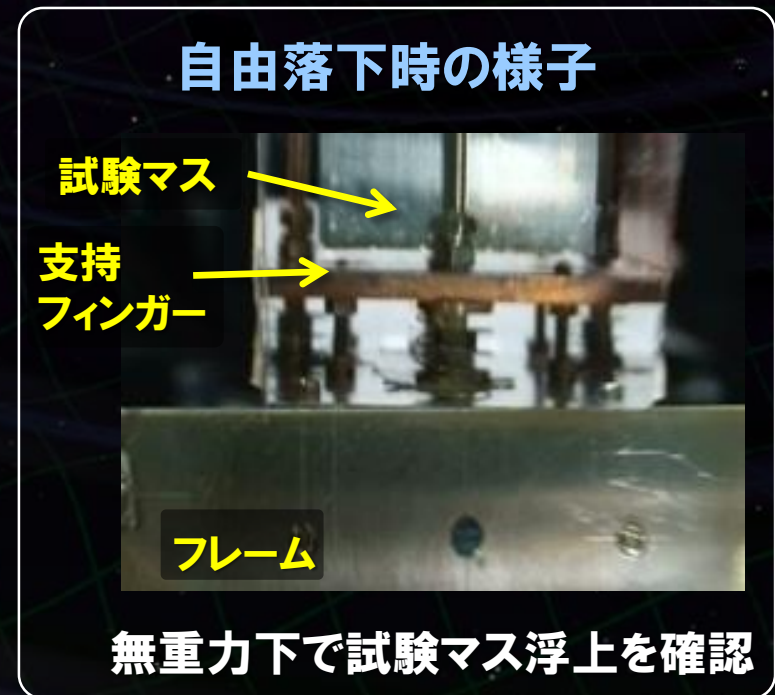
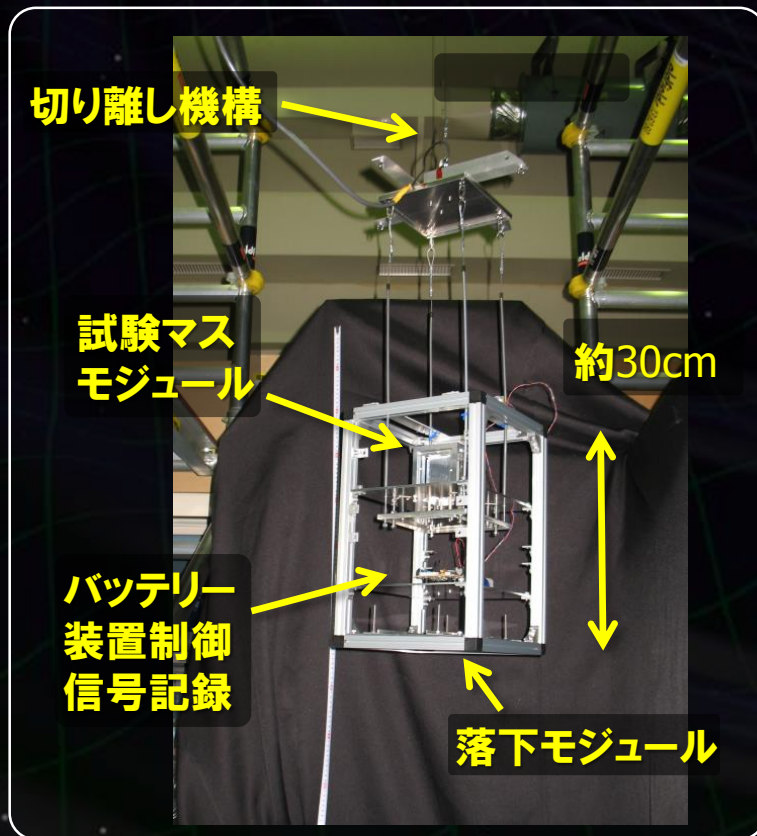
Feedback to the piezo stage at the end mirror and laser source.

The cavity can be operated.

by Kasuga

•RESCEU APCosPA Summer School on  
Cosmology and Particle Astrophysics  
(August 3rd, 2014, Matsumoto)

- 無重力下での試験マス制御デモンストレーション (国立天文台)
  - 落下モジュール (構造, 電源, センサ, ロガーなど)
  - ~3m落下設備 (足場, 切り離し機構, クッションなど)



今後, 静電S/Aによる制御をめざす.



# SWIMによる宇宙実証



Photo:  
JAXA

## SDS-1搭載のSWIM (Space wire demonstration module)

2009年1月打ち上げ, 2010年9月運用停止

⇒ 世界で最初の 宇宙重力波検出器



「いぶき」搭載カメラによる  
衛星分解の様子  
(2009年1月23日) ©JAXA

### SpaceCube2: Space-qualified Computer

CPU: HR5000

(64bit, 33MHz)

System Memory:

2MB Flash Memory

4MB Burst SRAM

4MB Asynch. SRAM

Data Recorder:

1GB SDRAM

1GB Flash Memory

SpW: 3ch

Size: 71 x 221 x 171

Weight: 1.9 kg

Power: 7W



Photo by JAXA

### SWIM<sub>μv</sub> : User Module

Processor test board

GW+Acc. sensor

FPGA board

DAC 16bit x 8 ch

ADC 16bit x 4 ch

→ 32 ch by MPX

Torsion Antenna x2

~47g test mass

Data Rate : 380kbps

Size: 124 x 224 x 174

Weight: 3.5 kg

Power: ~7W

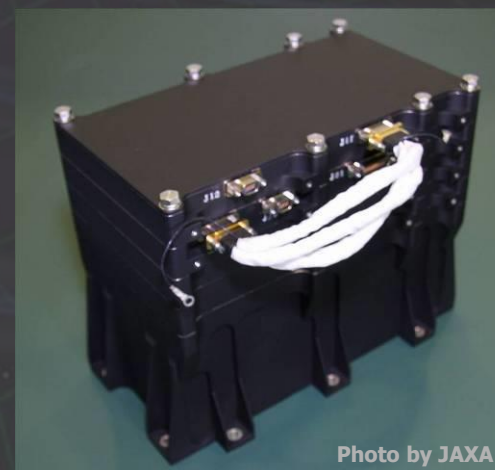


Photo by JAXA

SDS-1  
Bus System

Power +28V  
RS422 for CMD/TLM  
GPS signal

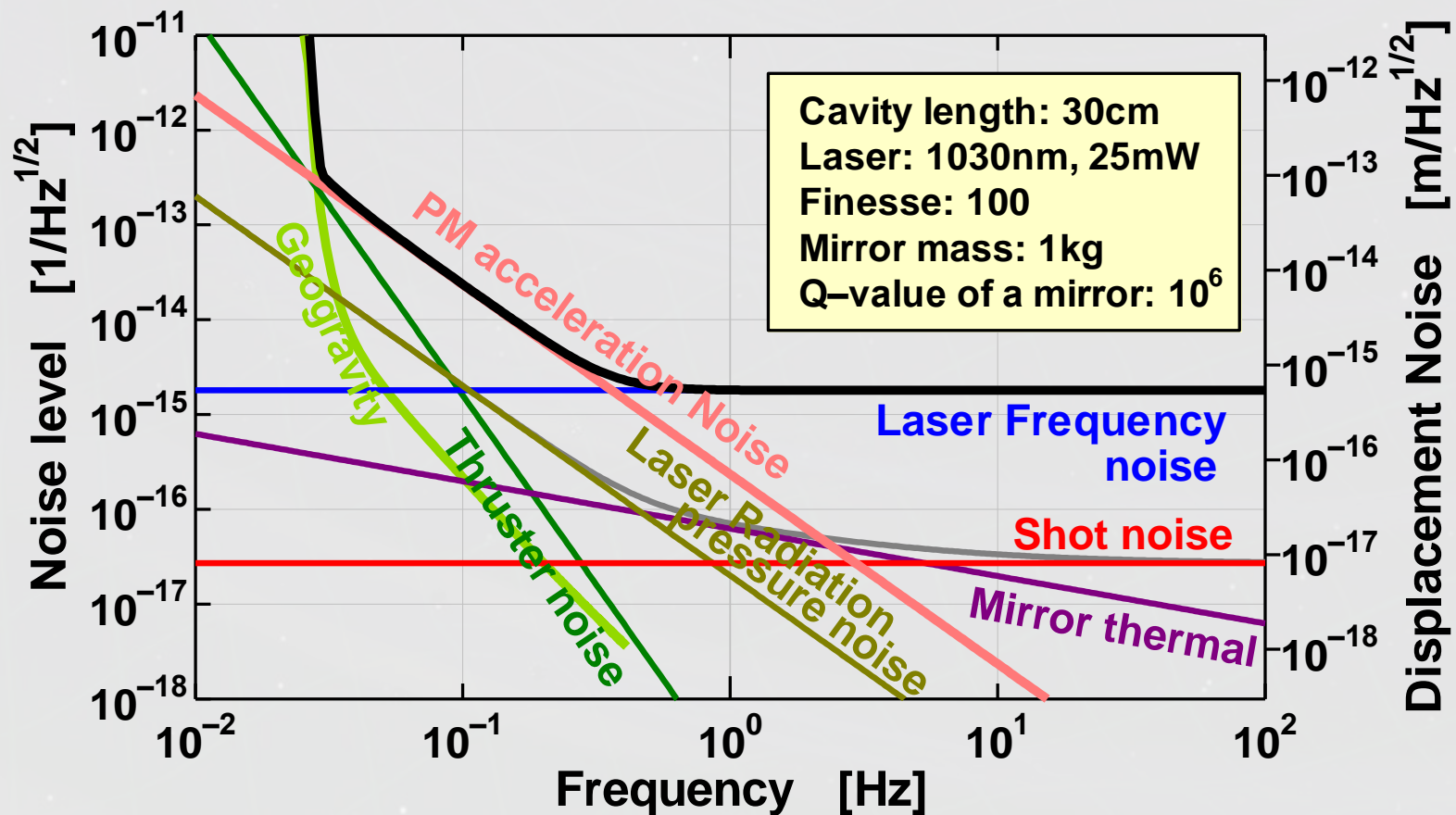
Power ±15V, +5V  
SpW x2 for CMD/TLM

# DPF Sensitivity

Laser source : 1030nm, 25mW  
IFO length : 30cm  
Finesse : 100, Mirror mass : 1kg  
Q-factor :  $10^5$ , Substrate: TBD  
Temperature : 293K

Satellite mass : 350kg, Area: 2m<sup>2</sup>  
Altitude: 500km  
Thruster noise:  $0.1\mu\text{N}/\text{Hz}^{1/2}$

(Preliminary parameters)



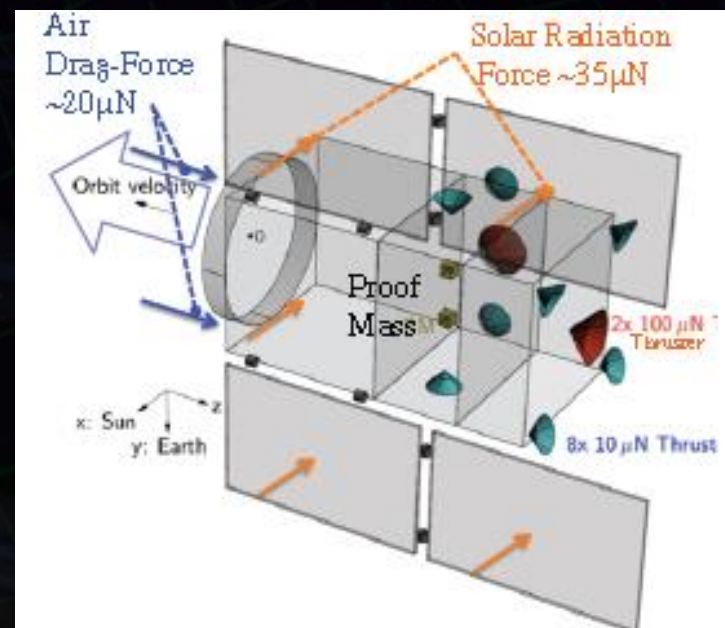


## ・ミッションスラスタ構成

- 準定常成分 **100  $\mu\text{N}$ スラスタ 2台**  
大気ドラッグ, 太陽輻射圧
- 変動成分 **10  $\mu\text{N}$ スラスタ 8台**  
大気圧変動, 太陽輻射変動

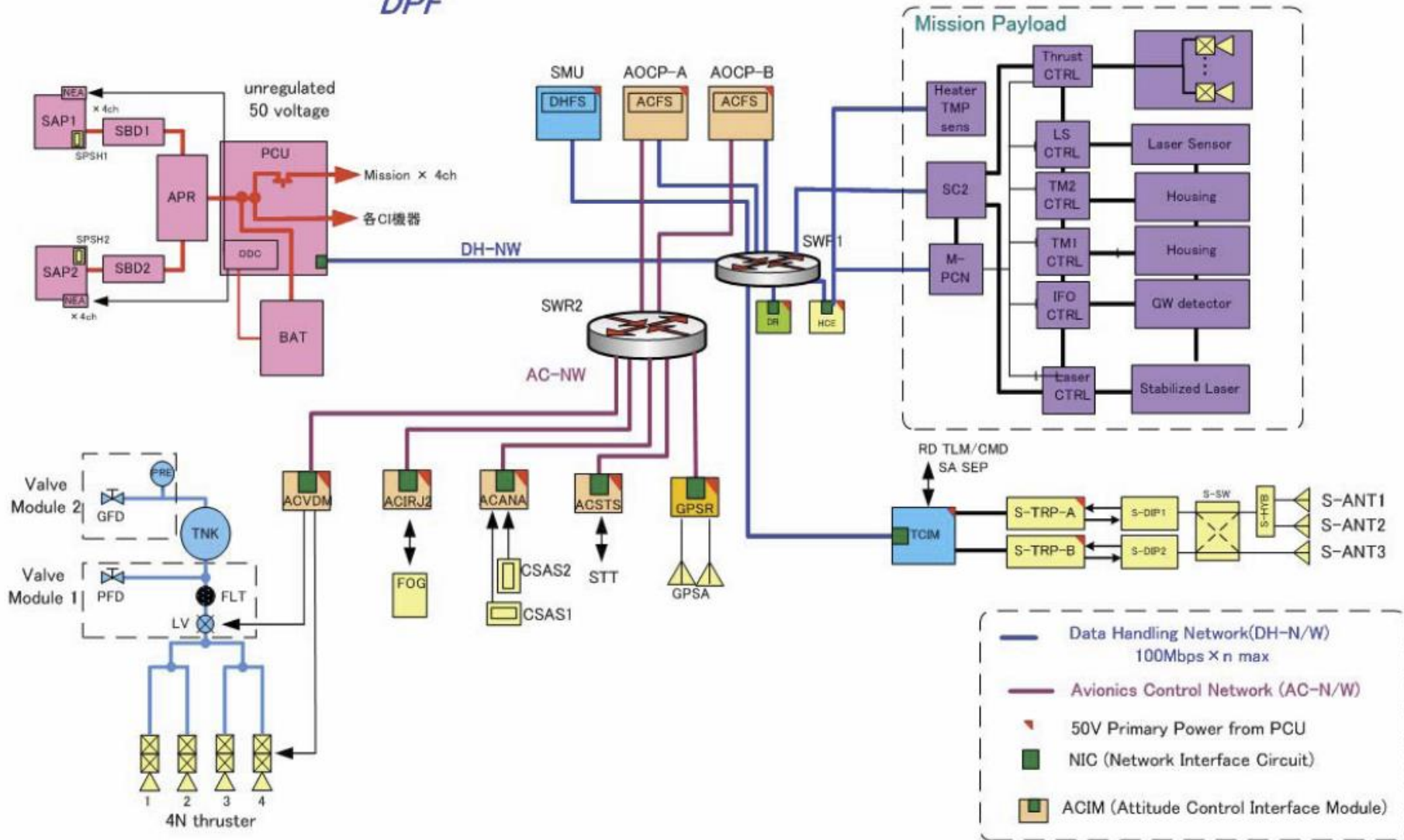
### ミッションスラスタ仕様

推力	0.5-100 $\mu\text{N}$ x2 (可変)
	0.5-10 $\mu\text{N}$ x 8 (可変)
分解能	0.1 $\mu\text{N}$
推力雑音	0.1 $\mu\text{N}/\text{Hz}^{1/2}$
制御応答	>10Hz
Isp	TBD
電力・質量	<40W, <40kg
運用寿命	4,300 時間



# DPFシステムブロック図

DPF







# DPFシステム概念検討（これまで）

補足

©NEC

## 熱設計検討

- 熱的要求条件
- 設計方針
- 排熱検討

## SpW信号処理系システム検討

- バス部からミッション部への通信方法

## 受動安定姿勢の検討

- 日照時安定姿勢の改善
- ミッションスラスタの構成・配置検討

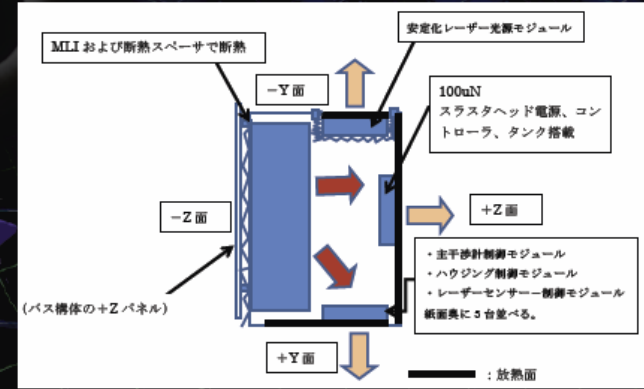
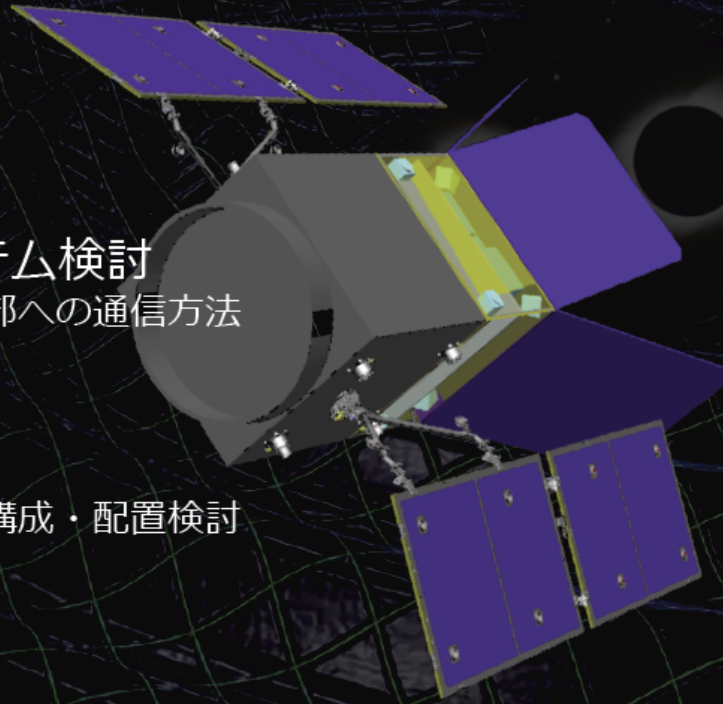
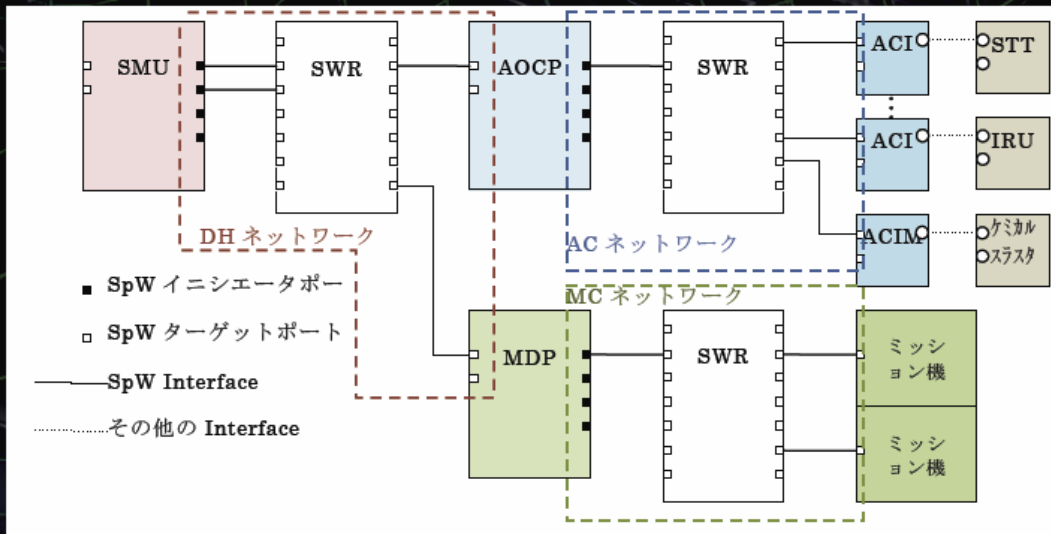


表 2-3 バス機器許容温度および発生熱量

搭載パネル	機器名称	動作時許容温度	発熱(定常観測+伝送)	備考
+X 独立熱制御	BAT-L	20 ~ 30	-	-
	BAT-H	20 ~ 30	-	-
-X	SWR2	-25 ~ 50	10.3	SPRINT-A ODR設計値
	PCU	-30 ~ 60	17.2	SPRINT-A ODR設計値
	ACSDN	-30 ~ 50	3.5	SPRINT-A ODR設計値
	ACIRM	-30 ~ 50	9.5	SPRINT-A ODR設計値
	ACANA	-30 ~ 50	10.5	SPRINT-A ODR設計値
	HCE	-20 ~ 50	9.6	SPRINT-A ODR設計値
	-Xパネル合計		60.6	
+Y	APR	-25 ~ 65	68	SPRINT-A ODR設計値
	ACSTS	-30 ~ 50	7	SPRINT-A ODR設計値
	SWR1	-25 ~ 50	10.3	SPRINT-A ODR設計値
	SBD	-30 ~ 60	11	SPRINT-A ODR設計値
	SADM	-30 ~ 60	1.5	SPRINT-A ODR設計値
	+Yパネル合計		97.8	
-Y	S-TRP-A	-20 ~ 55	10	SPRINT-A ODR設計値
	S-TRP-B	-20 ~ 55	27.6	SPRINT-A ODR設計値
	AQCP-B	-25 ~ 50	1	SPRINT-A ODR設計値
	AQCP-A	-25 ~ 50	13	SPRINT-A ODR設計値
	SMU	-25 ~ 50	19	SPRINT-A ODR設計値
	TCIM	-30 ~ 50	14	SPRINT-A ODR設計値
	DR	-25 ~ 55	6.5	SPRINT-A ODR設計値
	SADM	-30 ~ 60	1.5	SPRINT-A ODR設計値
	SBD	-30 ~ 60	11	SPRINT-A ODR設計値
	-Yパネル合計		103.6	
+Z	FOG	-10 ~ 50	6.9	IKAROS機載品
	S-SW	-20 ~ 50	0.2	SPRINT-A ODR設計値
	S-DIP1	-20 ~ 55	0.1	SPRINT-A ODR設計値
	S-DIP2	-20 ~ 55	0.1	SPRINT-A ODR設計値
	GAS	-30 ~ 60	1.0	SPRINT-A ODR設計値
	S-HYB	-20 ~ 55	1.6	SPRINT-A ODR設計値
	ミッション側からの熱入力		20	規定
	+Zパネル合計		29.9	
-Z	RCS用ヒータ		5.2	ASNARC実績
	-Zパネル合計		5.2	
+Z 独立熱制御	STT	-30 ~ 60	7.2	SPRINT-A ODR設計値
	バス合計		304.3	





## ・衛星構造のオプション案の検討

問題意識: 衛星構造(特にSAP)の共振など剛性を高めた構成の検討.

従来は衛星バスの制約から検討外であったが、ミッションの  
枠組み変更に伴い検討を開始.

(SE室との相談でもencourageされた)

結果: 成立する可能性があることを示唆.

### - 最低共振周波数

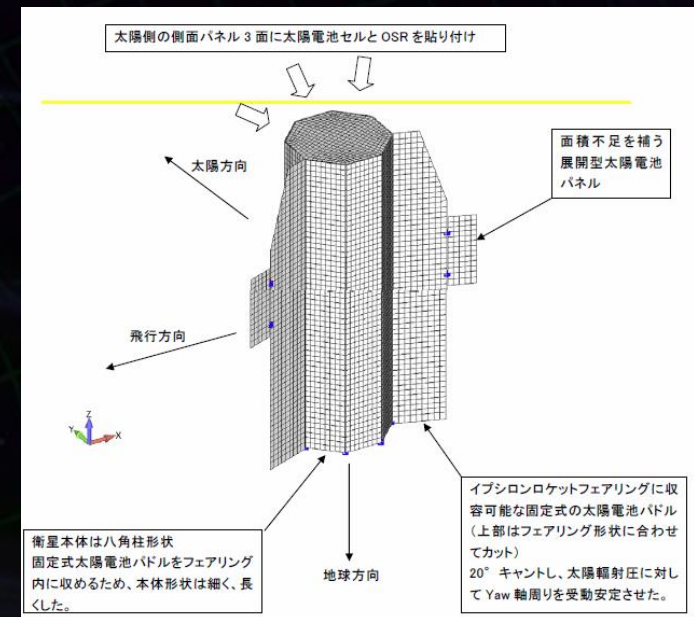
従来 1~2Hz → 今回 26.8 Hzに向上.

- 質量評価 → これまでとほぼ同等.

- SAP面積 従来 4.3 m<sup>2</sup> → 2.8 m<sup>2</sup>.

### - 要検討事項:

搭載機器配置, 質量バランス, 電力,  
排熱面設定, ミッションスラスタ配置,  
受動姿勢安定, コスト など.



# GW target of DPF



## Black hole events in our galaxy

### IMBH inspiral and merger

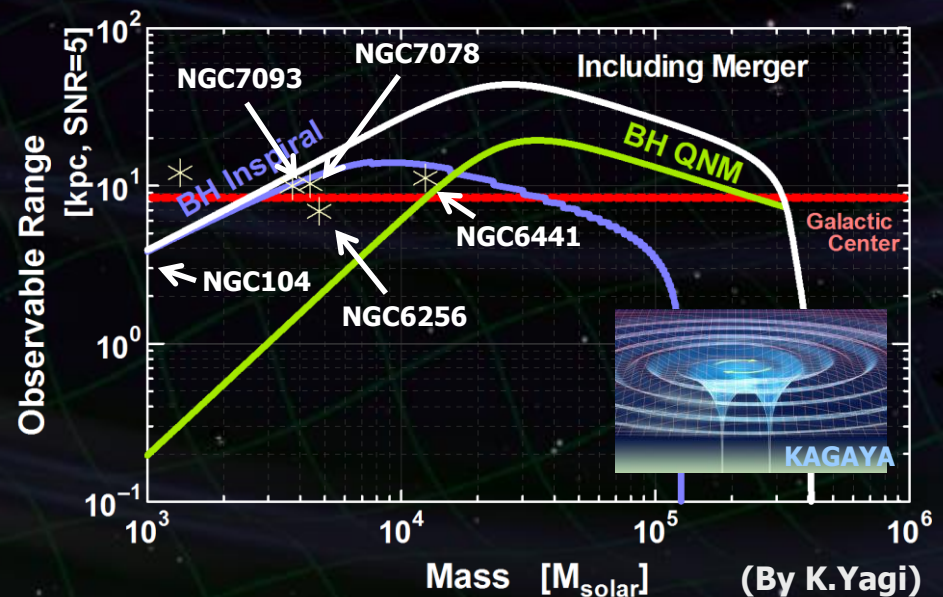
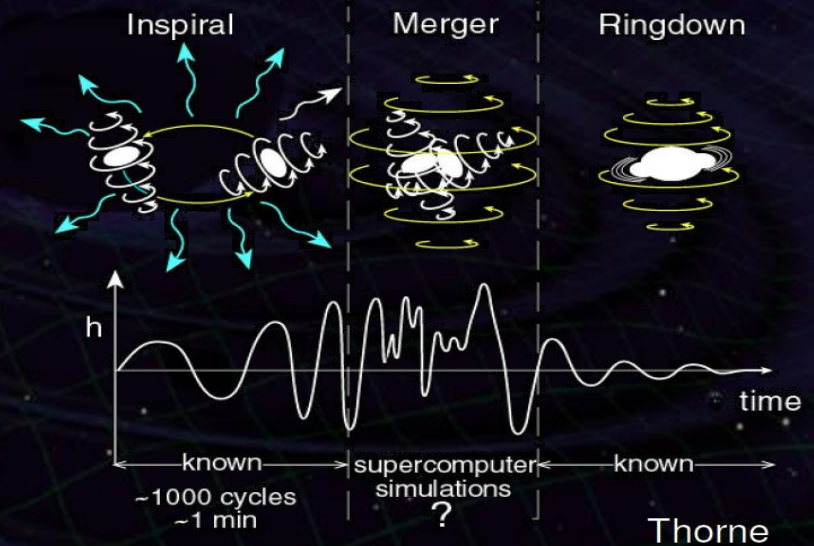
Obs. Distance 40kpc,  
for  $m = 2 \times 10^4 M_{\text{sun}}$

Obs. Duration ( $\sim 1000\text{sec}$ )

Observable range covers  
our Galaxy (SNR $\sim 5$ )

There may be IMBH at GCs  
DPF covers  $\sim 30$  GCs

Hard to access by others  
→ Original observation

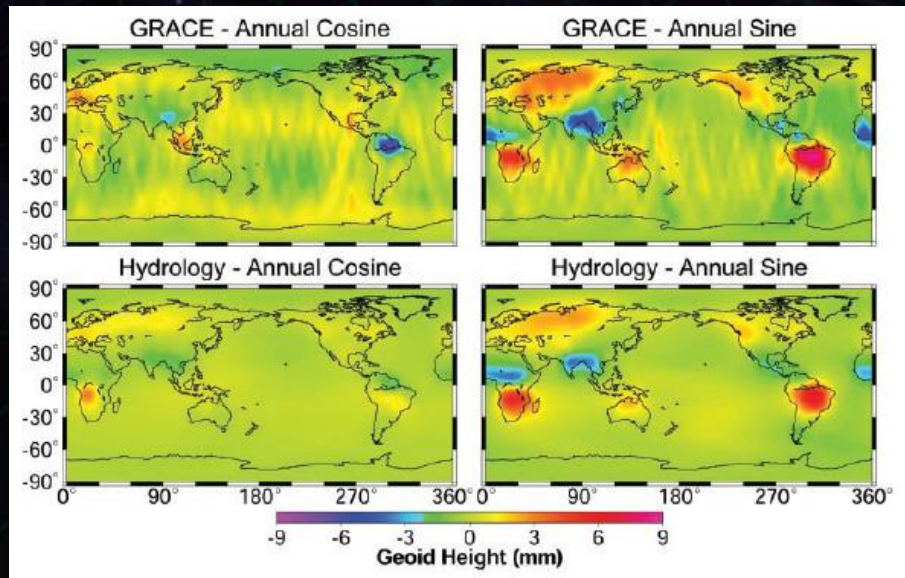




# Earth's Gravity Observation

Measure gravity field of the Earth  
from Satellite Orbits, and gravity-gradiometer

➔ comprehensive and homogeneous-quality data



Seasonal change of the gravitational potential  
observed by GRACE

Determine global gravity field  
→ Basis of the shape of  
the Earth (Geoid)

Monitor of change in time

→ Result of Earth's dynamics

Ground water motion

Strains in crusts by

earthquakes and volcanoes

## 3-types of satellite gravity missions

### Satellite-to Satellite tracking High-Low

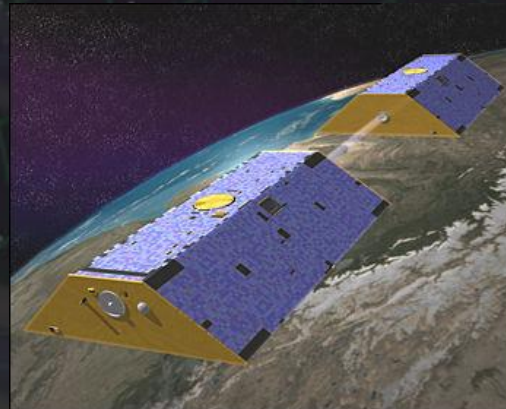
- Observe satellite orbit by global positioning system (GPS,...)
- Cancel drag-effects by accelerometer



**CHAMP** (GFZ, 2000-)

### Satellite-to Satellite tracking Low-Low

- Distance meas. by along-track satellites
- Cancel drag-effects by accelerometer



**GRACE** (NASA, 2002-)

### Satellite Gravity Gradiometry

- Observe potential by **gravity gradiometer**
- Drag-free control for cancellation of drags



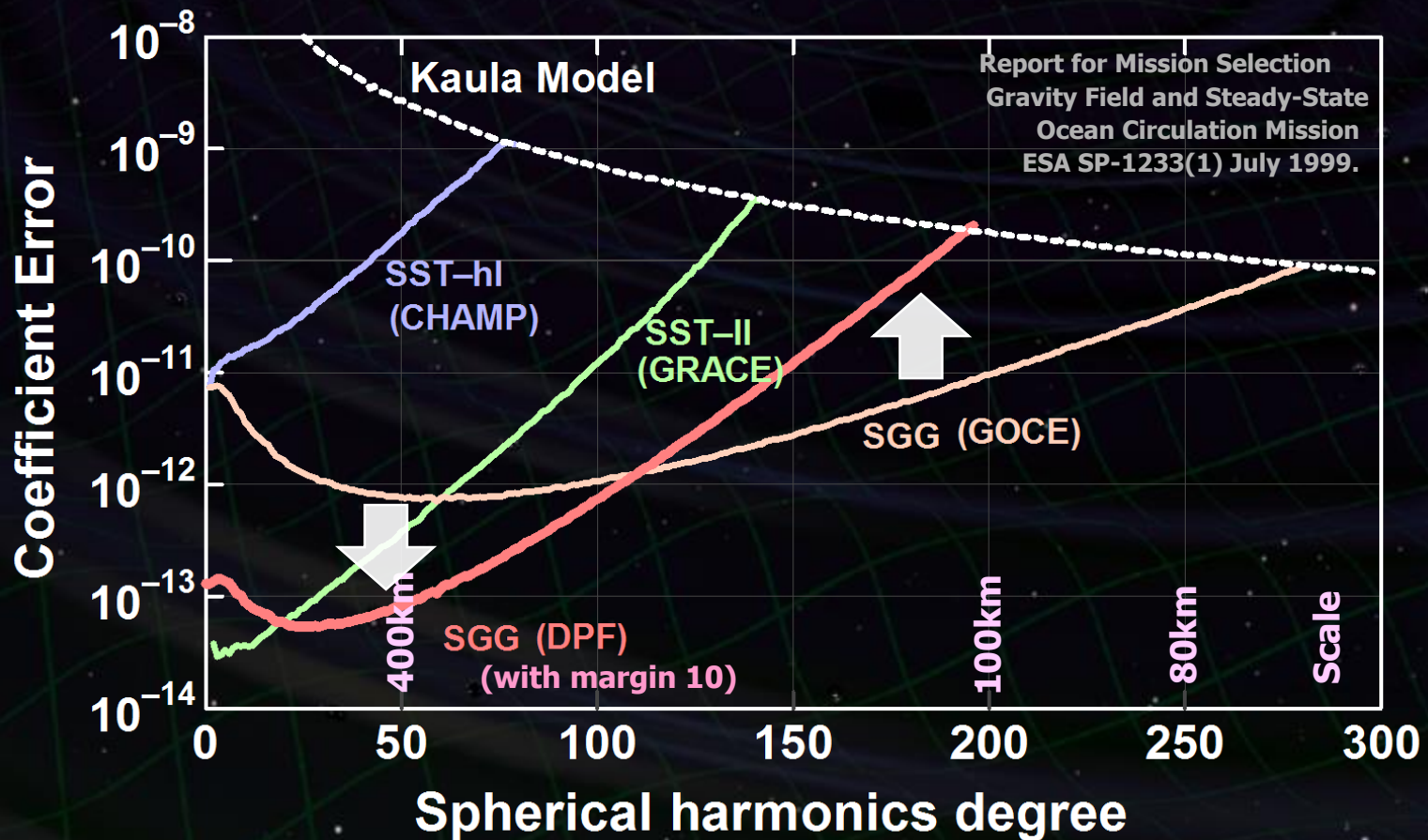
**GOCE** (ESA, 2009-)



## Comparison of sensitivities

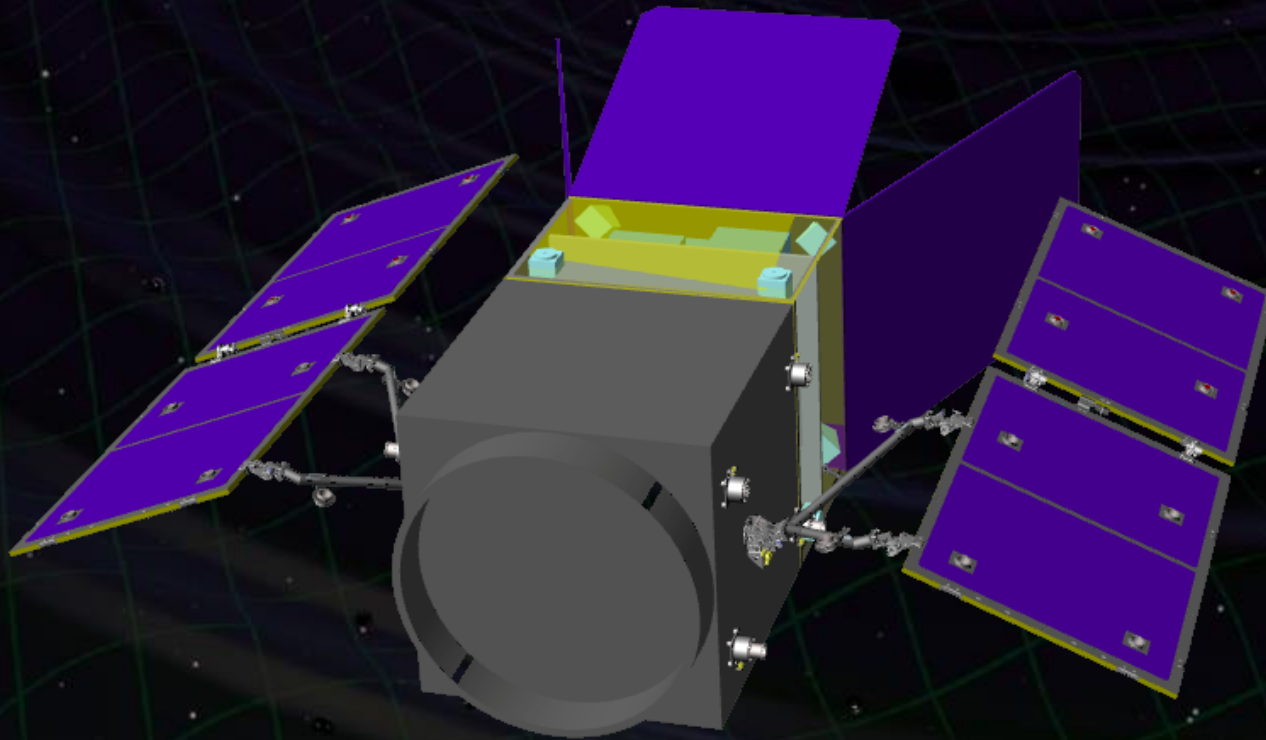
Better in low orders (large scale) ← Sensors

Worse in high orders (small scale) ← Altitude



## Mission design

- Structure and thermal modeling
- Drag-free control design



Design : NEC

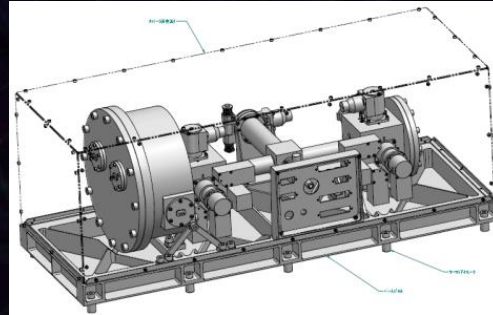


## BBMs (Bread-board model) for Core components

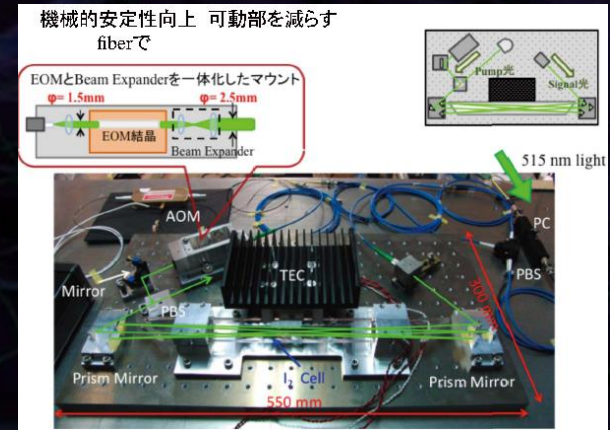
### Interferometer module



Univ. of Tokyo, NAOJ



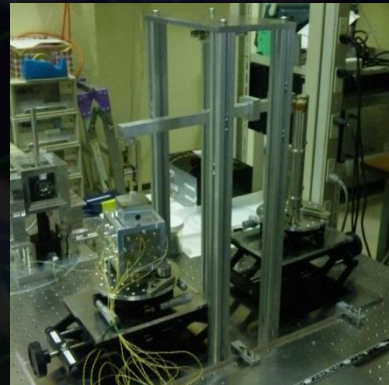
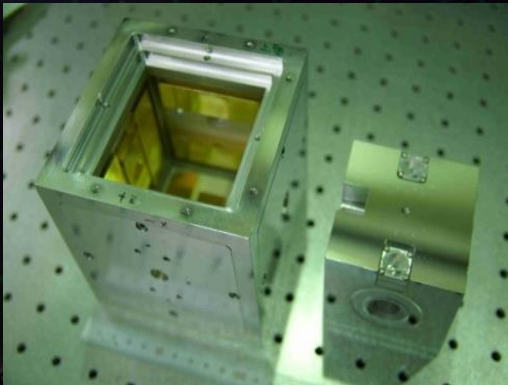
### Laser stabilization module



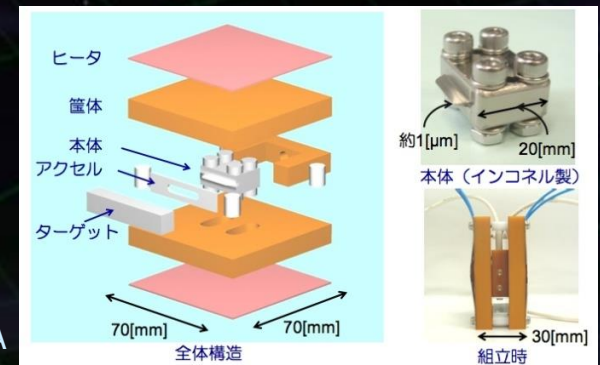
UEC, NICT, NASA/GSFC

### Test-mass module

NAOJ, Hosei Univ.



### Low-noise thruster module



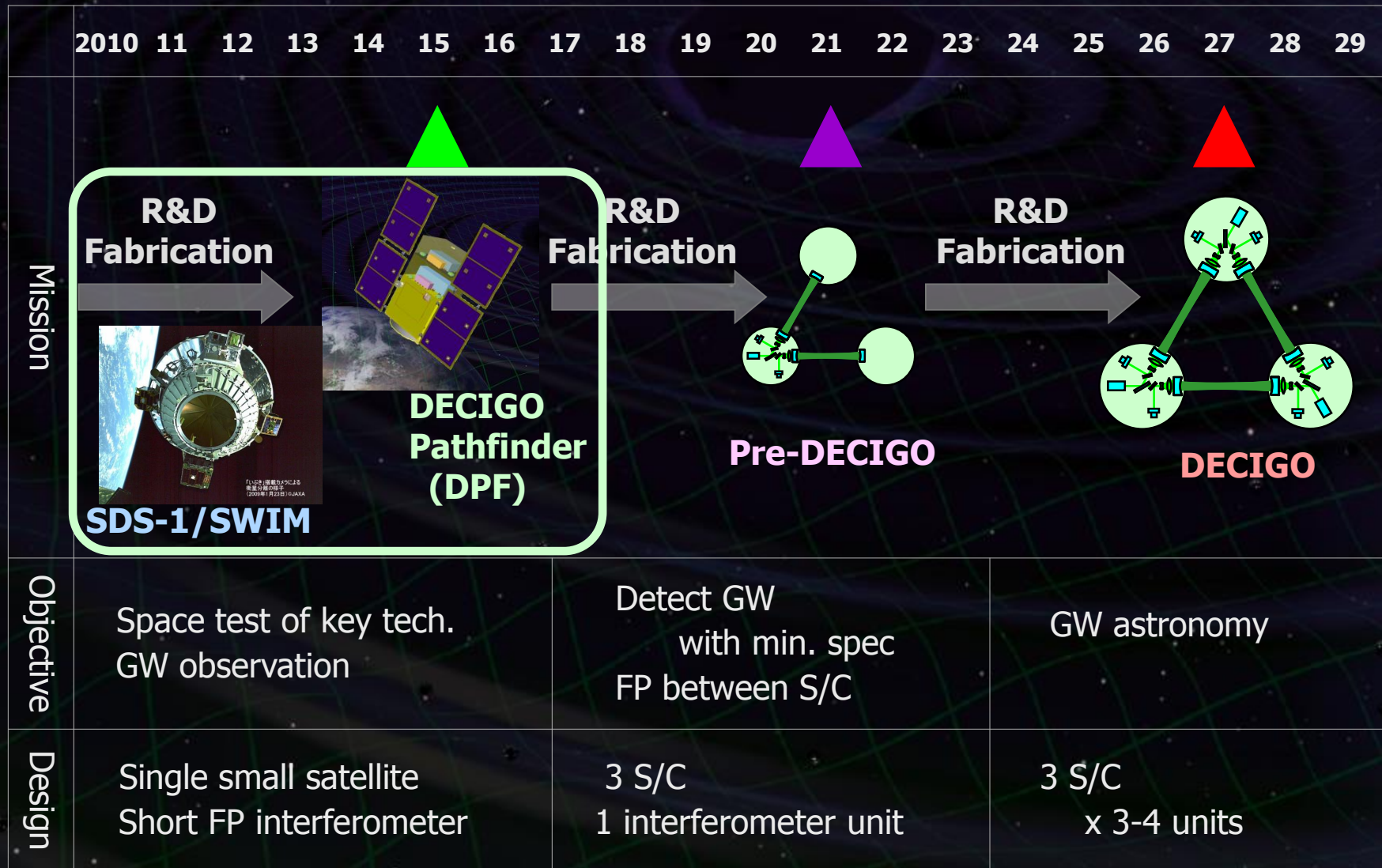
JAXA

# SWIM



# Roadmap

Figure: S.Kawamura



# Rotating TOBA : SWIM $\mu$ v

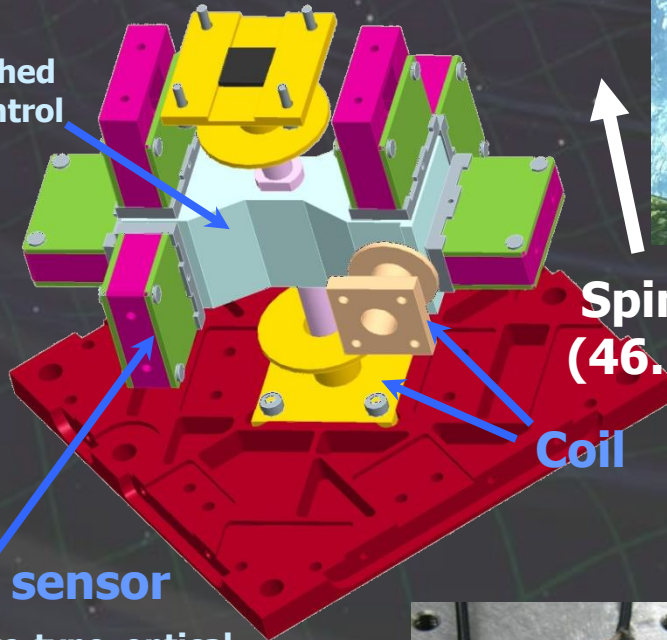
## Small Module SWIM $\mu$ v on SDS-1

Launched Jan. 2009, Terminated Sept. 2010

**TAM: Torsion Antenna Module with free-falling test mass**  
(Size : 80mm cube, Weight :  $\sim$ 500g)

### Test mass

$\sim$ 47g Aluminum, Surface polished  
Small magnets for position control



Spin Axis  
(46.5mHz)

Coil

### Photo sensor

Reflective-type optical  
displacement sensor  
Separation to mass  $\sim$ 1mm  
Sensitivity  $\sim 10^{-9}$  m/Hz $^{1/2}$   
6 PSs to monitor mass motion

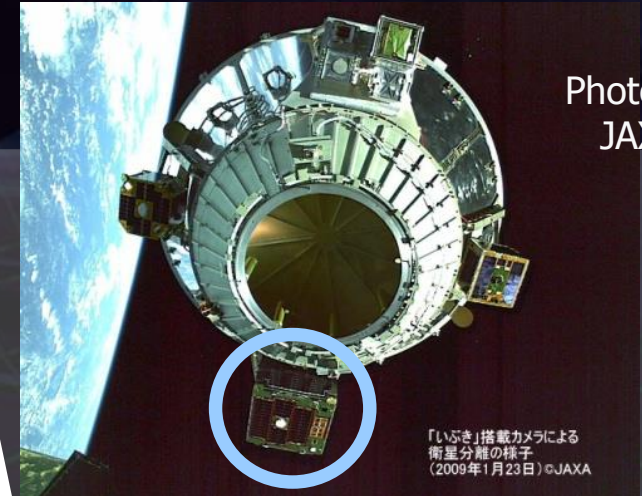
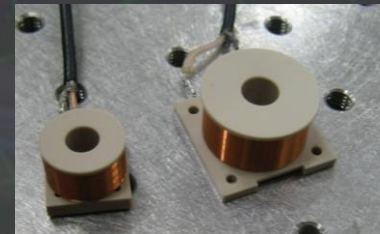
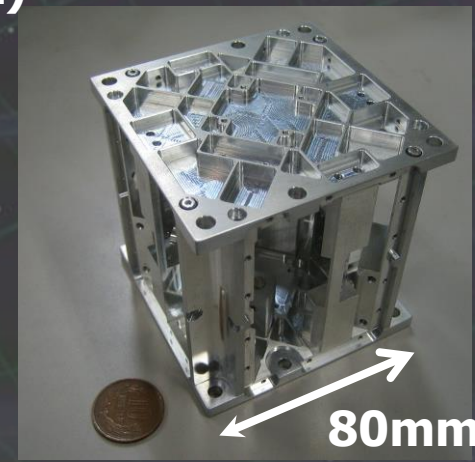


Photo:  
JAXA

「いぶき」搭載カメラによる  
衛星分離の様子  
(2009年1月23日) ©JAXA

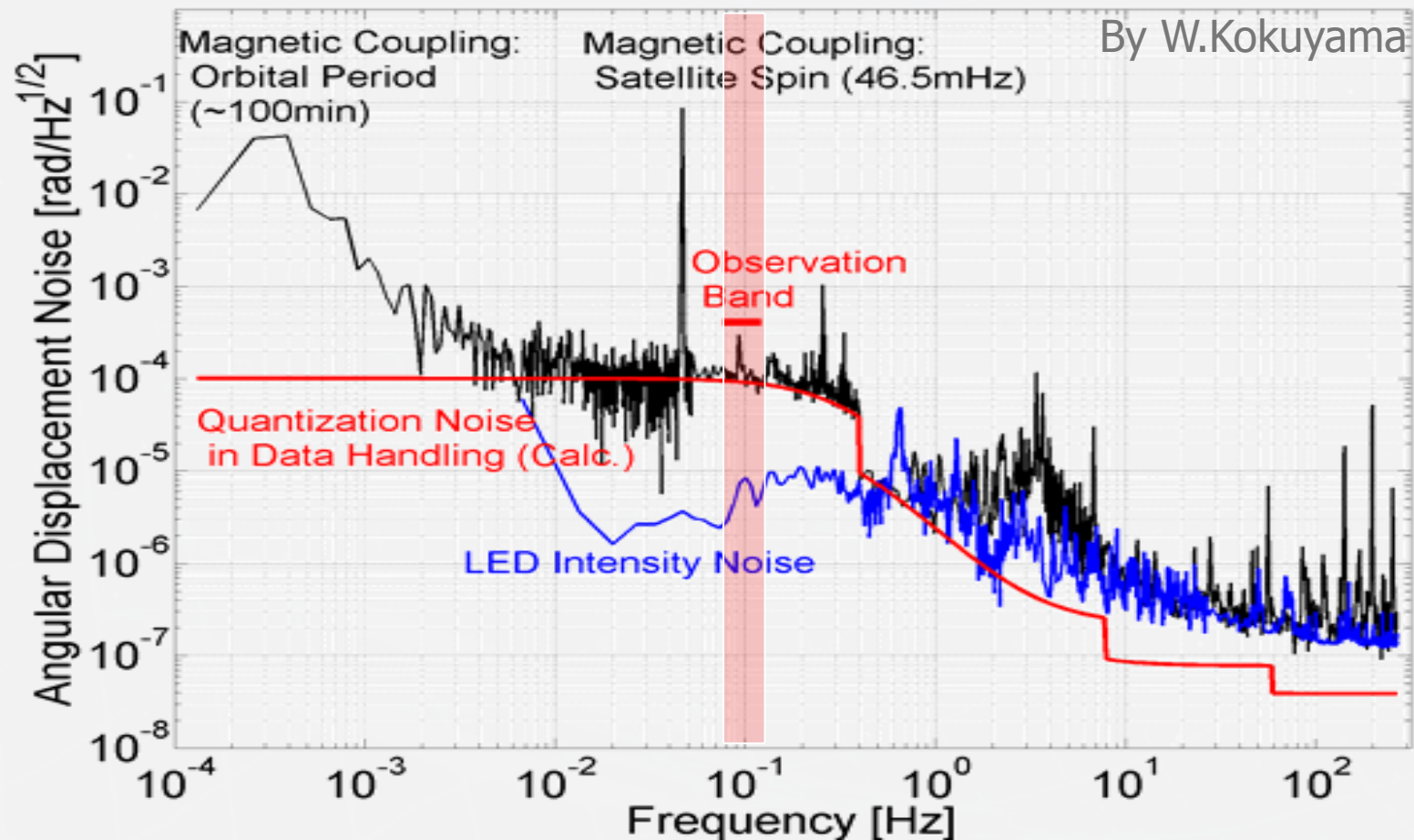


80mm



# Sensitivity

Though limited by non-fundamental noises,  
best as a space-borne GW detector.

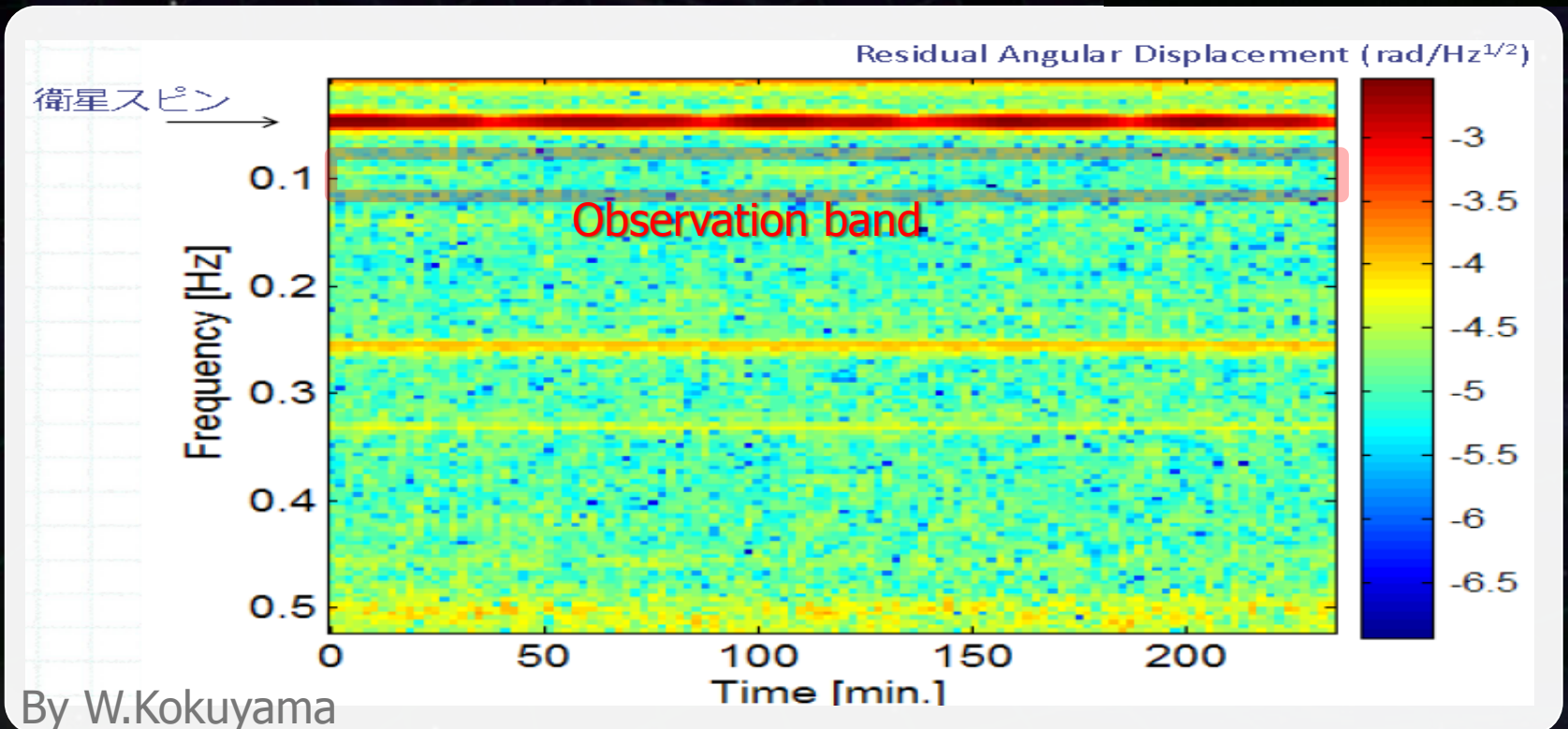
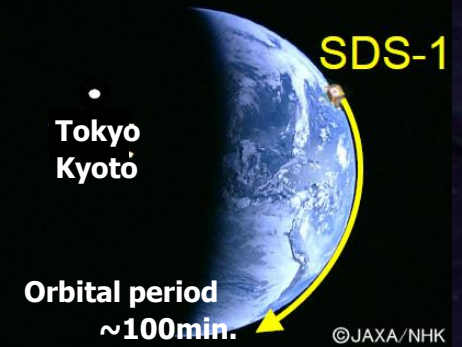


# Observation by SWIM

## Continuous data taking

Jun 17, 2010 ~120 min.

July 15, 2010 ~240 min.





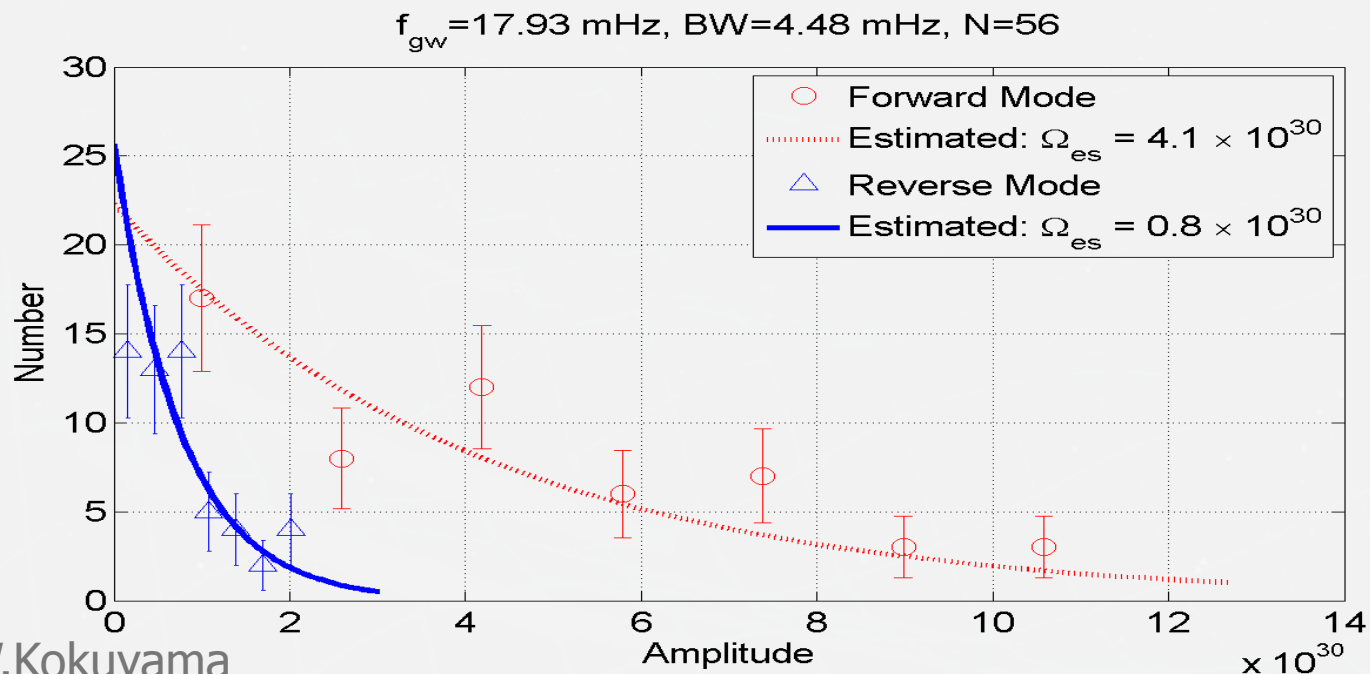
# Upper Limit on GWB

Upper Limit at two frequencies (two polarizations)

'Forward' mode  $\Omega_{\text{gw}}^{\text{FW}} = 1.7 \times 10^{31}$

'Reverse' mode  $\Omega_{\text{gw}}^{\text{RE}} = 3.1 \times 10^{30}$

(C.L. 95%,  $f_0$  18mHz, BW 4mHz)



By W.Kokuyama

# KAGRA and DECIGO

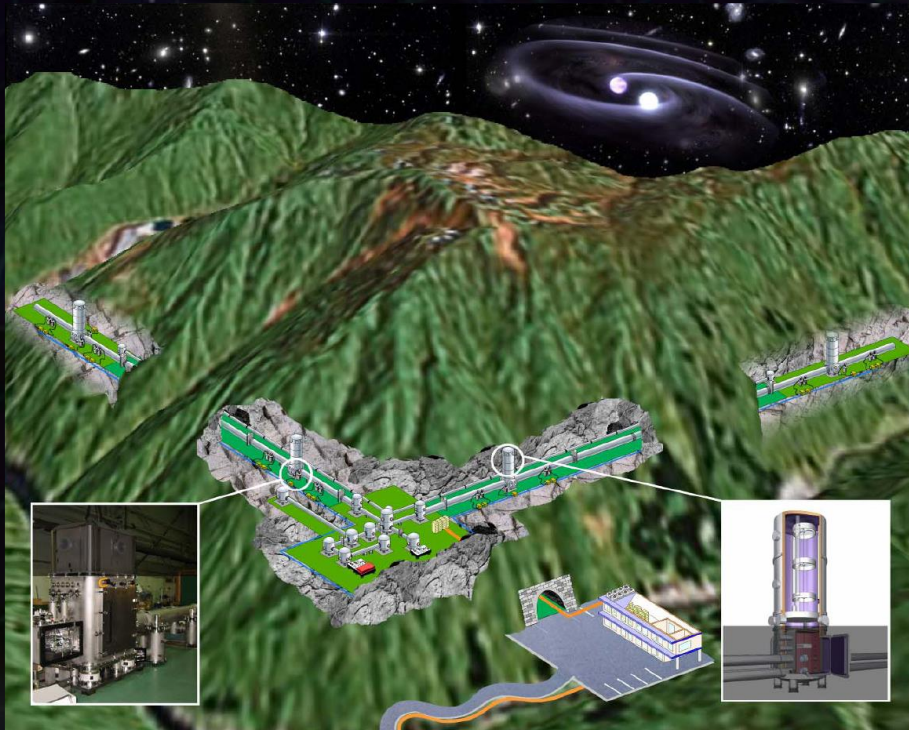


**KAGRA** (~2016)

Terrestrial Detector

→ High frequency events

Target: GW detection

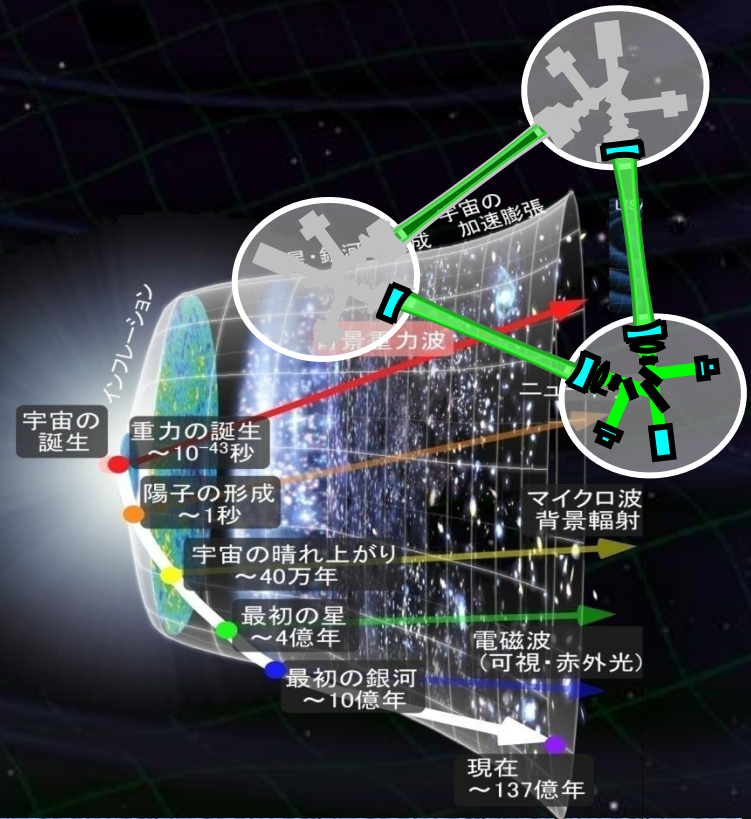


**DECIGO** (~2027)

Space observatory

→ Low frequency sources

Target: GW astronomy





# Roadmap

Figure: S.Kawamura

